

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

1. Introduction

Imagine infrastructure in a prograde circular low Earth orbit (LEO) whose primary purpose is to assemble and service massive payloads for Mars departures during multiple departure seasons. Assume each departure is accomplished with one trans-Mars injection (TMI) burn at sufficiently high thrust that it may be modeled impulsively with reasonable accuracy. Under this assumption, a Mars departure season typically lasts about a month, and successive seasons arise once every Mars synodic period such that they are centered about 26 months apart.

Interplanetary trajectories reported in this paper typically see initial definition as geocentric or heliocentric conic loci and are "blended" together using patched conic theory. Ultimately, all trajectories influencing this paper's results are modeled via numeric integration [1] of gravity accelerations exerted by the Earth, the Moon, and the Sun. Whenever within Earth's gravitational sphere of influence (at geocentric distances less than about 1 million km), trajectory modeling also reflects acceleration accounting for Earth's excess equatorial mass, known as the J_2 harmonic. Atmospheric drag experienced by the LEO infrastructure is intentionally omitted from trajectory modeling to avoid vehicle-specific results and to approximate an altitude maintenance strategy preserving infrastructure design lifetime.

This paper assumes the departure LEO is initially at inclination $i = 29^\circ$ with respect to Earth's true equator and at height $H = +400$ km with respect to an Earth equatorial radius $r_E = 6378.136$ km [2] such that $r \equiv H + r_E = 6778.136$ km*. The LEO plane is oriented to target an in-plane, single-impulse TMI on 14.0 July 2020 UT resulting in a Type 1 "short way" Mars intercept on 30.0 January 2021 UT with the associated transfer ellipse from Earth subtending a heliocentric angle less than 180° . A celestial sphere plot (CSP) is used to graphically illustrate geometric constraints governing this in-plane departure.

After the 14.0 July 2020 departure, the infrastructure is coasted in LEO until the next Mars departure season and compared to an ideal LEO with near-minimal i leading to an in-plane, single-impulse TMI on 9.0 September 2022 UT. This TMI solution results in a Type 1 Mars intercept on 28.0 March 2023 UT. A CSP is again applied to illustrating the planar mismatch between the coasted LEO from 2020 and the ideal Mars departure LEO in 2022. Strategies for minimizing this mismatch are then suggested.

2. Earth Departure Geometric Constraints

Orientation of the infrastructure's LEO plane is constrained at Earth departure by geocentric asymptotic velocity \mathbf{v}_∞ associated with the selected Type 1 heliocentric transfer ellipse from Earth to Mars. When Earth heliocentric velocity is subtracted from heliocentric velocity in the transfer ellipse at the Earth departure date, \mathbf{v}_∞ results. In order to provide an efficient in-plane TMI burn, the LEO plane must contain \mathbf{v}_∞ .

* Apogee and perigee heights H_A and H_P reported in this paper are referred to r_E and analytically account for J_2 perturbations [3].

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This paper reports v_∞ Cartesian components reckoned with respect to the geocentric Earth mean equator and equinox of epoch J2000.0 (J2K) coordinate system. In practice, a sufficiently accurate v_∞ is computed from the conic heliocentric transfer ellipse determined by solving a Lambert boundary value problem. Along with specifying a Type 1 heliocentric transfer, boundary values defining this Lambert problem are Earth's heliocentric position at Earth departure, Mars's heliocentric position at Mars arrival, and the time-of-flight between departure and arrival.

As vividly illustrated in [4] on pp. 114-115, v_∞ is the axis of symmetry for a manifold of geocentric Earth departure hyperbolas leading to the desired Type 1 heliocentric transfer. This manifold in turn defines a locus of possible injection points (LPIP) for TMI as illustrated in Figure 1. The LPIP is a small circle whose radius subtends a geocentric angle equal to β (called the asymptote angle) and whose center lies in the $-v_\infty$ direction.

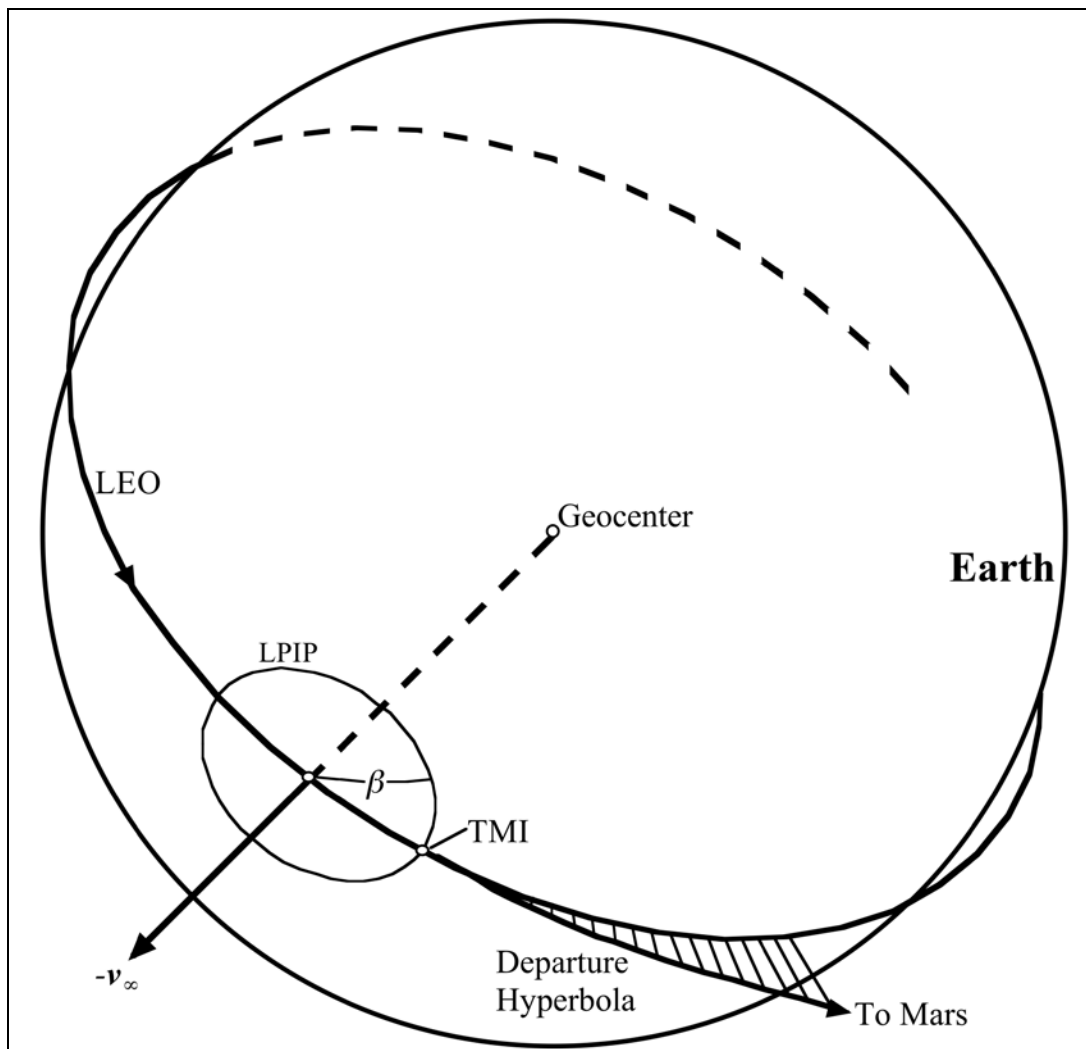


Figure 1. Earth departure geometry for Mars is constrained by $-v_\infty$. As the departure hyperbola approaches interplanetary space, velocity will approach $+v_\infty$.

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Generic departure geometry illustrated in Figure 1 adopts a conventional perspective looking down on Earth's surface from above. To illustrate specific departure geometries developed by this paper, however, geocentric vectors and planes are instead *projected* onto the J2K celestial sphere whose radius is effectively infinite. These CSPs are similar to conventional maps with longitude replaced by J2K right ascension in the horizontal direction, and latitude replaced by J2K declination in the vertical direction. Although north is still upward on a CSP, it should be noted east is to the left because the celestial sphere is being viewed from the geocenter looking outward at its *inside*. Consequently, infrastructure motion in its prograde LEO will be from right to left on a CSP.

Starting in the infrastructure's LEO immediately prior to TMI, a Mars-bound payload first coasts through a geocentric position in the $-\mathbf{v}_\infty$ direction. It then coasts through an arc subtending β before arriving at the TMI point[†]. Because this point is also perigee in a geocentric Earth departure hyperbola coplanar with the LEO, impulsive TMI change in velocity magnitude Δv_{TMI} is minimal. Under this geometry, TMI velocity change will be a purely prograde impulse with zero radial and out-of-plane components.

With the LEO plane constrained to contain \mathbf{v}_∞ , the LEO's i is also constrained as a consequence. If the declination δ_∞ of \mathbf{v}_∞ with respect to Earth's true equator is computed, i must be greater than or equal to $|\delta_\infty|$. In this paper, launches to the LEO-resident infrastructure from a true declination at $+28.5^\circ$ are assumed, a value near that for Cape Canaveral, Florida. To maximize payload mass per launch under this assumption, i will be selected no less than 29° or slightly greater than $|\delta_\infty|$, whichever value is greater.

At a prograde $i > |\delta_\infty|$, there are two LEO planes passing through a geocentric position in the $-\mathbf{v}_\infty$ direction. One plane will satisfy this condition on a northbound heading $0 < \psi < 90^\circ$ east of true north at TMI, and one will satisfy it on a southbound heading $90^\circ < \psi < 180^\circ$ east of true north at TMI. The LEO plane with northbound TMI is arbitrarily selected in lieu of compelling rationale to the contrary.

3. Earth Departure Date And LEO Inclination Selection

Earth departure date and infrastructure LEO i selection are facilitated by pork chop charts (PCCs). In this paper's context, a PCC is a two-dimensional matrix of values from an ordered array of Type 1 Lambert solutions each having Earth departure date t_D and Mars arrival date t_A . The value assigned to each solution in the matrix maps a third dimension and may be any single variable relatable to all the solutions. Matrix elements having t_D later than the corresponding t_A are left blank (no value is assigned).

[†] If this geometry is applied to planetary arrival, its description is somewhat altered. The arriving payload coasts to periapsis along its planetocentric approach hyperbola, where a retrograde orbit insertion impulse is applied. After coasting in the insertion orbit through a planetocentric arc subtending β , the payload passes through a planetocentric position in the $+\mathbf{v}_\infty$ direction.

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By convention, a PCC's columns increment from left-to-right with increasing t_D , and its rows increment from top-to-bottom with increasing t_A . Per the previous section's Earth departure geometric constraints, values assigned to each PCC matrix element are $|v_\infty|$ or δ_∞ . Values in a PCC are color-coded to indicate low (green), medium (pink), or high (red) magnitudes. When $|v_\infty|$ values are assigned, the low/medium threshold is 4 km/s, and the medium/high threshold is 6 km/s. For δ_∞ , the low/medium threshold is 28.5° , and the medium/high threshold is 57° .

The PCC pair governing selection of the 2020 Earth departure case appears in Figures 2 and 3. A notional 10-day departure season is boxed, but the actual departure case is the season-opening t_D at 14.0 July 2020 UT with $|v_\infty| = 3.665$ km/s. Since $\delta_\infty = +26.822^\circ$ for this case, $i = 29^\circ$ is selected.

| | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | R | S | T |
|----|-------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|-------------------|---------|---------|---------|--------|---------|---------|---------|----------|----------|
| 1 | Mars Arrive | | | | | | | | | | Earth Depart Date | | | | | | | | | |
| 2 | Date | 4/25/20 | 5/5/20 | 5/15/20 | 5/25/20 | 6/4/20 | 6/14/20 | 6/24/20 | 7/4/20 | 7/14/20 | 7/24/20 | 8/3/20 | 8/13/20 | 8/23/20 | 9/2/20 | 9/12/20 | 9/22/20 | 10/2/20 | 10/12/20 | 10/22/20 |
| 3 | 5/5/20 | 208.536 | | | | | | | | | | | | | | | | | | |
| 4 | 5/15/20 | 99.212 | 195.961 | | | | | | | | | | | | | | | | | |
| 5 | 5/25/20 | 63.285 | 93.045 | 183.769 | | | | | | | | | | | | | | | | |
| 6 | 6/4/20 | 45.590 | 59.241 | 87.063 | 171.956 | | | | | | | | | | | | | | | |
| 7 | 6/14/20 | 35.105 | 42.610 | 55.313 | 81.260 | 160.588 | | | | | | | | | | | | | | |
| 8 | 6/24/20 | 28.177 | 32.771 | 39.708 | 51.490 | 75.693 | 149.591 | | | | | | | | | | | | | |
| 9 | 7/4/20 | 23.260 | 26.281 | 30.491 | 36.870 | 47.830 | 70.290 | 138.967 | | | | | | | | | | | | |
| 10 | 7/14/20 | 19.599 | 21.685 | 24.422 | 28.245 | 34.153 | 44.263 | 65.065 | 128.772 | | | | | | | | | | | |
| 11 | 7/24/20 | 16.781 | 18.267 | 20.133 | 22.578 | 26.095 | 31.494 | 40.804 | 60.070 | 118.941 | | | | | | | | | | |
| 12 | 8/3/20 | 14.562 | 15.640 | 16.949 | 18.579 | 20.808 | 23.979 | 28.904 | 37.509 | 55.245 | 109.538 | | | | | | | | | |
| 13 | 8/13/20 | 12.791 | 13.574 | 14.506 | 15.618 | 17.087 | 19.058 | 21.907 | 26.444 | 34.323 | 50.661 | 100.679 | | | | | | | | |
| 14 | 8/23/20 | 11.363 | 11.926 | 12.588 | 13.351 | 14.337 | 15.602 | 17.334 | 19.945 | 24.065 | 31.317 | 46.411 | 92.415 | | | | | | | |
| 15 | 9/2/20 | 10.208 | 10.598 | 11.060 | 11.574 | 12.237 | 13.056 | 14.131 | 15.707 | 18.048 | 21.839 | 28.588 | 42.525 | 85.016 | | | | | | |
| 16 | 9/12/20 | 9.276 | 9.524 | 9.830 | 10.160 | 10.595 | 11.118 | 11.780 | 12.750 | 14.137 | 16.293 | 19.872 | 26.166 | 39.224 | 78.810 | | | | | |
| 17 | 9/22/20 | 8.529 | 8.655 | 8.836 | 9.025 | 9.292 | 9.608 | 9.988 | 10.589 | 11.421 | 12.704 | 14.794 | 18.198 | 24.264 | 36.728 | 74.165 | | | | |
| 18 | 10/2/20 | 7.945 | 7.954 | 8.030 | 8.108 | 8.249 | 8.414 | 8.616 | 8.961 | 9.450 | 10.231 | 11.534 | 13.595 | 17.035 | 23.070 | 35.254 | 71.663 | | | |
| 19 | 10/12/20 | 7.520 | 7.393 | 7.380 | 7.368 | 7.410 | 7.463 | 7.531 | 7.709 | 7.979 | 8.458 | 9.318 | 10.681 | 12.916 | 16.549 | 22.736 | 35.138 | 71.722 | | |
| 20 | 10/22/20 | 7.320 | 6.954 | 6.856 | 6.770 | 6.734 | 6.701 | 6.672 | 6.734 | 6.862 | 7.154 | 7.738 | 8.740 | 10.364 | 12.900 | 16.840 | 23.481 | 36.480 | 74.581 | |
| 21 | 11/1/20 | 8.305 | 6.624 | 6.438 | 6.290 | 6.191 | 6.092 | 5.990 | 5.971 | 6.004 | 6.183 | 6.639 | 7.411 | 8.710 | 10.660 | 13.591 | 18.035 | 25.261 | 39.276 | 80.280 |
| 22 | 11/11/20 | 61.926 | 6.424 | 6.107 | 5.907 | 5.758 | 5.606 | 5.449 | 5.373 | 5.345 | 5.456 | 5.830 | 6.490 | 7.615 | 9.291 | 11.648 | 15.044 | 20.005 | 27.988 | 43.436 |
| 23 | 11/21/20 | 62.101 | 7.214 | 5.846 | 5.606 | 5.416 | 5.222 | 5.024 | 4.907 | 4.839 | 4.913 | 5.246 | 5.850 | 6.880 | 8.382 | 10.425 | 13.244 | 17.086 | 22.641 | 31.557 |
| 24 | 12/1/20 | 62.059 | 62.011 | 5.640 | 5.377 | 5.154 | 4.924 | 4.693 | 4.547 | 4.453 | 4.509 | 4.826 | 5.405 | 6.383 | 7.777 | 9.623 | 12.089 | 15.292 | 19.616 | 25.852 |
| 25 | 12/11/20 | 61.980 | 61.995 | 42.488 | 5.243 | 4.967 | 4.702 | 4.442 | 4.273 | 4.163 | 4.212 | 4.525 | 5.095 | 6.043 | 7.365 | 9.075 | 11.306 | 14.104 | 17.709 | 22.565 |
| 26 | 12/21/20 | 61.869 | 61.949 | 61.932 | 5.672 | 4.880 | 4.555 | 4.263 | 4.072 | 3.950 | 3.997 | 4.312 | 4.878 | 5.806 | 7.074 | 8.685 | 10.747 | 13.268 | 16.409 | 20.451 |
| 27 | 12/31/20 | 61.727 | 61.871 | 61.930 | 60.705 | 5.077 | 4.501 | 4.153 | 3.935 | 3.800 | 3.844 | 4.161 | 4.725 | 5.636 | 6.860 | 8.393 | 10.327 | 12.646 | 15.466 | 18.978 |
| 28 | 1/10/21 | 61.555 | 61.763 | 61.888 | 61.852 | 7.979 | 4.633 | 4.125 | 3.859 | 3.704 | 3.741 | 4.055 | 4.614 | 5.508 | 6.694 | 8.162 | 9.995 | 12.158 | 14.742 | 17.887 |
| 29 | 1/20/21 | 61.352 | 61.624 | 61.814 | 61.881 | 60.801 | 5.456 | 4.229 | 3.852 | 3.658 | 3.679 | 3.984 | 4.533 | 5.408 | 6.559 | 7.971 | 9.718 | 11.758 | 14.161 | 17.035 |
| 30 | 1/30/21 | 61.121 | 61.456 | 61.708 | 61.848 | 61.760 | 12.527 | 4.652 | 3.940 | 3.665 | 3.652 | 3.939 | 4.473 | 5.325 | 6.443 | 7.804 | 9.479 | 11.416 | 13.674 | 16.341 |
| 31 | 2/9/21 | 60.863 | 61.259 | 61.573 | 61.779 | 61.819 | 60.713 | 6.246 | 4.207 | 3.741 | 3.664 | 3.918 | 4.428 | 5.255 | 6.338 | 7.653 | 9.263 | 11.113 | 13.251 | 15.753 |
| 32 | 2/19/21 | 60.577 | 61.034 | 61.408 | 61.677 | 61.797 | 61.721 | 17.393 | 4.913 | 3.925 | 3.721 | 3.920 | 4.396 | 5.192 | 6.241 | 7.511 | 9.063 | 10.837 | 12.874 | 15.241 |
| 33 | 3/1/21 | 60.266 | 60.782 | 61.216 | 61.546 | 61.733 | 61.812 | 60.518 | 7.149 | 4.323 | 3.845 | 3.951 | 4.378 | 5.136 | 6.148 | 7.376 | 8.875 | 10.581 | 12.530 | 14.782 |
| 34 | 3/11/21 | 59.930 | 60.504 | 60.996 | 61.386 | 61.636 | 61.801 | 61.693 | 60.520 | 5.237 | 4.083 | 4.020 | 4.375 | 5.087 | 6.060 | 7.245 | 8.694 | 10.338 | 12.209 | 14.362 |
| 35 | 3/21/21 | 59.569 | 60.201 | 60.749 | 61.198 | 61.508 | 61.742 | 61.822 | 60.172 | 7.839 | 4.547 | 4.152 | 4.395 | 5.047 | 5.976 | 7.118 | 8.519 | 10.106 | 11.907 | 13.973 |
| 36 | 3/31/21 | 59.186 | 59.873 | 60.477 | 60.983 | 61.351 | 61.648 | 61.823 | 61.647 | 21.219 | 5.544 | 4.394 | 4.448 | 5.018 | 5.896 | 6.994 | 8.348 | 9.882 | 11.619 | 13.607 |
| 37 | 4/10/21 | 58.780 | 59.521 | 60.180 | 60.743 | 61.168 | 61.523 | 61.770 | 61.820 | 59.647 | 8.188 | 4.833 | 4.557 | 5.007 | 5.823 | 6.873 | 8.181 | 9.665 | 11.342 | 13.259 |
| 38 | 4/20/21 | 58.353 | 59.147 | 59.859 | 60.477 | 60.957 | 61.369 | 61.680 | 61.835 | 61.641 | 19.989 | 5.812 | 4.766 | 5.024 | 5.759 | 6.757 | 8.017 | 9.453 | 11.074 | 12.926 |
| 39 | 4/30/21 | 57.905 | 58.750 | 59.514 | 60.186 | 60.721 | 61.189 | 61.559 | 61.788 | 61.872 | 58.677 | 8.238 | 5.168 | 5.088 | 5.710 | 6.646 | 7.857 | 9.245 | 10.813 | 12.605 |
| 40 | 5/10/21 | 57.436 | 58.332 | 59.147 | 59.871 | 60.460 | 60.981 | 61.408 | 61.702 | 61.902 | 61.627 | 17.798 | 6.008 | 5.235 | 5.684 | 6.543 | 7.702 | 9.043 | 10.560 | 12.295 |
| 41 | 5/20/21 | 56.948 | 57.892 | 58.757 | 59.532 | 60.174 | 60.748 | 61.231 | 61.583 | 61.861 | 61.936 | 56.751 | 8.064 | 5.543 | 5.694 | 6.452 | 7.551 | 8.844 | 10.312 | 11.993 |
| 42 | 5/30/21 | 56.442 | 57.432 | 58.345 | 59.171 | 59.864 | 60.490 | 61.026 | 61.434 | 61.777 | 61.984 | 61.569 | 15.357 | 6.204 | 5.770 | 6.378 | 7.408 | 8.650 | 10.070 | 11.699 |
| 43 | 6/9/21 | 55.916 | 56.952 | 57.912 | 58.787 | 59.530 | 60.207 | 60.796 | 61.258 | 61.659 | 61.949 | 61.987 | 52.732 | 7.811 | 5.970 | 6.333 | 7.273 | 8.462 | 9.832 | 11.412 |
| 44 | 6/19/21 | 55.373 | 56.453 | 57.458 | 58.381 | 59.173 | 59.900 | 60.541 | 61.056 | 61.512 | 61.868 | 62.055 | 61.510 | 13.089 | 6.437 | 6.336 | 7.152 | 8.279 | 9.600 | 11.131 |
| 45 | 6/29/21 | 54.812 | 55.935 | 56.983 | 57.953 | 58.793 | 59.569 | 60.261 | 60.827 | 61.336 | 61.751 | 62.026 | 62.089 | 44.513 | 7.595 | 6.429 | 7.051 | 8.103 | 9.372 | 10.856 |
| 46 | 7/9/21 | 54.234 | 55.397 | 56.488 | 57.503 | 58.391 | 59.214 | 59.956 | 60.573 | 61.134 | 61.604 | 61.945 | 62.179 | 61.366 | 11.237 | 6.711 | 6.984 | 7.937 | 9.150 | 10.586 |
| 47 | 7/19/21 | 53.640 | 54.842 | 55.974 | 57.033 | 57.966 | 58.836 | 59.627 | 60.294 | 60.905 | 61.429 | 61.829 | 62.153 | 62.196 | 32.797 | 7.469 | 6.978 | 7.786 | 8.934 | 10.321 |
| 48 | 7/29/21 | 53.028 | 54.268 | 55.439 | 56.541 | 57.519 | 58.435 | 59.274 | 59.989 | 60.650 | 61.226 | 61.681 | 62.073 | 62.312 | 61.052 | 9.843 | 7.096 | 7.656 | 8.725 | 10.060 |
| 49 | 8/8/21 | 52.401 | 53.677 | 54.886 | 56.029 | 57.050 | 58.011 | 58.896 | 59.660 | 60.370 | 60.996 | 61.503 | 61.954 | 62.289 | 62.293 | 22.666 | 7.518 | 7.565 | 8.525 | 9.805 |
| 50 | 8/18/21 | 51.757 | 53.068 | 54.313 | 55.496 | 56.560 | 57.564 | 58.495 | 59.306 | 60.064 | 60.740 | 61.298 | 61.803 | 62.207 | 62.435 | 60.460 | 8.931 | 7.551 | 8.340 | 9.555 |

Figure 2. Values of $|v_\infty|$ targeting Mars are tabulated for year 2020 Earth departure dates. The 14.0 July 2020 UT opening date of a notional 10-day departure season (boxed) has $|v_\infty| = 3.665$ km/s and is selected for assessment.

