Investigation of flow over a BWB at different angles of attack

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Introduction

- Blended Wing Body (BWB)
 - Unconventional configuration which integrates wing and fuselage into single lifting surface
 - No clear dividing line between wings and main body of the aircraft



Depiction of conventional Tube and Wing design (extreme left) with BWB configuration (B1 Lancer in center left, B2 bomber in center right) and flying wing design (extreme right)^[26] 3

Introduction

- Potential advantages
 - low wetted area to internal volume ratio
 - smooth varying cross-section distribution
- Potential challenges involved
 - Challenging design as tight coupling between aerodynamic performance, trim and stability
 - Concerns for commercial airliner applications regarding passenger safety, comfort and cabin pressurization
 - Several tailless designs could have inherent instability hence require special airfoils (with positive pitching moment) and fly by wire systems

Literature Review

- Liebeck, R. H.^{[5][15]} worked on designing a subsonic transport Blended wing body aircraft
- Designed the BWB platform for Boeing with varied size aircrafts for different carrying capacity (such as BWB-450, BWB-250)



Interior volume of BWB-450 aircraft compared to A380-700



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Qin et. al., 2004^[1]

- Titled: Aerodynamic considerations of Blended Wing Body Aircraft
- Aerodynamic analysis of baseline configuration
- Aerofoil optimization and surface optimization for design cruise condition for a commercial BWB followed by 3d surface optimization





sections



Masashi et. al., 2015^[2]

- Titled: Experimental Study on Aerodynamic Characteristics of Blended-Wing-Body by a Wake Integration Method
- Aerodynamic characteristic of the BWB in low speed flows using the wake measurement
- Winglet taper ratio: 0.25
- Winglet airfoil: NACA0012



Comparison of spanwise lift coefficient for baseline (left) and design with winglets (right)



Spanwise induced drag coefficient for baseline model (left) and with winglets (right)

Tatsuya et. al., 2019^[3]

- Titled: Wake Measurements on Blended Wing Body with Gurney Flaps in Low Speed Flows
- Investigated the effect of a Gurney flap (GF) on the BWB configuration and compares it to the baseline (similar to one given by Masashi Kashitani et al.^[2])



Parisa et. al., 2019^[19]

- Titled: Aerodynamic Design of Long-Range VTOL UAV
- Hybrid UAV design
- Analysis carried out for location of center body for the same
- Vertical location of VTOL drive also discussed



VTOL UAV concept as given by Parisa Footohi et al.^[19]. Left figure corresponds to VTOL mode and right figure corresponds to cruise mode

Other literature

- Chen et. al., 2017^[11] have discussed about modelling of a hybrid BWB UAV
 - Quad rotor configuration at wing tips
 - Analysed for various wind conditions
- Rodzewicz Mirosław , Goraj Zdobysław and Tomaszewski Adam, 2018^[17] had worked on UAV designs for Antarctic conditions
 - A comparison of performance between delta wing UAV and BWB UAV carried out
- Panagiotou et al., 2017^[10] worked on a design of Medium Altitude Long Endurance (MALE) UAV
 - BWB configuration
 - 3 BWB configurations designed and compared
- Geoffrey Larkina and Graham Coates, 2017^[18] worked on design of vertical stabilizer for BWB configuration
 - Baseline similar to the one given in reference 3
 - Twin stabilizer configuration discussed



Dual stabilizer model^[18]. Left one with vertical and right one with stabilizers inclined at an angle

- Some papers such as by Daniel J. Thompson, 2011^[13] and Kai Lehmkuehler et al., 2012^[14] discussed about fabrication of BWB UAVs and testing them in flight
- And many others which were focussed on design optimization^{[8][9][11][16]}

- From the literature review,
 - Limited studies on low Reynolds number performance of BWB
 - Limited studies on flow physics over BWB

Influencing factors on flow over BWB

- Reynolds number
- Sweep angles
- Angle of attack
- Airfoil configuration

BWB as Unmanned Aerial Vehicles (UAVs)

- BWB configuration can offer several potential advantages as UAV platform
 - Improved efficiency can improve range and endurance
 - High internal volume can allow for high payload carrying capabilities
 - Since the crafts are unmanned, cabin pressurization is not an issue
 - Larger lifting surface can promote hybrid designs for multirole applications



