

Asteroid Destinations Accessible for Human Exploration: A Preliminary Survey in Mid-2009

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The flexible path is one of several space exploration strategy options developed by the Review of U.S. Human Space Flight Plans Committee in 2009. Among proposed flexible path destinations are near-Earth objects, those asteroids and comets having perihelions of less than 1.3 astronomical units and periods of less than 200 years. Heliocentric orbit element criteria have been developed with the objective of rapidly identifying the near-Earth object subset potentially accessible for human exploration capabilities. When these criteria were applied to the Jet Propulsion Laboratory's small-body database in June 2009, the accessible subset was found to contain 36 near-Earth objects. Opportunities to visit these destinations have been obtained and assessed over the interval from 2020 through 2050. With the number of cataloged near-Earth objects expected to grow by more than an order of magnitude in the next 20 years, the number and frequency of human near-Earth object exploration opportunities will likewise increase.

Foreword

This paper is a facsimile of another having the same title and published in the *AIAA Journal of Spacecraft and Rockets* (Vol. 47, No. 6, November-December 2010, pp. 994-1002) with two exceptions. First, any post-publication errata perceived by the authors are corrected. Second, color figures and tables present in initial drafts of this paper have been restored, requiring some modifications to associated explanatory text.

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Nomenclature

a	= near-Earth object heliocentric orbit semi-major axis, astronomical units
a_A	= maximum heliocentric semi-major axis of a spacecraft Earth departure trajectory with energy $C3_X$, km or astronomical units
a_P	= minimum heliocentric semi-major axis of a spacecraft Earth departure trajectory with energy $C3_X$, km or astronomical units
$C3$	= spacecraft geocentric Earth departure energy (equivalent to v_{HE}^2), km^2/s^2
$C3_X$	= maximum $C3$ launch vehicle capability for a spacecraft of minimum mass (45.2 mT), km^2/s^2
e	= near-Earth object heliocentric orbit eccentricity
e_A	= eccentricity of a spacecraft heliocentric elliptical orbit with apses $r_A \times r_M$
e_P	= eccentricity of a spacecraft heliocentric elliptical orbit with apses $r_M \times r_P$
I_{SP}	= propulsive specific impulse, s
i	= near-Earth object heliocentric orbit inclination on the epoch J2000.0 ecliptic plane, deg
i_X	= spacecraft maximum attainable i after $C3_X$ is depleted by Δv , deg
p	= near-Earth object heliocentric orbit semi-latus rectum, km or astronomical units
r_A	= aphelion distance of a spacecraft Earth departure trajectory with semi-major axis a_A , km or astronomical units
r_{EPO}	= geocentric radius of a circular Earth parking orbit, km
r_M	= spacecraft reference heliocentric distance at Earth departure (1 astronomical unit or 149,597,870.691 km [3])
r_{MIN}	= nominal (best-estimate) near-Earth object minimum geocentric distance during an encounter with Earth, astronomical units
r_P	= perihelion distance of a spacecraft Earth departure trajectory with semi-major axis a_P , km or astronomical units
v_E	= spacecraft heliocentric speed in the ecliptic plane at Earth departure, km/s
v_{EI}	= geocentric spacecraft Earth return trajectory speed at 121.92 km height (approximate entry interface) above a spherical Earth of radius 6378.136 km [3], km/s
v_{HE}	= geocentric spacecraft asymptotic hyperbolic excess speed as Earth's gravitational sphere of influence is departed, km/s
v_M	= heliocentric circular orbit speed at r_M , km/s
v_{MIN}	= near-Earth object geocentric speed at the r_{MIN} encounter epoch, km/s
v_R	= near-Earth object heliocentric radial velocity component at heliocentric distance r_M , km/s
v_T	= near-Earth object heliocentric tangential velocity component at heliocentric distance r_M , km/s
ΔT	= spacecraft round-trip mission duration, days
Δv	= heliocentric velocity difference magnitude between a near-Earth object crossing a circular orbit of radius r_M and motion in the circular orbit at the crossing point, km/s
Δv_A	= near-Earth object-relative spacecraft arrival speed, km/s
Δv_D	= near-Earth object-relative spacecraft departure speed, km/s
Δv_{TNI}	= trans-near-Earth object injection change-in-velocity magnitude required to depart a circular Earth parking orbit of radius r_{EPO} and achieve v_{HE} , km/s
δ	= near-Earth object geocentric true declination, deg
δ_D	= spacecraft Earth departure hyperbolic escape asymptote true declination, deg
δ_R	= spacecraft Earth return hyperbolic approach asymptote true declination, deg