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| | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | R | S | T |
|----|-------------|---------|---------|---------|---------|--------|---------|---------|---------|---------|-------------------|---------|---------|---------|---------|---------|---------|---------|----------|----------|
| 1 | Mars Arrive | | | | | | | | | | Earth Depart Date | | | | | | | | | |
| 2 | Date | 4/25/20 | 5/5/20 | 5/15/20 | 5/25/20 | 6/4/20 | 6/14/20 | 6/24/20 | 7/4/20 | 7/14/20 | 7/24/20 | 8/3/20 | 8/13/20 | 8/23/20 | 9/2/20 | 9/12/20 | 9/22/20 | 10/2/20 | 10/12/20 | 10/22/20 |
| 3 | 5/9/20 | -15.001 | | | | | | | | | | | | | | | | | | |
| 4 | 5/15/20 | -12.896 | -12.845 | | | | | | | | | | | | | | | | | |
| 5 | 5/25/20 | -10.828 | -10.611 | -10.579 | | | | | | | | | | | | | | | | |
| 6 | 6/4/20 | -8.920 | -8.440 | -8.257 | -8.259 | | | | | | | | | | | | | | | |
| 7 | 6/14/20 | -7.258 | -6.453 | -6.023 | -5.902 | -5.936 | | | | | | | | | | | | | | |
| 8 | 6/24/20 | -5.886 | -4.732 | -3.993 | -3.655 | -3.593 | -3.653 | | | | | | | | | | | | | |
| 9 | 7/4/20 | -4.813 | -3.314 | -2.242 | -1.628 | -1.383 | -1.370 | -1.474 | | | | | | | | | | | | |
| 10 | 7/14/20 | -4.030 | -2.203 | -0.803 | 0.110 | 0.595 | 0.762 | 0.692 | 0.555 | | | | | | | | | | | |
| 11 | 7/24/20 | -3.520 | -1.985 | 0.324 | 1.532 | 2.278 | 2.654 | 2.692 | 2.556 | 2.390 | | | | | | | | | | |
| 12 | 8/3/20 | -3.265 | -0.834 | 1.162 | 2.645 | 3.646 | 4.252 | 4.449 | 4.378 | 4.180 | 3.966 | | | | | | | | | |
| 13 | 8/13/20 | -3.251 | -0.523 | 1.743 | 3.475 | 4.711 | 5.543 | 5.918 | 5.956 | 5.783 | 5.489 | 5.252 | | | | | | | | |
| 14 | 8/23/20 | -3.470 | -0.424 | 2.102 | 4.062 | 5.506 | 6.544 | 7.092 | 7.257 | 7.146 | 6.816 | 6.466 | 6.202 | | | | | | | |
| 15 | 9/2/20 | -3.926 | -0.512 | 2.279 | 4.449 | 6.075 | 7.292 | 7.995 | 8.281 | 8.247 | 7.907 | 7.474 | 7.063 | 6.768 | | | | | | |
| 16 | 9/12/20 | -4.640 | -0.764 | 2.312 | 4.683 | 6.469 | 7.837 | 8.666 | 9.054 | 9.091 | 8.749 | 8.249 | 7.706 | 7.227 | 6.948 | | | | | |
| 17 | 9/22/20 | -5.675 | -1.163 | 2.243 | 4.815 | 6.742 | 8.235 | 9.161 | 9.621 | 9.709 | 9.353 | 8.783 | 8.112 | 7.453 | 7.000 | 6.741 | | | | |
| 18 | 10/2/20 | -7.187 | -1.697 | 2.117 | 4.900 | 6.953 | 8.546 | 9.538 | 10.039 | 10.147 | 9.751 | 9.093 | 8.285 | 7.444 | 6.825 | 6.414 | 6.217 | | | |
| 19 | 10/12/20 | -9.606 | -2.377 | 1.989 | 5.003 | 7.169 | 8.836 | 9.863 | 10.371 | 10.463 | 9.990 | 9.214 | 8.247 | 7.218 | 6.448 | 5.914 | 5.634 | 5.566 | | |
| 20 | 10/22/20 | -14.412 | -3.266 | 1.922 | 5.200 | 7.465 | 9.178 | 10.208 | 10.684 | 10.722 | 10.129 | 9.195 | 8.044 | 6.826 | 5.929 | 5.312 | 5.000 | 4.953 | 4.996 | |
| 21 | 11/1/20 | -30.257 | -4.589 | 2.013 | 5.596 | 7.930 | 9.654 | 10.649 | 11.054 | 10.994 | 10.234 | 9.101 | 7.744 | 6.343 | 5.353 | 4.701 | 4.409 | 4.433 | 4.567 | 4.738 |
| 22 | 11/11/20 | 15.384 | -7.354 | 2.439 | 6.347 | 8.684 | 10.358 | 11.270 | 11.557 | 11.353 | 10.378 | 9.006 | 7.426 | 5.859 | 4.814 | 4.171 | 3.941 | 4.068 | 4.322 | 4.646 |
| 23 | 11/21/20 | 18.871 | -24.781 | 3.667 | 7.736 | 9.896 | 11.410 | 12.165 | 12.275 | 11.875 | 10.634 | 8.987 | 7.176 | 5.465 | 4.395 | 3.790 | 3.643 | 3.888 | 4.273 | 4.754 |
| 24 | 12/1/20 | 19.129 | 17.209 | 7.962 | 10.409 | 11.848 | 12.969 | 13.446 | 13.295 | 12.635 | 11.076 | 9.118 | 7.069 | 5.229 | 4.149 | 3.591 | 3.531 | 3.891 | 4.402 | 5.032 |
| 25 | 12/11/20 | 18.984 | 17.328 | 61.609 | 16.381 | 15.092 | 15.280 | 15.252 | 14.712 | 13.708 | 11.768 | 9.461 | 7.162 | 5.193 | 4.099 | 3.582 | 3.596 | 4.056 | 4.679 | 5.443 |
| 26 | 12/21/20 | 18.706 | 16.992 | 15.907 | 36.282 | 20.938 | 18.763 | 17.777 | 16.636 | 15.168 | 12.770 | 10.063 | 7.490 | 5.376 | 4.247 | 3.748 | 3.817 | 4.357 | 5.073 | 5.950 |
| 27 | 12/31/20 | 18.366 | 16.566 | 14.938 | 33.326 | 24.239 | 21.320 | 19.207 | 17.096 | 14.134 | 10.959 | 8.071 | 5.777 | 4.581 | 4.078 | 4.171 | 4.767 | 5.557 | 6.526 | |
| 28 | 1/10/21 | 17.990 | 16.107 | 14.245 | 13.455 | 65.768 | 33.532 | 26.389 | 22.627 | 19.587 | 15.913 | 12.177 | 8.914 | 6.392 | 5.087 | 4.635 | 5.265 | 6.106 | 7.147 | |
| 29 | 1/20/21 | 17.590 | 15.630 | 13.623 | 11.971 | 17.784 | 50.918 | 33.906 | 27.198 | 22.768 | 18.166 | 13.745 | 10.024 | 7.212 | 5.750 | 5.125 | 5.191 | 5.831 | 6.704 | 7.798 |
| 30 | 1/30/21 | 17.174 | 15.144 | 13.031 | 11.044 | 10.448 | 77.985 | 45.571 | 33.410 | 26.822 | 20.971 | 15.695 | 11.411 | 8.233 | 6.560 | 5.818 | 5.827 | 6.453 | 7.339 | 8.466 |
| 31 | 2/9/21 | 16.746 | 14.651 | 12.454 | 10.282 | 8.647 | 14.259 | 63.693 | 42.043 | 32.017 | 24.444 | 18.074 | 13.092 | 9.456 | 7.510 | 6.611 | 6.531 | 7.121 | 8.001 | 9.145 |
| 32 | 2/19/21 | 16.307 | 14.153 | 11.886 | 9.592 | 7.551 | 7.178 | 72.403 | 54.162 | 38.749 | 28.737 | 20.952 | 15.093 | 10.889 | 8.600 | 7.498 | 7.297 | 7.828 | 8.684 | 9.828 |
| 33 | 3/1/21 | 15.861 | 13.632 | 11.325 | 8.943 | 6.686 | 5.132 | 11.221 | 69.593 | 47.558 | 34.080 | 24.828 | 17.459 | 12.549 | 9.834 | 8.477 | 8.123 | 8.571 | 9.384 | 10.513 |
| 34 | 3/11/21 | 15.408 | 13.148 | 10.769 | 8.317 | 5.926 | 3.904 | 3.820 | 65.925 | 58.827 | 40.781 | 28.645 | 20.253 | 14.463 | 11.221 | 9.551 | 9.006 | 9.346 | 10.099 | 11.198 |
| 35 | 3/21/21 | 14.949 | 12.641 | 10.215 | 7.709 | 5.225 | 2.960 | 1.538 | 8.766 | 70.581 | 49.188 | 33.806 | 23.569 | 16.671 | 12.778 | 10.272 | 9.949 | 10.155 | 10.829 | 11.883 |
| 36 | 3/31/21 | 14.484 | 12.132 | 9.684 | 7.112 | 4.561 | 2.150 | 0.194 | 0.553 | 62.141 | 59.335 | 40.177 | 27.540 | 19.234 | 14.532 | 12.014 | 10.955 | 10.998 | 11.573 | 12.568 |
| 37 | 4/10/21 | 14.015 | 11.621 | 9.116 | 6.524 | 3.922 | 1.416 | -0.812 | -1.994 | 7.170 | 68.699 | 48.044 | 32.353 | 22.236 | 16.519 | 13.430 | 12.031 | 11.877 | 12.333 | 13.254 |
| 38 | 4/20/21 | 13.542 | 11.109 | 8.569 | 5.949 | 3.301 | 0.728 | -1.657 | -3.450 | -2.486 | 60.775 | 57.392 | 38.260 | 25.802 | 18.792 | 14.995 | 13.187 | 12.798 | 13.110 | 13.942 |
| 39 | 4/30/21 | 13.064 | 10.595 | 8.023 | 5.368 | 2.693 | 0.073 | -2.412 | -4.509 | -5.358 | 6.956 | 66.062 | 45.550 | 30.105 | 21.424 | 16.742 | 14.436 | 13.765 | 13.909 | 14.634 |
| 40 | 5/10/21 | 12.583 | 10.079 | 7.478 | 4.798 | 2.096 | -0.558 | -3.109 | -5.380 | -6.930 | -5.170 | 61.029 | 54.311 | 35.396 | 24.524 | 18.714 | 15.797 | 14.788 | 14.732 | 15.332 |
| 41 | 5/20/21 | 12.099 | 9.562 | 6.934 | 4.231 | 1.508 | -1.172 | -3.767 | -6.143 | -8.037 | -8.468 | 9.016 | 63.065 | 41.999 | 28.251 | 20.974 | 17.294 | 15.877 | 15.585 | 16.038 |
| 42 | 5/30/21 | 11.611 | 9.043 | 6.391 | 3.668 | 0.927 | -1.772 | -4.397 | -6.839 | -8.922 | -10.173 | -7.327 | 61.883 | 50.193 | 32.840 | 23.612 | 18.962 | 17.046 | 16.474 | 16.756 |
| 43 | 6/9/21 | 11.119 | 8.522 | 5.848 | 3.107 | 0.352 | -2.361 | -5.005 | -7.488 | -9.663 | -11.324 | -11.206 | 14.843 | 59.331 | 38.634 | 26.763 | 20.851 | 18.319 | 17.407 | 17.490 |
| 44 | 6/19/21 | 10.625 | 8.000 | 5.305 | 2.549 | -0.218 | -2.940 | -5.996 | -8.105 | -10.366 | -12.216 | -13.066 | -8.804 | 62.540 | 46.073 | 30.636 | 23.033 | 19.709 | 18.394 | 18.245 |
| 45 | 6/29/21 | 10.127 | 7.477 | 4.762 | 1.993 | -0.783 | -3.511 | -6.173 | -8.696 | -10.996 | -12.964 | -14.259 | -13.492 | 26.008 | 55.258 | 35.560 | 25.617 | 21.266 | 19.450 | 19.025 |
| 46 | 7/9/21 | 9.626 | 6.951 | 4.219 | 1.438 | -1.345 | -4.076 | -6.739 | -9.268 | -11.588 | -13.623 | -15.148 | -15.531 | -9.394 | 62.374 | 42.042 | 28.776 | 23.041 | 20.594 | 19.838 |
| 47 | 7/19/21 | 9.121 | 6.424 | 3.676 | 0.885 | -1.903 | -4.634 | -7.296 | -9.823 | -12.151 | -14.221 | -15.872 | -16.760 | -15.258 | 40.185 | 50.687 | 32.794 | 25.117 | 21.851 | 20.693 |
| 48 | 7/29/21 | 8.613 | 5.894 | 3.132 | 0.332 | -2.459 | -5.188 | -7.844 | -10.365 | -12.690 | -14.776 | -16.495 | -17.634 | -17.505 | -8.814 | 60.999 | 38.164 | 27.627 | 23.262 | 21.603 |
| 49 | 8/8/21 | 8.102 | 5.363 | 2.587 | -0.220 | -3.012 | -5.737 | -8.394 | -10.895 | -13.211 | -15.298 | -17.049 | -18.320 | -18.761 | -16.436 | 52.160 | 45.718 | 30.798 | 24.885 | 22.585 |
| 50 | 8/18/21 | 7.587 | 4.829 | 2.041 | -0.771 | -3.563 | -6.281 | -8.918 | -11.414 | -13.716 | -15.793 | -17.554 | -18.892 | -19.606 | -18.913 | -6.642 | 56.247 | 35.041 | 26.815 | 23.664 |

Figure 3. Values of δ targeting Mars are tabulated for year 2020 Earth departure dates. The 14.0 July 2020 UT opening date of a notional 10-day departure season (boxed) has $\delta_\infty = +26.822^\circ$ and is selected for assessment.

The \mathbf{v}_∞ vector for Earth departure on 14.0 July 2020 UT, leading to Type 1 Mars arrival on 30.0 January 2021 UT, is defined with J2K components in Equation (1).

$$\mathbf{v}_{\infty 20} = \begin{bmatrix} +3.078800 \\ +1.112367 \\ +1.647601 \end{bmatrix} \text{ km/s} \quad (1)$$

Earth departures for Mars in 2022 are more performance-challenged than those in 2020. No Type 1 trajectory with $|\mathbf{v}_\infty| < 4$ km/s is available. To make matters worse, δ_∞ cannot be brought much lower than $+40^\circ$ without substantially increasing $|\mathbf{v}_\infty|$ to more than 5 km/s. The PCC pair governing selection of the 2022 Earth departure case appears in Figures 4 and 5. A notional 10-day departure season is boxed, but the actual departure case is the season-opening t_D at 9.0 September 2022 UT with $|\mathbf{v}_\infty| = 4.309$ km/s. Since $\delta_\infty = +44.496^\circ$ for this case, $i = 45^\circ$ is selected.