X-48 Boeing prototype in test $flight^{[24]}$



Monica-1, Antarctic exploration UAV^[17]

Objective

 Study of BWB flow physics at a typical angle of attack and effect on flow physics with variation in angle of attack at low speeds to study the feasibility for UAV applications

Research Methodology





Low subsonic wind tunnel

Speed Range: 10-30m/s

Test section: 600mm X 600mm

Research Methodology

- Experimental Techniques
 - Force measurement
 - 5 component strain gauge balance
 - Power Supply (Low Noise DC 3 volts)
 - Signal Conditioner (Filter : 10Hz)
 - DAQ (National Instruments)
 - Flow visualization
 - Optimum mixture of Carbon soot, Oil, Oleic acid

Incidence Mechanism



Molmarc model: HO-PY-WT01 Pitch range: ±75 degrees

Yaw range : ±20 degrees

The model was mounted at the sample holder and the setup was observed to have negligible vibration under test conditions.

Model specifications

Specification	Full Scale Model ^[3]	Scaled Down Model
Root Chord	507.7mm	187.85mm
Span (b)	775mm	286.75mm
Mean Aerodynamic Chord (MAC)	123mm	45.52mm
Reference Area (S _{ref})	82400.00mm ²	11310.68mm ²
Sweep Angle (Center Body)	63.8 ⁰	63.8 ⁰
Sweep Angle (Wing)	38 ⁰	38 ⁰
Re (based on MAC)	58500	58500



- Model fabrication
 - Fabrication by 3D printing, using Fused Filament Fabrication (FFF) process.
 - Material used for printing: PET-G
 - Post processing for preparing model for tests



3D printed model in the printer



Fabricated model

Computation

- Grid size: 2.25 million
- Spalart Allamaras one equation turbulence model
- Second order discretisation was used for spatial and temporal terms
- Residual of the order of 10⁻⁵
- Reynolds number: 58500



Grid independence test

Grid	Number of elements	C _L value at 10 degrees angle of attack	C _D value at 10 degrees angle of attack
Grid 1	1.8 million	0.8262	0.1280
Grid 2	2.25 million	0.8250	0.1265
Grid 3	2.47 million	0.8249	0.1262
Experiment	-	1.063	0.1531

Results and Discussion







 C_L vs C_D for double delta wing^[29] and present study (experimental and computation)







Computation and experiment data comparison

 The following section discusses the flow physics over the BWB model by comparing oil flow and different flow contours from computation

CFD Streamlines and oil flow



Streamlines from CFD with oil flow pattern, 0 degrees angle of attack



Streamlines from CFD with oil flow pattern, 5 degrees angle of attack



Streamlines from CFD with oil flow pattern, 10 degrees angle of attack



Streamlines from CFD with oil flow pattern, 20 degrees angle of attack



Streamlines from CFD with oil flow pattern, 30 degrees Angle of attack



Streamlines from CFD with oil flow pattern, 50 degrees Angle of attack



Streamlines from CFD with oil flow pattern, 40 degrees Angle of attack

Skin friction with oil flow



Vorticity Contours



0 degrees vorticity contours at different x/C



Vorticity contours at different x/C at 5 degrees angle of attack



vorticity contours at different x/C at 10 degrees angle of attack



Vorticity contours at different x/C at 20 degrees angle of attack



Vorticity contours at different x/C at 30 degrees angle of attack



Vorticity contours at different x/C at 40 degrees angle of attack



Vorticity contours at different x/C at 50 degrees angle of attack

Conclusion

- BWB configuration was able to generate good amount of lift in low Reynolds number flows
- BWB configuration exhibits stall at very high angle of attack due to the contribution of center body to the lift production
- Stall observed close to 40 degrees angle of attack
- Max L/D Ratio was observed to be at low angles of attack close to 5 degrees
- BWB exhibits better aerodynamic efficiency compared to 65/40 degree double delta wing^[29].
- At high angles of attack, rear mounted and wing mounted control surface might lose effectivity
- Immense potential as a UAV configuration given good internal volume, high stall angle of attack and better aerodynamic efficiency compared to DDW^[29] at low Reynolds number.

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Thank You