- μ = Sun's reduced mass (132,712,439,940 km³/s² [3])
- μ_e = Earth's reduced mass (398,600.440 km³/s² [3])
- ν = near-Earth object heliocentric true anomaly when heliocentric distance is r_M , deg

I. Introduction

DURING mid-2009, the Review of U.S. Human Space Flight Plans Committee (HSFPC) requested a survey of known asteroids be conducted with the objective of identifying near-Earth objects (NEOs) accessible for anticipated human exploration capabilities beyond low-Earth orbit (LEO). This research into NEO accessibility is associated with the HSFPC's flexible path exploration strategy option [1]. The flexible path avoids transporting humans to any near-term exploration destination deep inside an extraterrestrial gravity well, such as the surfaces of the Moon or Mars. Instead, human exploration destinations beyond LEO are initially limited to lunar orbit, libration points in the Earth/Moon or Sun/Earth systems, NEOs, and eventually Mars orbit. After human transport technology and infrastructure have advanced sufficiently beyond LEO, capabilities to land on destinations such as the Moon and Mars are anticipated. Pending those milestones, NEOs will be the primary extraterrestrial surfaces with which humans will directly interact on the flexible path. Under NASA's Constellation Program, research into the motivation, techniques, and capabilities supporting NEO exploration had been conducted in 2006 [2], but a methodical survey of accessible NEOs was not within that effort's scope.

The HSFPC-motivated survey of known asteroids identifies accessible NEO destinations through a progressive sequence of stages as follows. These stages are further documented in subsequent sections, together with summaries of their results when applied to a June 2009 survey of the small-body database (SBDB) maintained by the Jet Propulsion Laboratory (JPL). Public access to the SBDB and its associated ephemerides is documented by [3] and is facilitated using JPL's HORIZONS online ephemeris system.**

Stage 1 filters the SBDB based on heliocentric semi-major axis a , eccentricity e , and ecliptic inclination i . Accessibility threshold values for these orbit elements are driven by optimistic launch vehicle performance assumptions intended to leave no viable NEO destination excluded. Stage 2 uses JPL-maintained ephemerides and searches the time interval from 2020 through 2050 for sufficiently close and predictable encounters between Earth and each NEO identified as potentially accessible by the Stage 1 SBDB filter. Beyond-LEO human mission duration is assumed to be less than a year, due to foreseeable spaceflight technology and residual crew health risks. Each viable human mission to a NEO destination from 2020 through 2050 will therefore fall in the time frame of the corresponding Earth encounter. Stage 3 assumes unperturbed (conic) heliocentric motion and designs optimized round-trip trajectories from Earth, loitering a minimum of 10 days at a NEO destination. Each mission is conducted in a time frame identified by Stage 2 for a Stage 1 NEO. Accessibility assessments for each NEO mission opportunity are then based on associated trajectory design parameters.

II. Stage 1: Small-Body Database Filter

An initial criterion with which to filter the current SBDB is launch vehicle Earth escape performance. In obtaining this specification, the strategy is to overestimate ultimately achievable Earth-departure propulsive performance such that some exploration destinations accepted by the

** Data available online at <http://ssd.jpl.nasa.gov/?horizons> [retrieved 23 March 2010].

Stage 1 filter as viable will ultimately be found marginally inaccessible by Stage 2 and/or Stage 3. This Stage 1 error condition is preferred to otherwise viable destinations being rejected by overly conservative filtering criteria. The following assumptions are key to launch-vehicle performance estimates.

Assumption A: the mission profile entails a single Ares V launch into a minimal-altitude Earth parking orbit (EPO). Nominal loiter time in this EPO before trans-NEO injection (TNI) and Earth departure stage (EDS) cryogenic propellant depletion is, at most, three orbits.