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

| | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | R | S | T |
|----|-------------|-------------------|---------|---------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|---------|----------|----------|---------|----------|----------|
| 1 | Mars Arrive | Earth Depart Date | | | | | | | | | | | | | | | | | | |
| 2 | Date | 7/1/22 | 7/11/22 | 7/21/22 | 7/31/22 | 8/10/22 | 8/20/22 | 8/30/22 | 9/9/22 | 9/19/22 | 9/29/22 | 10/9/22 | 10/19/22 | 10/29/22 | 11/8/22 | 11/18/22 | 11/28/22 | 12/8/22 | 12/18/22 | 12/28/22 |
| 3 | 7/11/22 | 216.412 | | | | | | | | | | | | | | | | | | |
| 4 | 7/21/22 | 104.852 | 207.160 | | | | | | | | | | | | | | | | | |
| 5 | 7/31/22 | 68.022 | 100.130 | 197.788 | | | | | | | | | | | | | | | | |
| 6 | 8/10/22 | 49.753 | 64.795 | 95.312 | 188.234 | | | | | | | | | | | | | | | |
| 7 | 8/20/22 | 38.836 | 47.277 | 61.481 | 90.368 | 178.538 | | | | | | | | | | | | | | |
| 8 | 8/30/22 | 31.559 | 36.819 | 44.718 | 58.057 | 85.355 | 168.631 | | | | | | | | | | | | | |
| 9 | 9/9/22 | 26.354 | 29.857 | 34.722 | 42.053 | 54.584 | 80.215 | 158.530 | | | | | | | | | | | | |
| 10 | 9/19/22 | 22.447 | 24.887 | 28.071 | 32.520 | 39.595 | 51.014 | 74.900 | 148.351 | | | | | | | | | | | |
| 11 | 9/29/22 | 19.415 | 21.153 | 23.336 | 26.193 | 30.285 | 36.564 | 47.381 | 69.751 | 138.121 | 128.043 | | | | | | | | | |
| 12 | 10/9/22 | 17.006 | 18.261 | 19.787 | 21.688 | 24.279 | 27.977 | 33.730 | 43.786 | 64.536 | 80.043 | 118.424 | | | | | | | | |
| 13 | 10/19/22 | 15.059 | 15.964 | 17.037 | 18.321 | 20.012 | 22.300 | 25.630 | 30.953 | 40.235 | 59.500 | 78.448 | 109.572 | | | | | | | |
| 14 | 10/29/22 | 13.466 | 14.108 | 14.856 | 15.717 | 16.831 | 18.278 | 20.289 | 23.354 | 28.242 | 36.886 | 54.866 | 73.948 | 102.078 | | | | | | |
| 15 | 11/8/22 | 12.152 | 12.591 | 13.096 | 13.656 | 14.378 | 15.290 | 16.523 | 18.362 | 21.163 | 25.757 | 33.948 | 50.831 | 70.257 | 102.078 | | | | | |
| 16 | 11/18/22 | 11.065 | 11.340 | 11.658 | 12.022 | 12.442 | 12.995 | 13.733 | 14.858 | 16.540 | 19.225 | 23.709 | 31.990 | 47.810 | 66.614 | 96.614 | | | | |
| 17 | 11/28/22 | 10.168 | 10.307 | 10.475 | 10.642 | 10.887 | 11.192 | 11.606 | 12.288 | 13.24 | 15.001 | 17.761 | 22.261 | 30.170 | 46.184 | 63.835 | | | | |
| 18 | 12/8/22 | 9.441 | 9.454 | 9.499 | 9.532 | 9.626 | 9.753 | 9.948 | 10.346 | 10.994 | 12.107 | 13.977 | 16.927 | 21.735 | 29.947 | 47.179 | 94.415 | | | |
| 19 | 12/18/22 | 8.892 | 8.762 | 8.696 | 8.619 | 8.596 | 8.592 | 8.636 | 8.852 | 9.264 | 10.055 | 11.445 | 13.614 | 17.008 | 22.288 | 31.038 | 46.944 | 98.547 | | |
| 20 | 12/28/22 | 8.401 | 8.225 | 8.042 | 7.870 | 7.754 | 7.653 | 7.592 | 7.691 | 7.963 | 8.576 | 9.709 | 11.465 | 14.143 | 18.062 | 23.914 | 33.490 | 52.572 | 106.053 | |
| 21 | 1/7/23 | 9.018 | 7.873 | 7.529 | 7.262 | 7.067 | 6.891 | 6.759 | 6.785 | 6.981 | 7.505 | 8.508 | 10.045 | 12.333 | 15.530 | 19.889 | 26.556 | 37.052 | 57.810 | 116.514 |
| 22 | 1/17/23 | 13.999 | 7.841 | 7.164 | 6.782 | 6.513 | 6.278 | 6.096 | 6.082 | 6.242 | 6.734 | 7.679 | 9.100 | 11.161 | 13.934 | 17.618 | 22.685 | 29.937 | 41.507 | 64.363 |
| 23 | 1/27/23 | 57.922 | 8.739 | 6.998 | 6.429 | 6.078 | 5.790 | 5.573 | 5.539 | 5.693 | 6.185 | 7.112 | 8.469 | 10.388 | 12.889 | 16.091 | 20.294 | 25.889 | 33.887 | 46.660 |
| 24 | 2/6/23 | 61.803 | 14.904 | 7.204 | 6.222 | 5.794 | 5.411 | 5.167 | 5.127 | 5.291 | 5.800 | 6.727 | 8.049 | 9.869 | 12.180 | 15.057 | 18.705 | 23.326 | 29.475 | 38.270 |
| 25 | 2/16/23 | 62.044 | 16.696 | 8.461 | 6.222 | 5.545 | 5.130 | 4.861 | 4.820 | 5.001 | 5.536 | 6.470 | 7.766 | 9.512 | 11.680 | 14.321 | 17.586 | 21.574 | 26.627 | 33.352 |
| 26 | 2/26/23 | 22.447 | 24.887 | 28.071 | 32.520 | 39.595 | 51.014 | 74.900 | 148.351 | 4.599 | 4.798 | 5.356 | 6.297 | 7.572 | 9.257 | 11.312 | 13.772 | 16.756 | 20.303 | 30.134 |
| 27 | 3/8/23 | 62.005 | 61.986 | 54.369 | 48.062 | 43.608 | 4.860 | 4.496 | 4.447 | 4.660 | 5.237 | 6.182 | 7.435 | 9.067 | 11.028 | 13.343 | 16.109 | 19.332 | 23.171 | 27.863 |
| 28 | 3/18/23 | 61.912 | 62.028 | 61.520 | 53.907 | 46.123 | 4.900 | 4.427 | 4.353 | 4.571 | 5.160 | 6.102 | 7.334 | 8.917 | 10.797 | 12.991 | 15.584 | 18.557 | 22.029 | 26.163 |
| 29 | 3/28/23 | 61.786 | 61.988 | 61.982 | 49.890 | 37.582 | 5.124 | 4.437 | 4.309 | 4.520 | 5.110 | 6.045 | 7.253 | 8.790 | 10.598 | 12.690 | 15.140 | 17.914 | 21.104 | 24.830 |
| 30 | 4/7/23 | 61.631 | 62.002 | 62.052 | 61.346 | 52.535 | 5.685 | 4.548 | 4.315 | 4.498 | 5.080 | 6.001 | 7.183 | 8.677 | 10.420 | 12.423 | 14.751 | 17.361 | 20.328 | 23.741 |
| 31 | 4/17/23 | 61.450 | 61.783 | 62.024 | 61.995 | 42.218 | 7.035 | 4.809 | 4.374 | 4.502 | 5.062 | 5.964 | 7.118 | 8.570 | 10.255 | 12.177 | 14.400 | 16.872 | 19.656 | 22.823 |
| 32 | 4/27/23 | 61.241 | 61.634 | 61.945 | 62.011 | 31.015 | 8.015 | 5.343 | 4.503 | 4.531 | 5.054 | 5.930 | 7.055 | 8.466 | 10.095 | 11.945 | 14.075 | 16.428 | 19.059 | 22.025 |
| 33 | 5/7/23 | 61.007 | 61.456 | 61.830 | 62.084 | 61.995 | 32.407 | 6.497 | 4.743 | 4.591 | 5.055 | 5.898 | 6.990 | 8.361 | 9.938 | 11.723 | 13.769 | 16.018 | 18.517 | 21.316 |
| 34 | 5/17/23 | 60.748 | 61.252 | 61.684 | 62.012 | 62.140 | 60.598 | 9.550 | 5.187 | 4.695 | 5.066 | 5.866 | 6.922 | 8.253 | 9.782 | 11.505 | 13.475 | 15.631 | 18.015 | 20.672 |
| 35 | 5/27/23 | 60.463 | 61.022 | 61.509 | 61.901 | 62.135 | 62.042 | 23.510 | 6.088 | 4.874 | 5.092 | 5.834 | 6.852 | 8.142 | 9.624 | 11.290 | 13.191 | 15.263 | 17.545 | 20.278 |
| 36 | 6/6/23 | 60.154 | 60.765 | 61.307 | 61.757 | 62.067 | 62.233 | 59.692 | 8.313 | 5.193 | 5.143 | 5.805 | 6.778 | 8.028 | 9.464 | 11.076 | 12.912 | 14.908 | 17.098 | 19.522 |
| 37 | 6/16/23 | 59.820 | 60.483 | 61.078 | 61.585 | 61.957 | 62.297 | 62.098 | 6.785 | 5.339 | 5.288 | 5.781 | 6.701 | 7.909 | 9.301 | 10.862 | 12.638 | 14.563 | 16.570 | 18.955 |
| 38 | 6/26/23 | 59.461 | 60.175 | 60.822 | 61.383 | 61.815 | 62.171 | 62.345 | 57.629 | 7.352 | 5.421 | 5.769 | 6.623 | 7.786 | 9.135 | 10.647 | 12.366 | 14.226 | 16.255 | 18.492 |
| 39 | 7/6/23 | 59.077 | 59.842 | 60.539 | 61.154 | 61.642 | 62.061 | 62.356 | 62.138 | 12.801 | 5.804 | 5.780 | 6.545 | 7.660 | 8.966 | 10.430 | 12.096 | 13.894 | 15.852 | 18.007 |
| 40 | 7/16/23 | 58.669 | 59.483 | 60.231 | 60.898 | 61.440 | 61.916 | 62.289 | 62.446 | 52.372 | 6.704 | 5.840 | 6.470 | 7.530 | 8.793 | 10.212 | 11.826 | 13.566 | 15.457 | 17.536 |
| 41 | 7/26/23 | 58.236 | 59.099 | 59.896 | 60.615 | 61.209 | 61.741 | 62.177 | 62.458 | 62.231 | 9.968 | 6.012 | 6.405 | 7.398 | 8.616 | 9.991 | 11.556 | 13.241 | 15.070 | 17.078 |
| 42 | 8/5/23 | 57.779 | 58.689 | 59.535 | 60.304 | 60.950 | 61.535 | 62.030 | 62.387 | 62.598 | 39.764 | 6.492 | 6.363 | 7.265 | 8.436 | 9.767 | 11.285 | 12.918 | 14.687 | 16.629 |
| 43 | 8/15/23 | 57.297 | 58.254 | 59.147 | 59.966 | 60.664 | 61.301 | 61.851 | 62.270 | 62.604 | 62.351 | 8.221 | 6.374 | 7.133 | 8.253 | 9.540 | 11.013 | 12.596 | 14.309 | 16.189 |
| 44 | 8/25/23 | 56.790 | 57.792 | 58.732 | 59.601 | 60.349 | 61.037 | 61.641 | 62.117 | 62.525 | 62.761 | 24.294 | 6.531 | 7.008 | 8.067 | 9.311 | 10.740 | 12.275 | 13.954 | 15.754 |
| 45 | 9/4/23 | 56.258 | 57.305 | 58.291 | 59.208 | 60.046 | 60.745 | 61.401 | 61.932 | 62.399 | 62.752 | 62.503 | 7.276 | 7.690 | 8.788 | 9.978 | 11.464 | 13.154 | 14.951 | 16.824 |
| 46 | 9/14/23 | 55.702 | 56.792 | 57.823 | 58.788 | 59.635 | 60.423 | 61.131 | 61.715 | 62.238 | 62.660 | 62.904 | 14.465 | 8.844 | 9.686 | 10.881 | 12.516 | 14.322 | 16.189 | 18.149 |
| 47 | 9/24/23 | 55.120 | 56.253 | 57.327 | 58.339 | 59.235 | 60.072 | 60.832 | 61.468 | 62.044 | 62.525 | 62.867 | 62.783 | 6.990 | 7.495 | 8.600 | 9.905 | 11.308 | 12.819 | 14.476 |
| 48 | 10/4/23 | 54.524 | 55.676 | 56.762 | 57.782 | 58.709 | 59.529 | 60.292 | 60.992 | 61.627 | 62.199 | 62.660 | 62.904 | 14.465 | 8.844 | 9.686 | 10.881 | 12.516 | 14.322 | 16.189 |
| 49 | 10/14/23 | 53.881 | 55.095 | 56.254 | 57.357 | 58.347 | 59.281 | 60.142 | 60.880 | 61.560 | 62.150 | 62.611 | 63.005 | 63.134 | 7.148 | 8.103 | 9.333 | 10.657 | 12.077 | 13.637 |
| 50 | 10/24/23 | 53.224 | 54.476 | 55.676 | 56.822 | 57.859 | 58.840 | 59.750 | 60.540 | 61.271 | 61.913 | 62.428 | 62.878 | 63.220 | 7.252 | 8.044 | 9.341 | 10.728 | 12.176 | 13.719 |

Figure 4. Values of $|v_{\infty}|$ targeting Mars are tabulated for year 2022 Earth departure dates. The 9.0 September 2022 UT opening date of a notional 10-day departure season (boxed) has $|v_{\infty}| = 4.309$ km/s and is selected for assessment.

| | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O | P | Q | R | S | T |
|---|-------------|-------------------|---------|---------|---------|---------|---------|---------|--------|---------|---------|---------|----------|----------|---------|----------|----------|---------|----------|----------|
| 1 | Mars Arrive | Earth Depart Date | | | | | | | | | | | | | | | | | | |
| 2 | Date | 7/1/22 | 7/11/22 | 7/21/22 | 7/31/22 | 8/10/22 | 8/20/22 | 8/30/22 | 9/9/22 | 9/19/22 | 9/29/22 | 10/9/22 | 10/19/22 | 10/29/22 | 11/8/22 | 11/18/22 | 11/28/22 | 12/8/22 | 12/18/22 | 12/28/22 |
| 3 | 7/11/22 | 11.145 | | | | | | | | | | | | | | | | | | |
| 4 | 7/21/22 | 13.291 | 13.393 | | | | | | | | | | | | | | | | | |
| 5 | 7/31/22 | 15.093 | 15. | | | | | | | | | | | | | | | | | |

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

The \mathbf{v}_{∞} vector for Earth departure on 9.0 September 2022 UT, leading to Type 1 Mars arrival on 28.0 March 2023 UT, is defined with J2K components in Equation (2).

$$\mathbf{v}_{\infty 22} = \begin{bmatrix} +1.592308 \\ +2.633242 \\ +3.016596 \end{bmatrix} \text{ km/s} \quad (2)$$

4. Earth Departure Velocity Verification And Refinement For Year 2020

With $\mathbf{v}_{\infty 20}$ determined, the corresponding semi-minor axis b_{20} is computed from Equation (3) [4, p. 28] and Earth's reduced mass $\mu = 398,600.440 \text{ km}^3/\text{s}^2$ [2].

$$b_{20} = r \sqrt{\frac{2\mu}{r |\mathbf{v}_{\infty 20}|^2} + 1} = 21,172.212 \text{ km} \quad (3)$$

The 2020 departure hyperbola's β is determined from Equation (4) [4, p. 27].

$$\beta_{20} = \arctan \left\{ \frac{b_{20} |\mathbf{v}_{\infty 20}|^2}{\mu} \right\} = 35.504^\circ \quad (4)$$

With $\mathbf{v}_{\infty 20}$ and β_{20} in hand, the 2020 TMI's LPIP is defined. Together with $\mathbf{v}_{\infty 20}$, each geocentric vector corresponding to a point on this LPIP defines a plane of Earth departure on 14.0 July 2020 UT. These planes are assessed to determine the one with $i = 29^\circ$ whose TMI has a northeasterly heading such that $0 < \psi < 90^\circ$. The desired plane has $\psi_{20} = 65.077^\circ$ and Equation (5)'s geocentric J2K position at TMI.

$$\mathbf{r}_{20} = \begin{bmatrix} -3653.895 \\ -5422.855 \\ -1784.607 \end{bmatrix} \text{ km} \quad (5)$$

Equation (6) [4, p. 28] provides a patched conic estimate of geocentric speed following 2020's TMI.

$$v'_{20+} = \sqrt{\frac{2\mu}{r} + |\mathbf{v}_{\infty 20}|^2} = 11.447469 \text{ km/s} \quad (6)$$

It is then possible to construct a patched conic estimate of geocentric J2K velocity following 2020's TMI per Equation (7).

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

$$\mathbf{v}'_{20+} = \begin{bmatrix} +7.909101 \\ -6.855020 \\ +4.636742 \end{bmatrix} \text{ km/s} \quad (7)$$

Equation (7)'s estimate serves as an initial guess in a differential corrections iteration [5] using the trajectory modeling method described in Section 1. Each iteration starts at 14.0 July 2020 UT with Equation (5)'s TMI position, terminates at 30.0 January 2021 UT, and seeks to match heliocentric position of Mars at the terminal epoch with an error less than 1 km. Only 3 iterations are necessary to correct the Equation (7) initial velocity estimate to that given by Equation (8) and achieve the desired Mars position match. The vector difference magnitude between Equations (7) and (8) is only 0.154098 km/s. Because the differential corrections iteration rapidly converges to very nearly the patched conic estimate with which it is seeded, the two independent processes serve to mutually validate all year 2020 Earth departure results.

$$\mathbf{v}_{20+} = \begin{bmatrix} +7.829105 \\ -6.860184 \\ +4.768348 \end{bmatrix} \text{ km/s} \quad (8)$$

Equation (7)'s horizontal velocity is scaled to produce nearly circular apsis heights averaging +400 km ($H_A = +400.7$ km and $H_P = +399.3$ km). The resulting geocentric J2K velocity appears in Equation (9) and is adopted as that of LEO infrastructure at the TMI epoch 14.0 July 2020 UT.

$$\mathbf{v}_{20-} = \begin{bmatrix} +5.301064 \\ -4.594568 \\ +3.107770 \end{bmatrix} \text{ km/s} \quad (9)$$

Magnitude of the vector difference between Equations (8) and (9) is equivalent to $\Delta v_{TMI} = 3.779091$ km/s. Due to the correction in post-TMI velocity applied to Equation (7) in obtaining Equation (8), Δv_{TMI} reflects a small TMI steering angle of 0.771° from the purely prograde thrust direction.

Earth departure geometry for 14.0 July 2020 UT consistent with that described in Section 2 is illustrated in the Figure 6 CSP using Equations (1), (4), (5), and (9) values. This departure case's LPIP is also plotted in Figure 6.

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

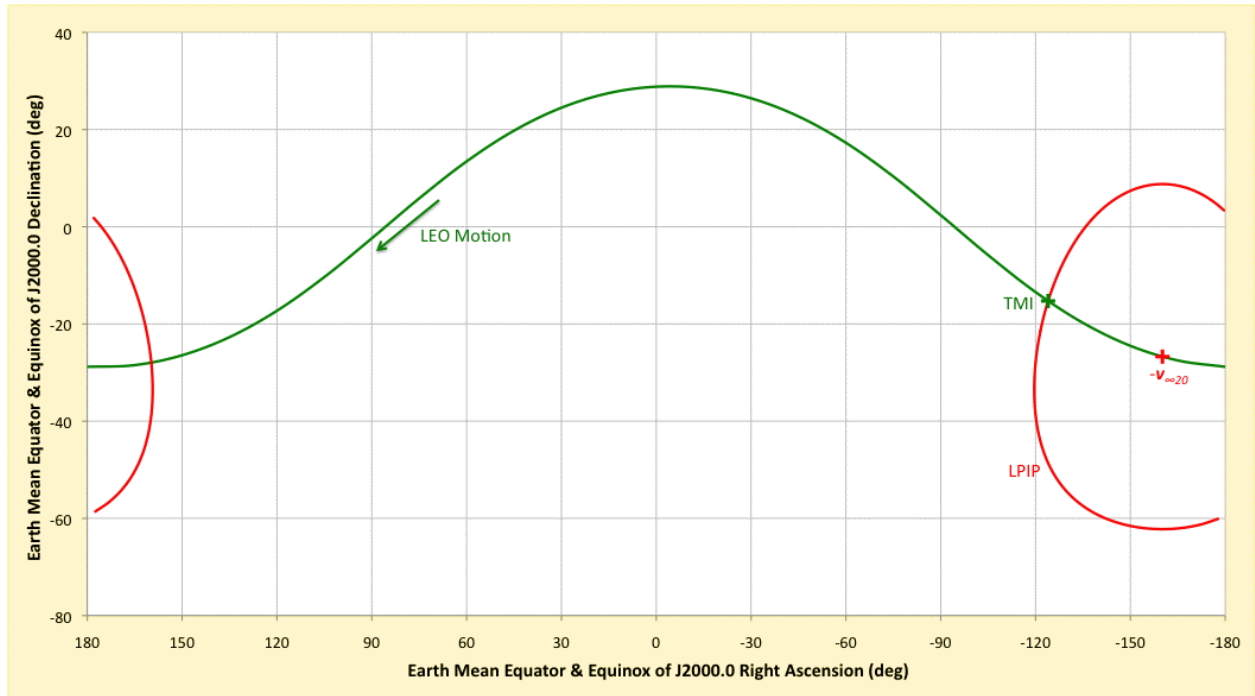


Figure 6. A LEO plane with $i = 29^\circ$ (green line) supporting prograde Earth departure for Mars on 14.0 July 2020 UT is projected onto the geocentric J2K celestial sphere. Note infrastructure motion in the LEO plane passes through $-v_{\infty 20}$ (red +) before reaching TMI (green +) on a northbound heading. The geocentric arc from $-v_{\infty 20}$ to TMI is β_{20} .

5. Year 2020 LEO Coast To Year 2022

The trajectory modeling method described in Section 1 is supplied with LEO initial conditions at the 14.0 July 2020 UT Earth departure epoch obtained from Equations (5) and (9). A simulated LEO coast to the 9.0 September 2022 UT Earth departure epoch is then performed. Terminal geocentric J2K conditions from this coast appear in Equations (10) and (11).

$$\mathbf{r}_{20 \rightarrow 22} = \begin{bmatrix} +3944.059 \\ +4465.877 \\ -3230.562 \end{bmatrix} \text{ km} \quad (10)$$

$$\mathbf{v}_{20 \rightarrow 22} = \begin{bmatrix} -5.455183 \\ +5.344323 \\ +0.728862 \end{bmatrix} \text{ km/s} \quad (11)$$

The coast's terminal conditions show the LEO's apses to be little changed from the initial near-circular orbit at +400 km height ($H_A = +401.1$ km and $H_P = +399.7$ km). This consistency is expected from not simulating LEO atmospheric drag during the coast, and it reasonably approximates infrastructure orbit lifetime maintenance operations. Likewise, $i = 28.977^\circ$ is

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obtained at the coast's terminal epoch, indicating LEO inclination is well preserved during the two-year interval. In contrast, LEO right ascension of the ascending node (RAAN) has been dynamic throughout the coast due almost entirely to torques exerted by J_2 perturbations.

To illustrate LEO planar motion during the coast, osculating geocentric angular momentum normal to the plane is projected onto the geocentric J2K celestial sphere at daily intervals in Figures 7-10. These CSPs are narrow strips in declination, each vertical axis spanning only 0.3° . Magnified vertical scaling reveals minute variations in declination as angular momentum precesses a full 360° in right ascension over cycles about 50 days in duration[‡]. Each of these 4 CSPs in turn plots 4 precession cycles color-coded in a chronological sequence of blue diamonds, orange squares, green triangles, and purple dots. The start of each UT calendar month, together with the two Earth departure epochs, is annotated with the corresponding date in Figures 7-10.

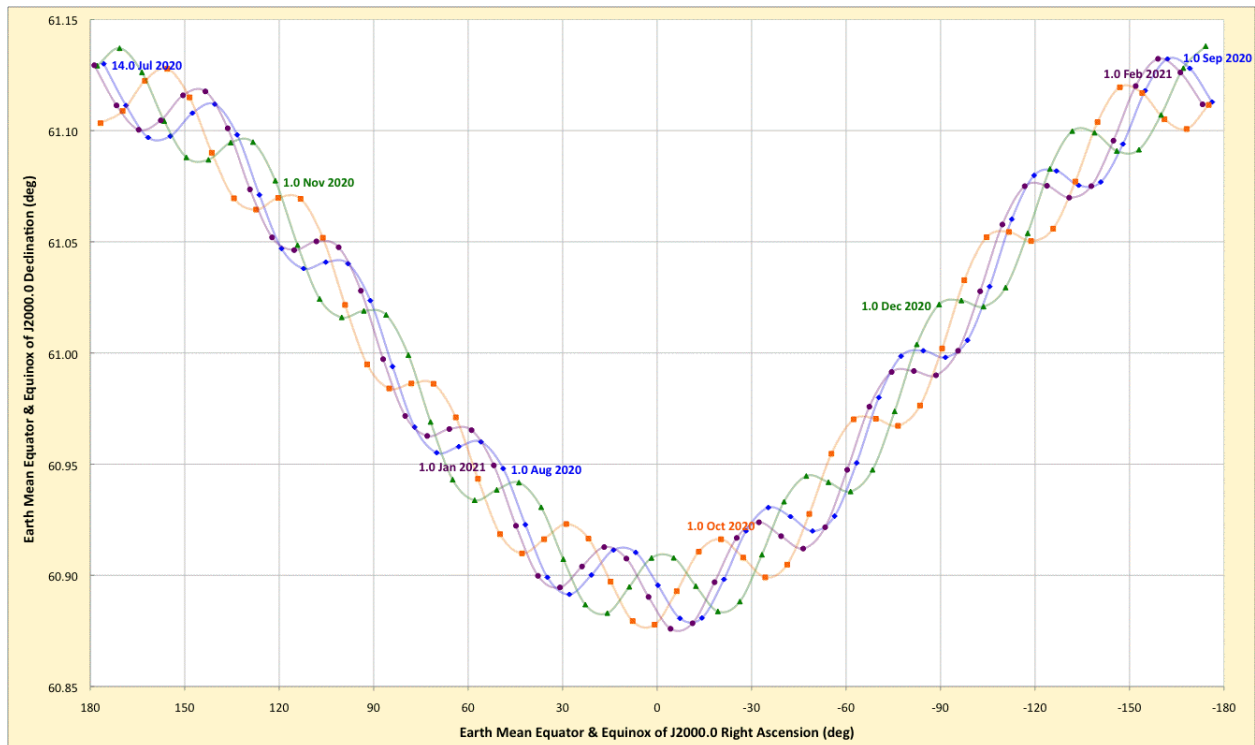


Figure 7. The coasted LEO's osculating geocentric angular momentum vector is projected onto the geocentric J2K celestial sphere at daily intervals from 14.0 July 2020 UT to 2.0 February 2021 UT.

[‡] Note that, in the context of this paper's prograde LEO, the angular momentum vector's declination with respect to Earth's true equator is simply $90^\circ - i$ because i is also defined with respect to Earth's true equator. In contrast, all CSPs have declination plotted with respect to the J2K equator. Therefore, although $i = 29^\circ$ at the 14.0 July 2020 Earth departure epoch, the Figure 7 initial point at that epoch has a J2K declination of $+61.130^\circ$, slightly different from its true declination of $90^\circ - 29^\circ = +61^\circ$.

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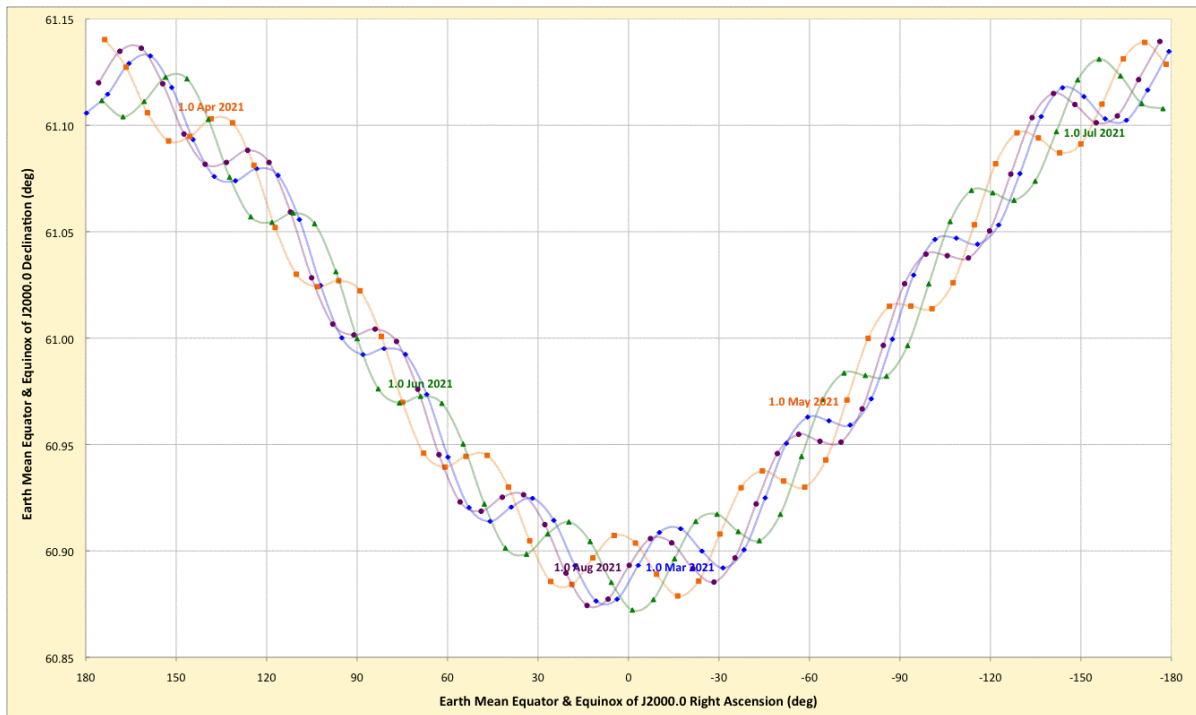


Figure 8. The coasted LEO's osculating geocentric angular momentum vector is projected onto the geocentric J2K celestial sphere at daily intervals from 3.0 February 2021 UT to 26.0 August 2021 UT.