Assumption B: post-TNI EDS-injected spacecraft (payload) mass is 45,243 kg. This equates to a minimal capability crew exploration vehicle (CEV) with capacity to impart NEO arrival and NEO departure impulses totaling 3.0 km/s, using storable hypergolic propellant with a specific impulse (I_{SP}) of 314 s. The assumed CEV crew module mass is 9506 kg ([4], Table 5-1, p. 228, portable document format (PDF) p. 234), and the CEV wet service module mass is scaled by a factor of 2.62 from its Exploration Systems Architecture Study baseline ([4], Table 5-2, p. 241, PDF p. 247) to a value of 35,737 kg (28,165 kg of which is usable propellant mass), thereby achieving the imposed 3.0 km/s capability.

In the context of permissive filtering criteria based on optimistic propulsive performance, it should be noted the filter is not a substitute for detailed mission analysis applied to a specific NEO destination during a specific time frame. The following disclaimers will apply to destinations deemed accessible by the Stage 1 filtration process.

Disclaimer 1: none of the filter criteria deal with mission duration. In general, shorter transit times between the Earth and a NEO destination will require greater propulsive capability from both the launch vehicle and the spacecraft. Consequently, a viable NEO destination according to the filter may prove to be inaccessible when actual trajectory designs are computed for which the transit times comply with human mission duration limits.

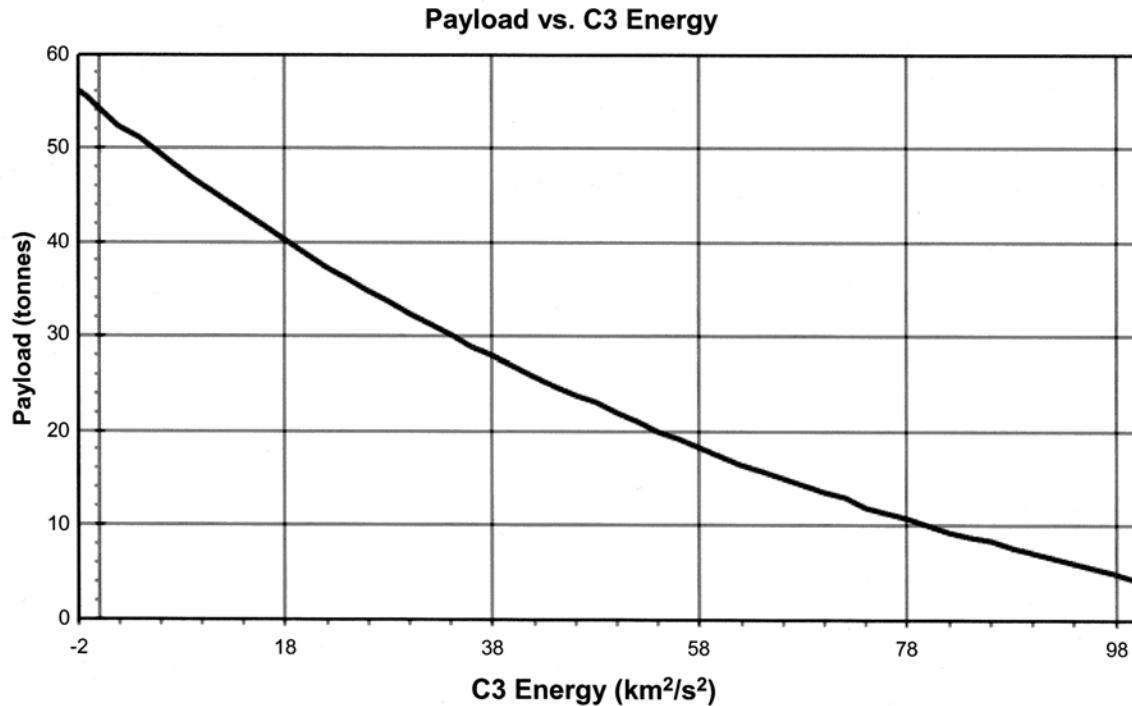
Disclaimer 2: none of the filter criteria deal with launch vehicle performance losses imposed by EPO equatorial inclination requirements. In general, v_{HE} or EDS-injected payload mass will be reduced if EPO equatorial inclination cannot be designed near 28.5° . Although a NEO destination's i may be small, the mission trajectory's $|\delta_D|$ may be large because the NEO can attain large $|\delta|$ near Earth. Furthermore, large $|\delta|$ NEO geometry is likely to arise. As observed in Disclaimer 1, only sufficiently close Earth approaches are compatible with sufficiently short human-mission transits. The lowest possible EPO inclination supporting a coplanar TNI is equivalent to $|\delta_D|$ ([5], Fig. 6.17).