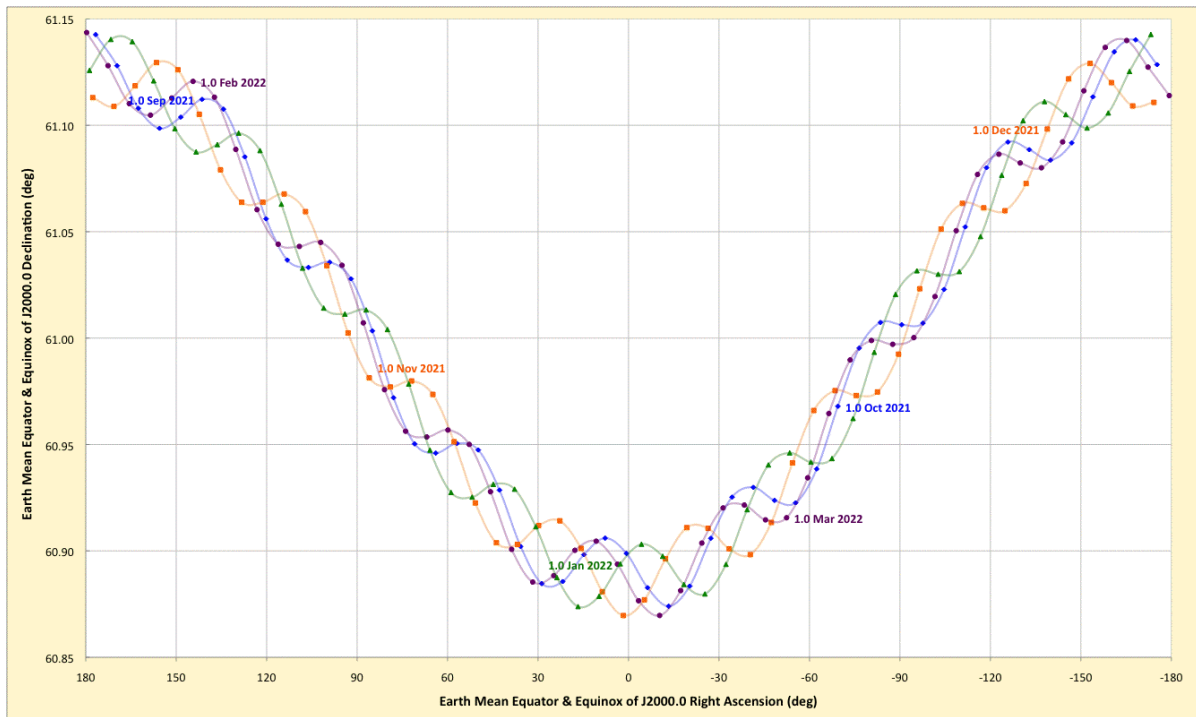


Figure 9. The coasted LEO's osculating geocentric angular momentum vector is projected onto the geocentric J2K celestial sphere at daily intervals from 27.0 August 2021 UT to 19.0 March 2022 UT.

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

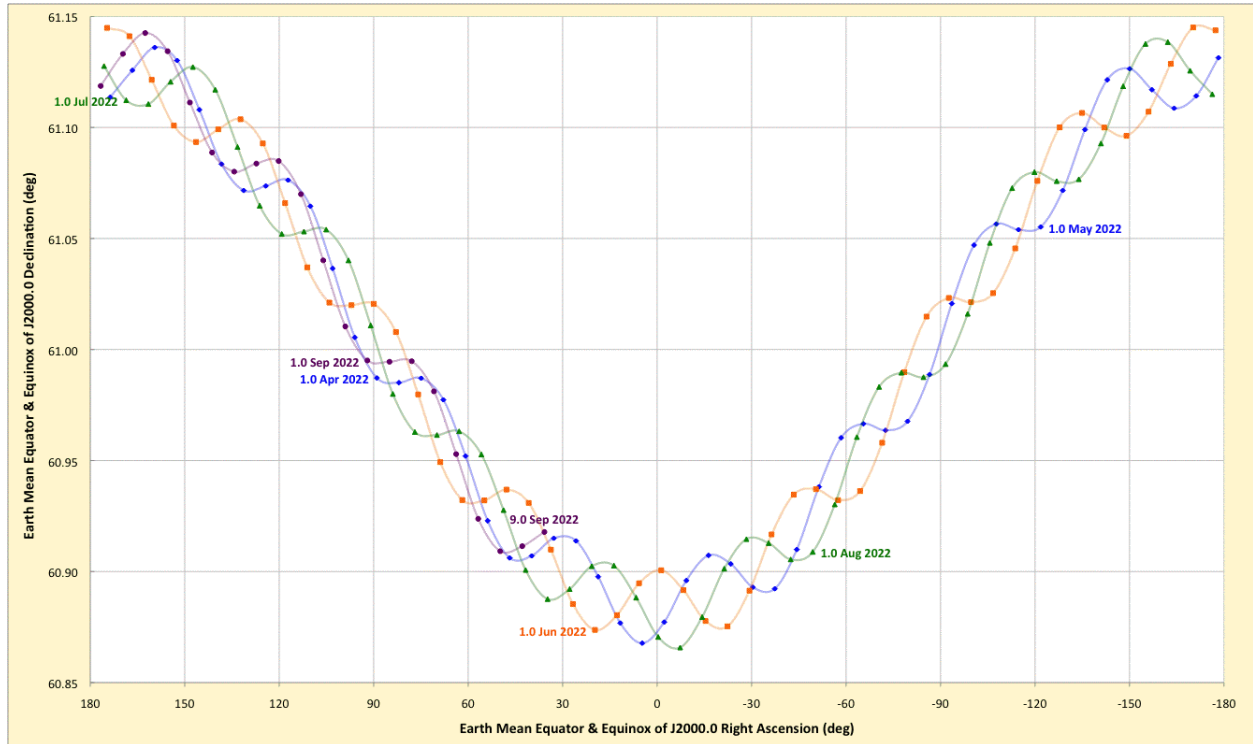


Figure 10. The coasted LEO's osculating geocentric angular momentum vector is projected onto the geocentric J2K celestial sphere at daily intervals from 20.0 March 2022 UT to 9.0 September 2022 UT.

Angular momentum variations in declination evident in Figures 7-10 arise from two distinct sources. The first of these is due to the J_2 perturbation's force component acting normal to the coasted LEO plane [6, p. 567]. But this torque averages zero over the interval between successive Earth true equator crossings, about 46.2 min in the coasted LEO. Nevertheless, polling the coasted LEO at differing points in its half-orbit J_2 cycle influences daily angular momentum computations reflected in Figures 7-10. Variations depending on sampling the J_2 cycle amount to 0.035° (peak-to-valley) in CSP declination and are easily resolved by the magnified vertical scale common to Figures 7-10. At $31.169 J_2$ cycles per day, 6 days are required to sample all portions of a J_2 cycle at daily intervals. Thus, the higher frequency declination variations seen in Figures 7-10 are partially attributable to an artifact: relatively infrequent sampling of a periodic J_2 cycle having no net effect over intervals more than 0.8 hrs.

The sinusoidal variation in declination whose amplitude spans the vertical axis in Figures 7-10 is due to another artifact. This variation would disappear if coasted LEO angular momentum were plotted on a celestial sphere whose declination is with respect to Earth's true equator. On such a CSP, J_2 -induced precession in the angular momentum vector would be about an axis parallel to the CSP declination axis. But J2K declination is inclined to true declination during the LEO coast by about 0.12° , giving rise to a 0.24° peak-to-valley declination variation during each 50-day precession cycle in Figures 7-10.

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Moon and Sun gravitational forces also contain components normal to the coasted LEO plane. But a LEO is small in scale and short in period compared to lunar/solar distances and their geocentric motions. Consequently, these perturbations only impart miniscule changes on the order of 0.01° to the coasted LEO plane's terminal orientation when compared with a coast having only J_2 perturbations. Even near the LEO coast's terminal conditions, planar deviations in a coast without Moon/Sun perturbations would barely be resolved in Figure 10 and only by the highly magnified declination scale.

6. Earth Departure Velocity Verification And Refinement For Year 2022

With $\mathbf{v}_{\infty 22}$ determined, the corresponding semi-minor axis b_{22} is computed from Equation (12) [4, p. 28] and Earth's reduced mass $\mu = 398,600.440 \text{ km}^3/\text{s}^2$ [2].

$$b_{22} = r \sqrt{\frac{2\mu}{r|\mathbf{v}_{\infty 22}|^2} + 1} = 18,355.837 \text{ km} \quad (12)$$

The 2022 departure hyperbola's β is determined from Equation (13) [4, p. 27].

$$\beta_{22} = a \tan \left\{ \frac{b_{22} |\mathbf{v}_{\infty 22}|^2}{\mu} \right\} = 40.535^\circ \quad (13)$$

With $\mathbf{v}_{\infty 22}$ and β_{22} in hand, the 2022 TMI's LPIP is defined. Together with $\mathbf{v}_{\infty 22}$, each geocentric vector corresponding to a point on this LPIP defines a plane of Earth departure on 9.0 September 2022 UT. These planes are assessed to determine the one with $i = 45^\circ$ whose TMI has a northeasterly heading such that $0 < \psi < 90^\circ$. The desired plane has $\psi_{22} = 53.317^\circ$ and Equation (14)'s geocentric J2K position at TMI.

$$\mathbf{r}_{22} = \begin{bmatrix} +1628.976 \\ -5748.410 \\ -3200.836 \end{bmatrix} \text{ km} \quad (14)$$

Equation (15) [4, p. 28] provides a patched conic estimate of geocentric speed following 2022's TMI.

$$v'_{22+} = \sqrt{\frac{2\mu}{r} + |\mathbf{v}_{\infty 22}|^2} = 11.669741 \text{ km/s} \quad (15)$$

It is then possible to construct a patched conic estimate of geocentric J2K velocity following 2022's TMI per Equation (16).

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$$\mathbf{v}'_{22+} = \begin{bmatrix} +9.914678 \\ -0.601150 \\ +6.125409 \end{bmatrix} \text{ km/s} \quad (16)$$

Equation (16)'s estimate serves as an initial guess in a differential corrections iteration [5] using the trajectory modeling method described in Section 1. Each iteration starts at 9.0 September 2022 UT with Equation (14)'s TMI position, terminates at 28.0 March 2023 UT, and seeks to match heliocentric position of Mars at the terminal epoch with an error less than 1 km. Only 3 iterations are necessary to correct the Equation (16) initial velocity estimate to that given by Equation (17) and achieve the desired Mars position match. The vector difference magnitude between Equations (16) and (17) is only 0.088261 km/s. Because the differential corrections iteration rapidly converges to very nearly the patched conic estimate with which it is seeded, the two independent processes serve to mutually validate all year 2022 Earth departure results.

$$\mathbf{v}_{22+} = \begin{bmatrix} +9.870252 \\ -0.640011 \\ +6.191030 \end{bmatrix} \text{ km/s} \quad (17)$$

Equation (16)'s horizontal velocity is scaled to produce nearly circular apsis heights averaging +400 km ($H_A = +401.6$ km and $H_P = +398.4$ km). The resulting geocentric J2K velocity appears in Equation (18) and is adopted as that of LEO infrastructure at the TMI epoch 9.0 September 2022 UT.

$$\mathbf{v}_{22-} = \begin{bmatrix} +6.516679 \\ -0.395121 \\ +4.026084 \end{bmatrix} \text{ km/s} \quad (18)$$

Magnitude of the vector difference between Equations (17) and (18) is equivalent to $\Delta v_{TMI} = 3.999177$ km/s. Due to the correction in post-TMI velocity applied to Equation (16) in obtaining Equation (17), Δv_{TMI} reflects a small TMI steering angle of 0.433° from the purely prograde thrust direction.

Earth departure geometry for 9.0 September 2022 UT consistent with that described in Section 2 is illustrated in the Figure 11 CSP using Equations (2), (13), (14), and (18) values. This departure case's LPIP is also plotted in Figure 11, together with the LEO plane coasted from 14.0 July 2020 UT to 9.0 September 2022 UT as defined by terminal conditions from Equations (10) and (11).

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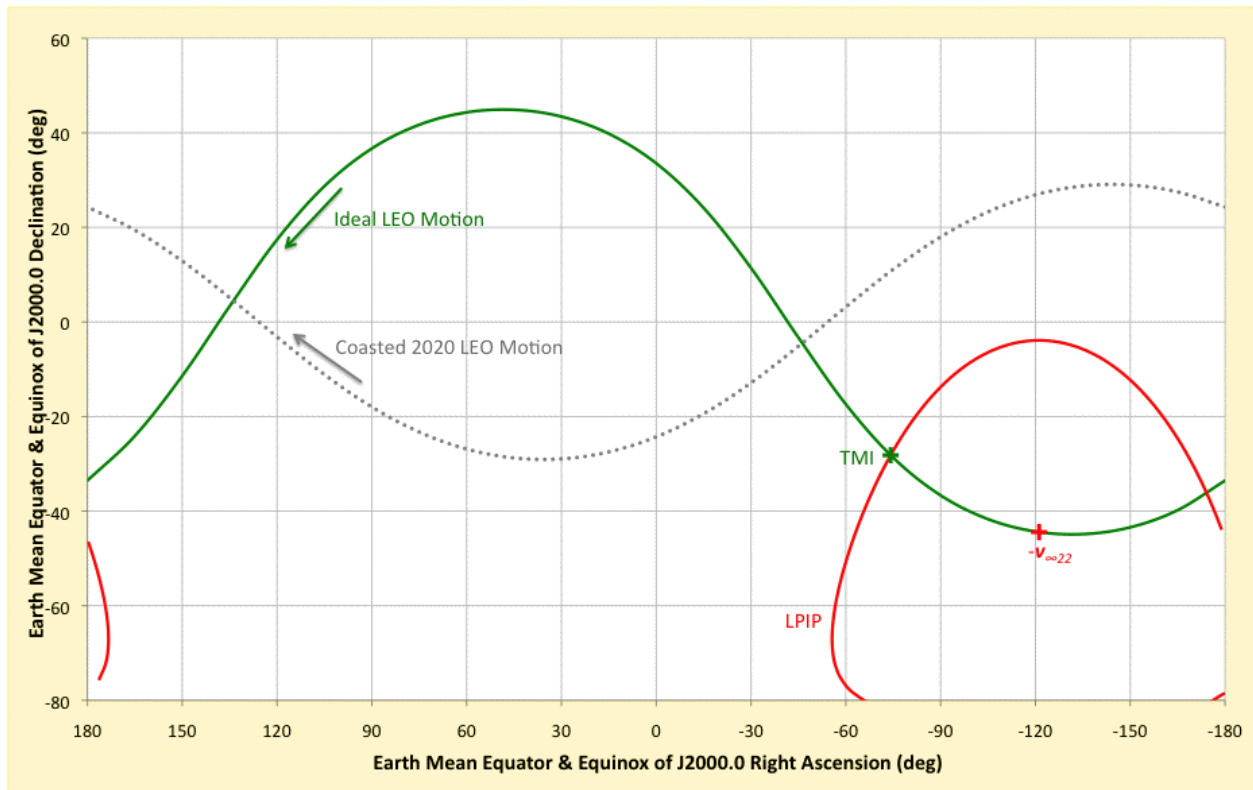


Figure 11. An ideal LEO plane with $i = 45^\circ$ (green line) supporting prograde Earth departure for Mars on 9.0 September 2022 UT is projected onto the geocentric J2K celestial sphere. Note infrastructure motion in the LEO plane passes through $-v_{\infty 22}$ (red +) before reaching TMI (green +) on a northbound heading. The geocentric arc from $-v_{\infty 22}$ to TMI is β_{22} , and the dotted gray line is the LEO plane coasted in Section 5 from an ideal Earth departure for Mars on 14.0 July 2020 UT.

The wedge angle between ideal and coasted LEO planes plotted in Figure 11 is 73.500° . This angle can be zeroed with a single planar correction impulse $\Delta v_{PC} = 9.180$ km/s at either of the two intersection points, or nodes, between the two planes evident in Figure 11. Such a correction exceeds Δv_{TMI} and even surpasses geocentric speed in either LEO per Equations (11) and (18). More sophisticated strategies, with which orbiting infrastructure supporting the 2020 Earth departure can also support the 2022 Earth departure, are suggested in Section 7.

7. Reuse Strategies Covering Multiple Earth Departure Seasons For Mars

Although the reusable infrastructure assembles and services massive payloads prior to each payload's departure for Mars, this infrastructure may be highly maneuverable when free of payload obligations. The following subsections suggest strategies to maneuver infrastructure in support of multiple servicing campaigns. These strategies are presented in the context of achieving ideal Earth departure geometry for Mars during years 2020 and 2022 as developed in Sections 3, 4, and 6.

Trajectory Challenges Faced By Reusable Infrastructure In Earth Orbit Supporting Multiple Departures For Mars

7.1 Alter LEO H To Obtain A Desired RAAN

As illustrated in Figure 11, the ideal J2K RAAN to depart Earth for Mars at $i = 45^\circ$ on 9.0 September 2022 UT is -41.677° , while J2K RAAN on that date coasted from an ideal departure at $i = 29^\circ$ on 14.0 July 2020 UT is $+125.706^\circ$. Subtracting the coasted RAAN from the ideal 2022 RAAN produces a desired J2K RAAN shift $\Delta\Omega = -167.383^\circ$ (negative $\Delta\Omega$ signifies a westward RAAN shift). If this shift could be imparted during the 2020-to-2022 coast, wedge angle between the two planes would be reduced to the difference in their J2K inclinations, or $44.915^\circ - 29.079^\circ = 15.836^\circ$. The smaller wedge in turn reduces Δv_{PC} to 2.114 km/s.

In a prograde orbit, planar precession due to J_2 results in a westward RAAN drift over time. The rate of RAAN drift increases in magnitude with decreasing orbit height and decreasing inclination [6, pp. 591-592]. Consequently, when the 14.0 July 2020 UT state vector from Equations (5) and (9) is scaled to produce nearly circular apsis heights averaging $+342.5$ km ($H_A = +343.2$ km and $H_P = +341.8$ km) while retaining $i = 29^\circ$, a coast to 9.0 September 2022 UT achieves $\Delta\Omega = +0.009^\circ$. Initial and terminal geocentric J2K states for this coast appear in Equations (19) through (22).

$$\mathbf{r}_{\Omega 20} = \begin{bmatrix} -3622.886 \\ -5376.834 \\ -1769.462 \end{bmatrix} \text{ km} \quad (19)$$

$$\mathbf{v}_{\Omega 20} = \begin{bmatrix} +5.323751 \\ -4.614231 \\ +3.121070 \end{bmatrix} \text{ km/s} \quad (20)$$

$$\mathbf{r}_{\Omega 20 \rightarrow 22} = \begin{bmatrix} +1453.064 \\ -6236.516 \\ -2038.688 \end{bmatrix} \text{ km} \quad (21)$$

$$\mathbf{v}_{\Omega 20 \rightarrow 22} = \begin{bmatrix} +7.104015 \\ +0.705419 \\ +2.900428 \end{bmatrix} \text{ km/s} \quad (22)$$

The coasted orbit plane in Figure 11 is replaced by that defined with Equations (21) and (22) in Figure 12. Note that the Δv_{PC} impulse required to increase i to 45° must occur at the coasted plane's nodes with the ideal Earth departure plane (which are also the coasted LEO's nodes on the J2K equator in this case) and therefore cannot be combined with Δv_{TMI} .

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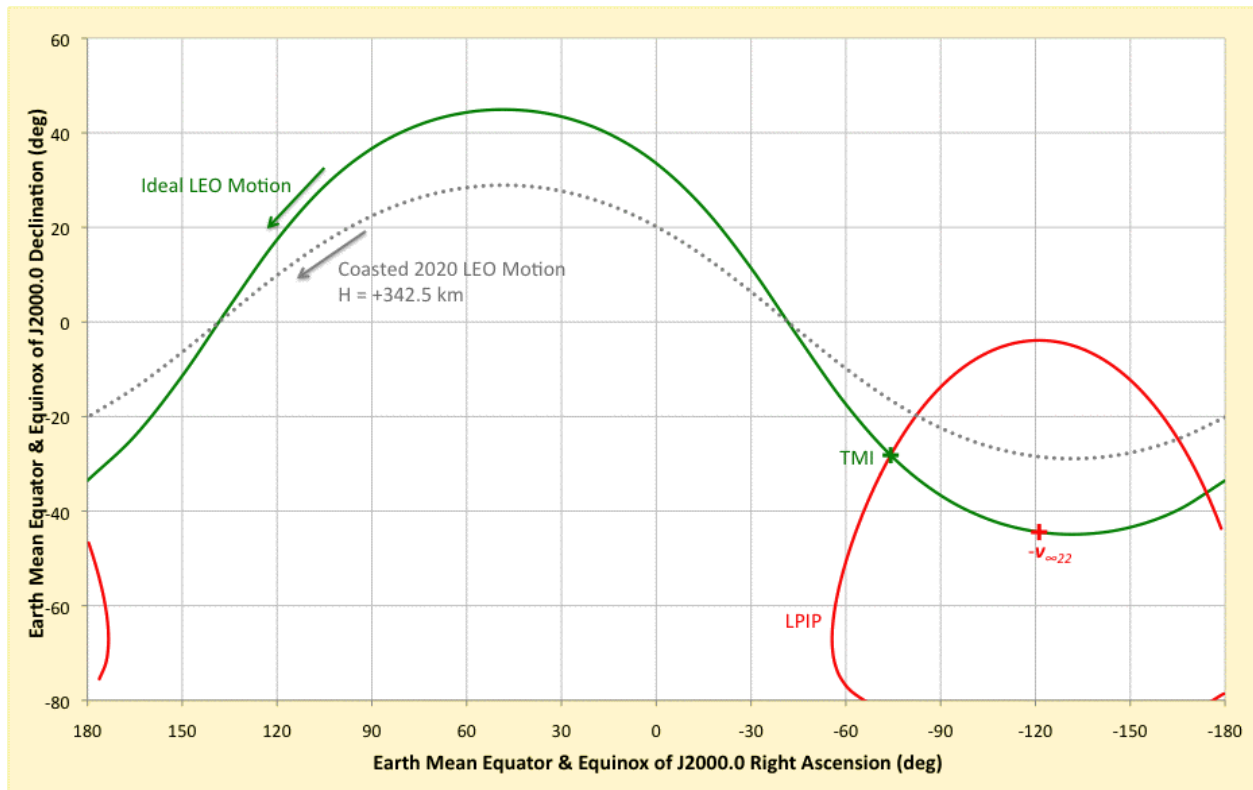


Figure 12. Ideal Earth departure geometry for Mars on 9.0 September 2022 UT is reproduced from Figure 11. Height associated with the LEO plane coasted from 14.0 July 2020 UT has been lowered from +400 km in Figure 11 to +342.5 km (dotted gray line) in order to match J2K RAAN with that of the ideal LEO.

In addition to propellant required to lower the coasted orbit to $H = +342.5$ km (and possibly return it to $H = +400$ km), this strategy requires more propulsion to counteract orbit decay due to atmospheric drag than would a LEO at greater H . Massive payload servicing at $H < +400$ km may be inadvisable. Only during early phases of its assembly was the International Space Station (ISS) orbit permitted to decay down to H near +320 km (reference http://www.nasa.gov/mission_pages/shuttle/shuttlemissions/archives/sts-101.html). Together with its highly maneuverable mass, prolonged reduced solar activity (and the reduced atmospheric density it imparts) facilitated flying the nascent ISS in such low orbits.

Assuming freedom from payload obligations to coast at H appreciably different from +400 km over more than two years to achieve a RAAN match could be highly optimistic. Massive payload servicing near +400 km (or some other standard H) may dictate the coast performed in this subsection instead be conducted at an even lower H over a more curtailed interval between servicing obligations at the higher standard H .

There is also a reverse strategy to that developed by this subsection in which an easterly J2K RAAN shift $\Delta\Omega = 360^\circ - 167.383^\circ = +192.617^\circ$ is conducted with $H > +400$ km. This strategy enjoys reduced atmospheric drag with respect to lower orbit heights, but it also suffers increased radiation flux from particles trapped in Earth's magnetosphere. Because this flux is harmful to

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human health and spacecraft systems, ISS is rarely operated at $H > +430$ km. Such a constraint would not leave much of an orbit height envelope in which to shift RAAN eastward with respect to a coast at $H = +400$ km.

7.2 Utilize An Elliptical Earth Parking Orbit (EEPO)

An EEPO offers opportunities to take advantage of two fundamental astrodynamics techniques. At apogee, geocentric speed is at a minimum, and a required plane change can be achieved with minimal Δv_{PC} . At perigee, geocentric speed is at a maximum, and Δv_{TMI} can be dramatically reduced from the corresponding impulse in LEO [7]. Fully realizing this "Oberth effect" presumes the TMI geometry described in Section 2, together with perigee located at TMI.

As a context for applying these techniques by example, consider an EEPO with $i = 29^\circ$ and $H_p = +400$ km at 14.0 July 2020 UT. Position for this EEPO example is \mathbf{r}_{20} from Equation (5), and geocentric J2K velocity is \mathbf{v}_{20} from Equation (9) scaled to produce a geographic longitude of ascending node on Earth's true equator (LAN) repetition every two days. This condition also causes rendezvous phase angles to repeat on that cycle, standardizing planning and flight procedures associated with massive payload logistics to the reusable infrastructure. The repeated LAN is near 28° W with ascending node passages at 00:15:19 UT on 12 July 2020 and 00:06:30 UT on 14 July 2020 bracketing the TMI epoch. Figure 13 illustrates motion in the EEPO between these two node passages. Scaled \mathbf{v}_{20} in the EEPO at perigee on 14.0 July 2020 UT is given by Equation (23), producing $H_A = +121,639.3$ km.

$$\mathbf{v}_{20-EEPO} = \begin{bmatrix} +7.302022 \\ -6.328849 \\ +4.280839 \end{bmatrix} \text{ km/s} \quad (23)$$

Raising apogee about a third of the way to the Moon's orbit is a launch vehicle performance challenge compared to LEO, and it applies to logistics throughout the entire massive payload assembly and servicing campaign. But this challenge also permits much of the kinetic energy required for TMI to be generated soon after each massive payload element is launched using efficient cryogenic propellant. To perform TMI with cryogenic propellant from a circular LEO would require low temperature storage in that thermally challenging environment, likely over a time interval measured in months to a year or more.

Consider a maximum plane change of 90° performed during EEPO apogee passage on 13 July 2020 at 00:04:30 UT. Geocentric speed at this point is 0.565 km/s, and the $90^\circ \Delta v_{PC} = 0.798$ km/s. This is a dramatic reduction from a similar impulse in an $H = +400$ km circular orbit, but it may not be the maximum Δv_{PC} required to rotate the EEPO plane 90° . In general, the line of nodes between the EEPO and the desired orbit plane will not lie along the EEPO line of apsides. Therefore, a less optimal geometry could require shifting the plane change impulse well away from apogee to locations where higher geocentric speeds prevail. The node closer to apogee is the plane change's preferred location in order to minimize geocentric speed and Δv_{PC} .

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Geocentric speed at the EEPO perigee is 2.896 km/s greater than that in a circular $H = +400$ km orbit, reducing the 14.0 July 2020 UT Δv_{TMI} by a similar amount to 0.893 km/s. This impulse again includes a small TMI steering angle of 0.771° from the purely prograde thrust direction.

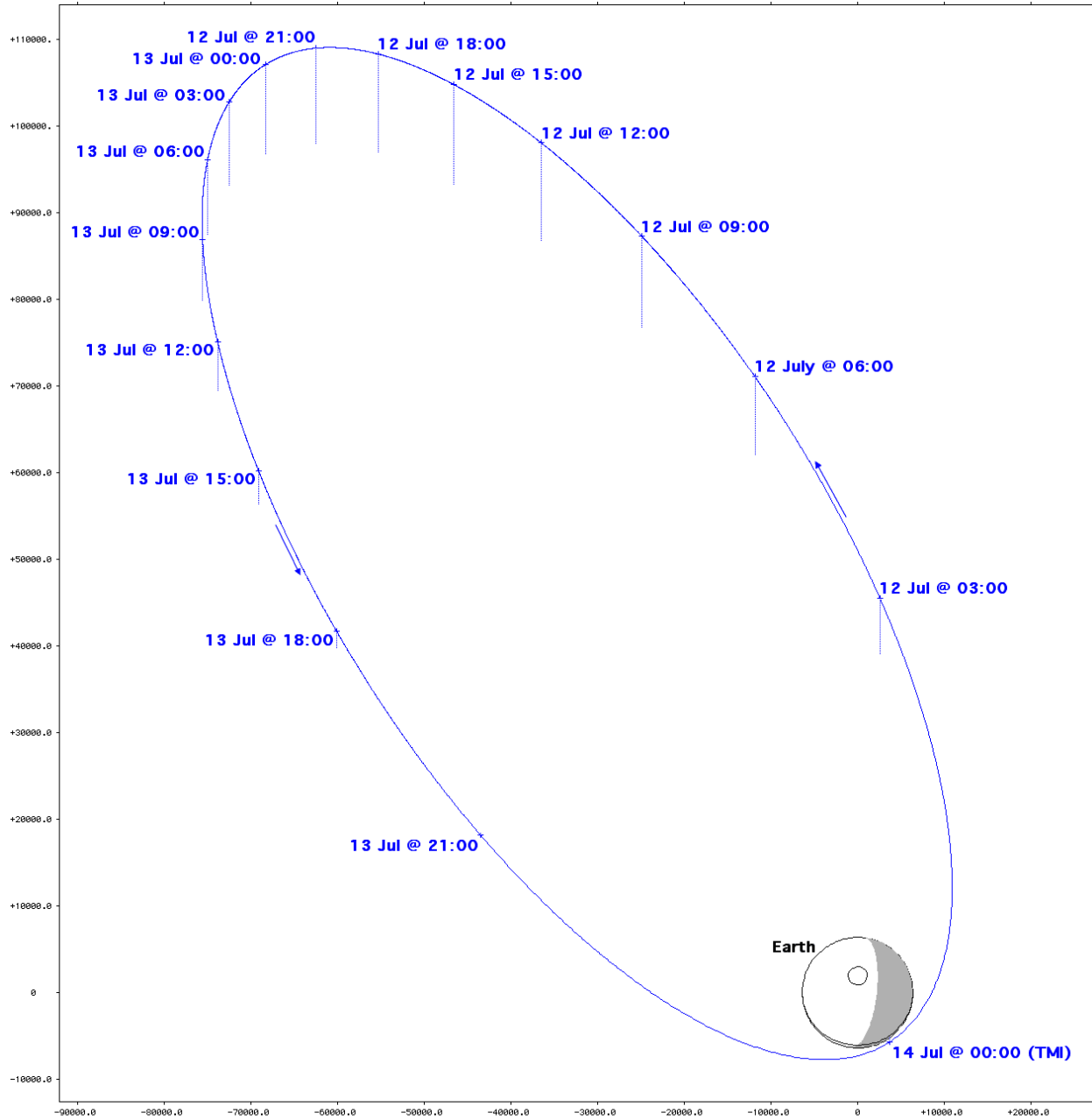


Figure 13. Geocentric inertial motion is plotted in an EEPO with $i = 29^\circ$ and $H_A \times H_P = +121,639.3$ km \times +400 km as viewed nearly normal to the plane of motion. The plot spans successive Earth true equator ascending node passages bracketing the 14.0 July 2020 UT perigee at which TMI would be performed. Time tick annotations are UT, dotted lines are projections onto Earth's true equatorial plane, and the shaded area is Earth's nightside.