Because Ares V is far from operational, the relationship between the EDS-injected payload mass and $C3$ or v_{HE} is subject to appreciable revision. The Figure 1 plot ([6], p. 26) is used to obtain $C3_X = 11.1 \text{ km}^2/\text{s}^2$ (equivalent to $v_{HE} = 3.33 \text{ km/s}$) for a minimal 45.2 mT payload mass delivered to TNI from EPO equatorial inclinations near 28.5° . In personal communications with Sumrall [6] during mid-2009, Figure 1's pedigree had been verified to be highly optimistic in the context of initial human exploration capability beyond LEO. Contrary to the optimistic shaded disclaimer in Figure 1, Sumrall revealed the associated curve exceeds current Ares V usable payload mass expectations by at least 10%.



Ares V Escape Performance

Extended Shroud



LEO performance for new Constellation point of departure vehicle (51.00.48) is expected to exceed values shown here. Performance analysis will be updated for the 51.00.48 vehicle.

National Aeronautics and Space Administration

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Figure 1: Ares V EDS-injected payload mass versus Earth departure energy ([6], p. 26)

The $C3_X$ capability initially defines an annular region in the ecliptic plane for which the reference heliocentric radius r_M is 1 astronomical unit (AU). Circular orbit speed at r_M is v_M .

$$v_M = \sqrt{\frac{\mu}{r_M}} = 29.784692 \text{ km/s}$$

The annulus inner radius r_P is computed assuming $C3_X$ is applied as a retrograde Earth departure impulse.

$$a_P = \left[\frac{2}{r_M} - \frac{(v_M - \sqrt{C3_X})^2}{\mu} \right]^{-1} = 123,511,664 \text{ km} = 0.825624 \text{ AU}$$

$$r_P = 2a_P - r_M = 97,425,458 \text{ km} = 0.651249 \text{ AU}$$

Similarly, the annulus outer radius r_A is computed assuming $C3_X$ is applied as a posigrade Earth departure impulse.

$$a_A = \left[\frac{2}{r_M} - \frac{(v_M + \sqrt{C3_X})^2}{\mu} \right]^{-1} = 195,867,433 \text{ km} = 1.309293 \text{ AU}$$

$$r_A = 2a_A - r_M = 242,136,996 \text{ km} = 1.618586 \text{ AU}$$

A heliocentric elliptical orbit with apses $r_M \times r_P$ will have eccentricity e_P , and a complementary orbit in the annulus with apses $r_A \times r_M$ will have eccentricity e_A .

$$e_P = \frac{r_M}{a_P} - 1 = 0.211204 \quad e_A = \frac{r_A}{a_A} - 1 = 0.236229$$

Now consider a NEO orbit with cataloged heliocentric semi-major axis a and eccentricity e . Effective Earth/NEO heliocentric velocity difference magnitude Δv is to be computed by assuming a close approach between the two orbits, facilitating sufficiently short human mission transit times. This process begins by determining the NEO orbit's semi-latus rectum.

$$p = a(1 - e^2) \quad (1)$$

The polar equation for conic sections then leads to trigonometric expressions for true anomaly ν when the NEO's heliocentric distance is r_M . For purposes of Δv computation, ν is confined to quadrants 1 and 2.

$$\cos \nu = \frac{\frac{p}{r_M} - 1}{e} \quad (2)$$

$$\sin \nu = \sqrt{1 - \cos^2 \nu} \quad (3)$$

The component of NEO heliocentric radial velocity at heliocentric distance r_M arises from the time derivative of the polar equation for conic sections.

$$v_R = \sqrt{\frac{\mu}{p}} e \sin \nu \quad (4)$$

The component of NEO heliocentric tangential velocity at heliocentric distance r_M arises from the time derivative of the scalar relationship between ν and angular momentum.

$$v_T = \sqrt{\frac{\mu}{p}} (1 + e \cos \nu) \quad (5)$$

Spacecraft heliocentric speed in the ecliptic plane at Earth departure is determined by the foregoing components.