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The Figure 13 EEPO passes through regions with some of the highest trapped particle radiation flux in Earth's magnetosphere (reference the Trapped Radiation section at <http://srag-nt.jsc.nasa.gov/SpaceRadiation/What/What.cfm>). If the reusable infrastructure or massive payload destined for Mars is radiation-sensitive, EEPO perigee can be raised to evade regions with unacceptable particle fluxes. In this case, apogee can also be raised to maintain desirable LAN repetition properties of the Figure 13 EEPO.

If perigee must be raised appreciably from $H = +400$ km, taking full advantage of the Oberth effect will likely entail lowering it back just before TMI. In the context of Earth departure for Mars, it actually requires less propellant to lower EEPO perigee and perform TMI than it does to perform TMI directly from a higher perigee. For a typical EEPO with 2-day period, the break-even point between these two competitive strategies is near $|v_\infty| = 2$ km/s. At $|v_\infty| > 2$ km/s, lowering perigee as much as possible for TMI is propellant-efficient. Per $|v_\infty|$ data in Figures 2 and 4, the "lowest possible H at TMI" strategy definitely applies to Earth departures for Mars in years 2020 and 2022. A relatively small perigee-lowering impulse, performed about a day before TMI to maximize the Oberth effect, can in practice also serve as a useful test of the TMI propulsion system before committing a massive and presumably costly payload (possibly carrying a crew) to Mars transit.

In contrast to an $H = +400$ km circular LEO, a 2-day EEPO experiences appreciable Moon and Sun gravity perturbations. Left uncontrolled, these can significantly alter orbit elements, including inclination and apsis heights, between successive Mars departure seasons. For example, coasting the Figure 13 EEPO to 9.0 September 2022 UT produces an orbit with $i = 25.334^\circ$ and $H_A \times H_P = +121,737.0$ km \times -664.706 km. This decayed orbit outcome, even in the absence of atmospheric drag, is another argument in favor of long-term EEPO maintenance at H_P considerably above $+400$ km. When drag is considered, higher perigee in an EEPO virtually eliminates its energy-robbing effects until shortly before TMI.

7.3 Loiter In A Selenocentric Distant Retrograde Orbit (DRO)

This strategy requires a trans-lunar injection (TLI) impulse whose magnitude can be approximated by requiring $|v_\infty| = 0$ post-TLI. In this discussion, the initial and final orbits are assumed to be EEPOs supporting purely prograde TMI impulses during two different Earth departure seasons. Application of this strategy to TMIs from LEO would entail considerably larger impulses than its application to TMIs from EEPO and is therefore inadvisable except to address unplanned contingencies.

Following massive payload servicing obligations in EEPO, the reusable infrastructure will loiter there for at least a few months awaiting sufficient alignment of its line of apsides with the Sun/Earth line. Geometry relevant to this alignment is illustrated in Figure 13, with the EEPO perigee initially located at a local solar time of approximately 8 PM. As Earth revolves about the Sun in the months following Figure 13's TMI, EEPO perigee will approach local solar noon. At this point, it will be possible for a near-perigee TLI impulse about 0.28 km/s in magnitude to send the infrastructure on a trajectory closely approaching the second Sun/Earth libration point (SEL2), about 1.5 million km (or 1%) outside Earth's heliocentric orbit. Transit past SEL2 is designed to satisfy two objectives. First, it incurs solar gravity perturbations causing

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infrastructure geocentric total energy to more closely match the Moon's. Second, a coasted return to the Moon's vicinity is targeted to occur near lunar last-quarter phase such that selenocentric speed is minimal.

Loitering an additional six months in EEPO would place perigee sufficiently close to local solar midnight, and a near-perigee TLI impulse about 0.28 km/s in magnitude could send the infrastructure on a trajectory closely approaching the first Sun/Earth libration point (SEL1), about 1.4 million km inside Earth's heliocentric orbit. This TLI targets return to the Moon's vicinity near its first-quarter phase. A similar technique was applied to achieve lunar orbit for the twin Gravity Recovery And Interior Laboratory (GRAIL) spacecraft and is illustrated in Figure 14 from downloaded as-flown trajectory data [2].

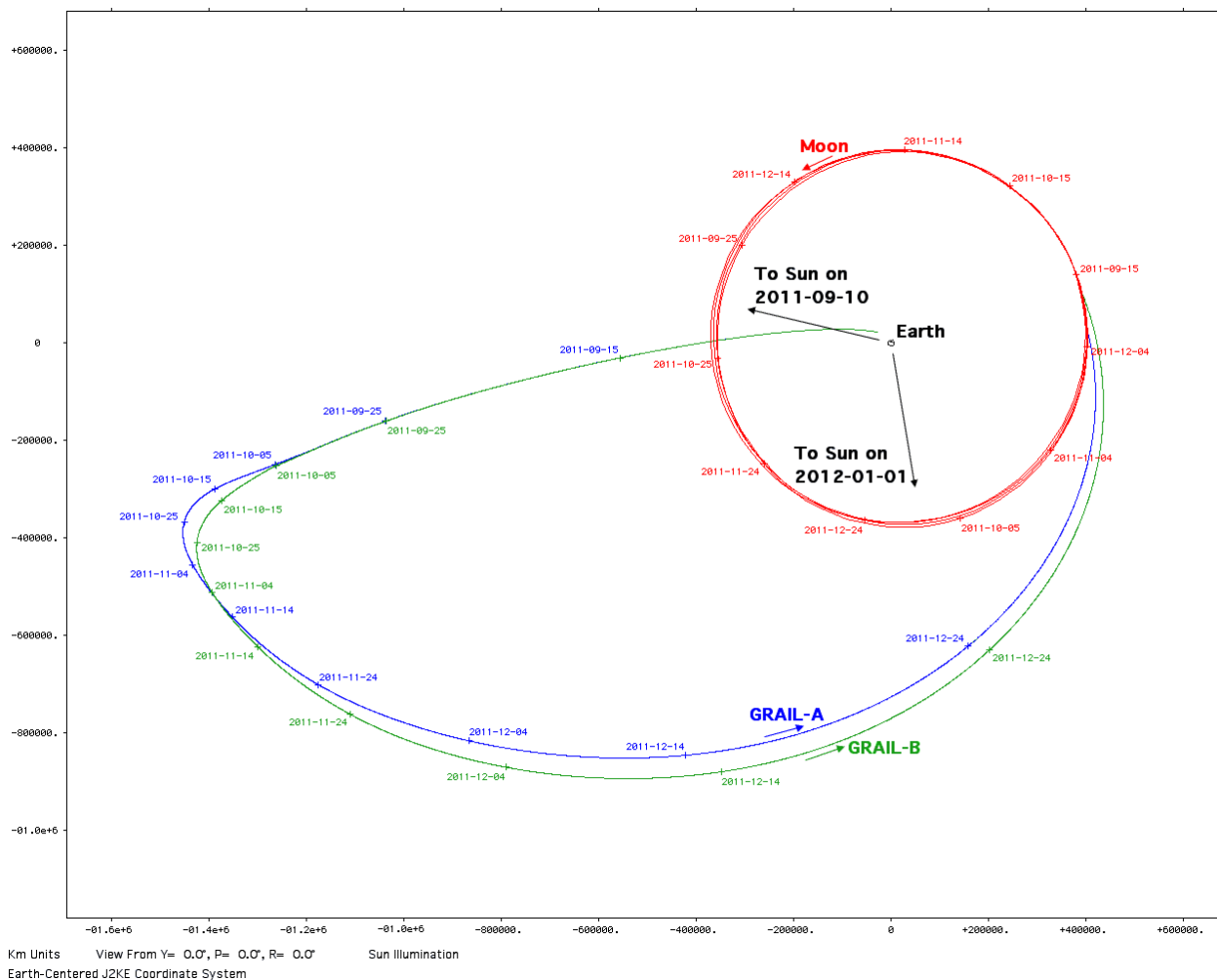


Figure 14. Geocentric as-flown GRAIL trajectories (blue and green) are plotted in the inertial ecliptic plane. Time tick labels are in year-month-day format. Note how solar perturbations to these trajectories cause them to intercept the Moon's orbit (red) tangentially so as to minimize selenocentric speed and achieve lunar orbit with minimal propulsion.

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Per Figure 14's GRAIL example, arrival at the Moon's vicinity can be expected about 4 months after TLI. Research supporting near-Earth asteroid redirection into a stable selenocentric DRO indicates DRO insertion from a slow lunar approach can be achieved with an impulse approximately 0.1 km/s in magnitude [8].

Depending on future servicing obligations, the reusable infrastructure may safely loiter in the DRO for decades, straying no more than about 70,000 km from the Moon. If those obligations are relatively immediate, however, the DRO loiter interval may be shortened to less than a month. In general, DRO departure must occur at the proper time of the lunar month to ensure a subsequent EEPO is established with its perigee located on the LPIP and its plane containing v_{∞} at TMI in accord with Section 2 geometric constraints. Conic transfer from the Moon's orbit to $H_p = +400$ km requires a trans-Earth injection (TEI) impulse about 0.83 km/s in magnitude[§], and lowering apogee of the resulting orbit to 120,000 km, thus establishing a 2-day EEPO, requires an impulse about 0.19 km/s in magnitude. Table 1 summarizes an approximate and expedited timeline example for the selenocentric DRO loiter strategy.

Table 1. Phase Elapsed Time (PET) is measured in months since a massive payload performs TMI after assembly and servicing by reusable infrastructure in an initial EEPO. The infrastructure then undergoes a trajectory recycling process to achieve the correct EEPO for a subsequent TMI at 26 months PET. This process entails loitering in the initial EEPO and in a selenocentric DRO. After recycling to the second EEPO, the infrastructure has 16 months in which to assemble and service a second massive payload before it departs Earth for Mars.

| PET (months) | Event |
|--------------|--|
| 0 | First Earth departure season TMI. Begin loiter in supporting EEPO. |
| 4 | Depart EEPO for SEL2 flyby with 0.28 km/s TLI impulse. |
| 8 | Return to Moon and achieve 70,000 km radius DRO with 0.1 km/s impulse. |
| 9 | Perform 0.57 km/s TEI impulse and establish 2-day EEPO supporting second Earth departure season with 0.19 km/s impulse several days later. |
| 10 | Begin servicing operations for second Earth departure season TMI. |
| 26 | Second departure season TMI. |

Other researchers have proposed similar trajectory recycling strategies. For example, Farquhar advocates loitering at SEL2 to reuse Earth/Mars transport infrastructure [9, Chapter 15].

[§] This TEI impulse magnitude estimate assumes no lunar gravity must be overcome to achieve lunar escape and is consistent with a circular selenocentric DRO of radius 70,000 km near the Moon's gravitational sphere of influence. A TEI impulse of 0.83 km/s is also thought to be near a mean value because zero selenocentric speed is assumed pre-TEI. But a 70,000 km DRO has selenocentric speed near 0.26 km/s. Therefore, a TEI targeted to occur near the Earth/Moon line 70,000 km beyond the Moon's geocentric orbit could have a reduced impulse of $0.83 - 0.26 = 0.57$ km/s.

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8. Conclusions

A scenario has been documented in which reusable infrastructure in Earth orbit assembles and services a massive payload departing for Mars in 2020. The infrastructure remains in space to repeat this task in 2022. Geometric constraints governing the infrastructure's orbit for the two Earth departure seasons have been presented and shown to require dramatically different planar orientations. These conflicting trajectory constraints pose formidable challenges to infrastructure reuse.

If infrastructure is based in circular LEO, a large wedge angle develops with respect to the Earth departure orbit plane required in 2022 when the Earth departure orbit plane in 2020 is coasted to 2022. Some of this wedge angle can be removed by deviating from the reuse scenario's specified LEO height to target the required 2022 departure RAAN. Even if this technique is practical, a dedicated inclination plane change impulse about 2 km/s in magnitude is necessary to zero the wedge angle. Placing infrastructure in LEO to support the reuse scenario is therefore not recommended.

As an alternative to LEO, reusable infrastructure based in an EEPO with period near 2 days is proposed. This orbit permits much of the propulsive energy required to depart Earth for Mars to be expended only hours after a massive payload element is launched to achieve infrastructure rendezvous, thereby vastly reducing departure cryogenic propellant storage requirements. The EEPO plane is easily rotated if plane change impulses can be placed near apogee. In lieu of that circumstance, the EEPO provides access to Moon and Sun perturbations capable of achieving the desired 2022 Earth departure EEPO in approximately 10 months using impulses totaling about 1 km/s. Consequently, the infrastructure reuse scenario during years 2020 into 2022 favors Earth departure for Mars from a 2-day EEPO.

To avoid excessive radiation exposure from particles trapped in Earth's magnetic field, minimize atmospheric drag orbit energy losses, and evade orbit decay, EEPO perigee must be sufficiently high. It may then be necessary to lower the massive payload's perigee to a minimal safe height immediately prior to TMI. Only at the minimum practical perigee will the payload be taking maximum advantage of the Oberth effect's propulsive efficiency at TMI.

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