$$v_E = \sqrt{v_R^2 + v_T^2} \quad (6)$$

Assuming Earth's heliocentric orbit is circular with radius r_M , Δv can then be computed.

$$\Delta v = \sqrt{v_R^2 + (v_T - v_M)^2} \quad (7)$$

In cases where $|\cos \nu| > 1$ in Eq. (2), r_M is not intermediate to the NEO orbit's apses. For these instances, e is ignored, Eq. (8) replaces Eq. (6), and Eq. (9) replaces Eq. (7).

$$v_E = \sqrt{\mu \left(\frac{2}{r_M} - \frac{1}{a} \right)} \quad (8)$$

$$\Delta v = |v_E - v_M| \quad (9)$$

The residual $C3_X - \Delta v^2$ approximates surplus launch energy available to attain the NEO orbit plane. Assuming this residual is positive, the maximum attainable heliocentric inclination i_X can be estimated.

$$i_X = \arctan \left(\frac{\sqrt{C3_X - \Delta v^2}}{v_E} \right) \quad (10)$$

With this formulaic background documented, filter processing and logic are summarized using the following procedural steps.

Step 1: specific to a NEO destination candidate being filtered, fetch heliocentric semi-major axis a , eccentricity e , and ecliptic inclination i from JPL's SBDB. Proceed to Step 2.

Step 2: if $a_P < a < a_A$, proceed to Step 3. Otherwise, this NEO is rejected and Step 1 may be performed for another candidate.

Step 3: if $a < r_M$ and $e < e_P$ or if $a \geq r_M$ and $e < e_A$, proceed to Step 4. Otherwise, this NEO is rejected and Step 1 may be performed for another candidate.

Step 4: compute p from Eq. (1) and $\cos \nu$ from Eq. (2). If $|\cos \nu| > 1$, compute Δv from Eqs. (8) and (9). Otherwise, compute Δv with Eqs. (3–7). Proceed to Step 5.

Step 5: if $\Delta v^2 < C3_X$, proceed to Step 6. Otherwise, $i_X \equiv 0$, this NEO is rejected, and Step 1 may be performed for another candidate.

Step 6: compute i_X from Eq. (10). If $i < i_X$, this NEO is accepted as a viable destination. Otherwise, it is rejected. Step 1 may be performed for another candidate.

Table 1 contains numeric filtering examples applied to current NEO element sets obtained from JPL's HORIZONS ephemeris system. Any **red** value is cause for rejection as a viable destination, while a **green** value signifies a passed criterion necessary for acceptance as a viable NEO destination. Thus, 2000 SG₃₄₄ and 1999 AO₁₀ are the only viable destinations in Table 1. Because i_X is a computed filter criterion, Table 1 i_X values have no coloration and are included for comparison with corresponding i values. In **shaded** Table 1 cases, where $i_X = 0$ per filter Step 5, it is then possible to assess i according to filter Step 6 and color its value accordingly. Given that Step 5 has already rejected a NEO with $i_X = 0$, assessing i in such cases is purely for reference purposes.

Table 1: SBDB filtration examples

Filter Quantity	2000 SG ₃₄₄	1999 AO ₁₀	2003 YS ₇₀	(433) Eros	(99942) Apophis	(25143) Itokawa	(4660) Nereus
a (AU)	0.982804	0.910773	1.317601	1.458252	0.922378	1.322775	1.488671
e	0.065447	0.112650	0.252754	0.222907	0.191055	0.279444	0.360147
i (deg)	0.108	2.263	0.403	10.829	3.331	1.728	1.433
Δv (km/s)	1.889514	2.207358	4.196370	4.360665	5.194682	5.604860	6.778057
i_X (deg)	5.310	5.041	0	0	0	0	0

In June 2009, JPL used foregoing computations and logic to filter the current SBDB for viable destinations. Table 2 summarizes the three-dozen NEOs identified by this process in order of decreasing diameter. Estimated NEO diameters appearing in Table 2 and throughout this paper

are based on absolute magnitude and assume a geometric albedo of 0.15. These diameters may therefore be in error by a factor typically ranging from 0.5 to 2. Computation refinements to filter criteria since June 2009, as documented herein, find 1998 HG₄₉ Table 2 values produce $i_X = 4.110^\circ$. Although 1998 HG₄₉ is rejected in accord with filter Step 6, it is retained as a viable human exploration destination throughout this paper because it was reported as such to the HSFPC. Its Stage 3 assessment also serves to illustrate mission design characteristics from targeting a marginally inaccessible NEO with respect to Stage 1 criteria.

Table 2: Accessible NEO destinations in order of decreasing approximate diameter

Designation	a (AU)	e	i (deg)	Approx. Dia. (m)
1996 XB ₂₇	1.188926	0.057895	2.465	150
1998 HG ₄₉	1.201267	0.113052	4.195	143
2001 BB ₁₆	0.854315	0.172498	2.027	104
2003 SM ₈₄	1.125731	0.082259	2.795	99
2000 AE ₂₀₅	1.164083	0.137356	4.46	90
2001 QJ ₁₄₂	1.062293	0.086336	3.106	72
1999 AO ₁₀	0.911559	0.110971	2.622	57
2008 BT ₂	1.173194	0.080773	3.075	47
2008 CX ₁₁₈	1.144725	0.035265	2.42	45
2001 FR ₈₅	0.982699	0.027874	5.244	43
2000 SG ₃₄₄	0.977455	0.066908	0.11	38
2007 TF ₁₅	1.107648	0.041611	4.185	34
1999 CG ₉	1.060676	0.062472	5.158	31
1993 HD	1.126322	0.039145	0.552	30
2005 ER ₉₅	1.223111	0.15909	3.336	30
2006 BZ ₁₄₇	1.023436	0.098617	1.409	29
2006 QQ ₅₆	0.985266	0.045555	2.797	23
2003 YN ₁₀₇	0.989355	0.013997	4.32	19
2006 UB ₁₇	1.140651	0.103764	1.991	19
2007 VU ₆	0.976508	0.090496	1.223	17
1999 VX ₂₅	0.900003	0.139586	1.663	16
2005 LC	1.133458	0.102199	2.8	15
2001 GP ₂	1.037742	0.073962	1.279	14
2005 QP ₈₇	1.232859	0.17534	0.268	10
2008 EA ₉	1.059154	0.079842	0.424	10
2006 JY ₂₆	1.011314	0.083722	1.421	8
2008 HU ₄	1.096781	0.078187	1.322	8
2008 KT	1.015719	0.086706	1.991	8
2009 BD	1.008566	0.039071	0.382	8
1991 VG	1.026915	0.049141	1.446	7
2007 UN ₁₂	1.053823	0.060455	0.235	6
2008 TS ₁₀	1.257401	0.201616	1.459	6
2000 LG ₆	0.917411	0.111081	2.833	5
2008 UA ₂₀₂	1.033057	0.068465	0.264	5
2006 RH ₁₂₀	1.033211	0.024507	0.596	4
2008 JL ₂₄	1.038238	0.10663	0.55	4

III. Stage 2: Destination Near-Earth Object Encounters with Earth

As noted in Section II's SBDB filter Disclaimer 1, otherwise viable NEO destinations may never approach Earth closely enough to permit sufficiently short round-trip mission duration $\Delta T < 365$ days. Section IV documents experience with planning practical round trips to NEOs

appearing in Table 2. This experience indicates the NEO destination must approach Earth within ~ 0.1 AU as a necessary condition leading to sufficiently brief ΔT . Because a NEO's encounter epoch with Earth falls in the time frame of any practical mission, this epoch serves to initiate a more detailed Stage 3 mission design.

Stage 2 performs a JPL HORIZONS search for Earth encounters within ~ 0.1 AU for each Table 2 destination over the time interval from 2020 through 2050. Table 3 summarizes results from these searches, with encounters listed according to decreasing NEO diameter. A subset of Table 2 NEOs has no Earth encounters reportable by HORIZONS. These NEOs are cited in Table 3 with blank cells corresponding to encounter-specific data.

It should be noted that any Table 3 encounter prediction could be affected by unknown systematic biases in the small number ($\ll 150$) of astrometric measurements currently available for any of the referenced NEOs. Prediction uncertainty associated with any NEO destination would be improved by additional astrometric measurements, including data obtained from planetary radar and robotic spacecraft. The fourth column in Table 3 indicates whether or not an encounter search by HORIZONS is aborted before the requested search interval's end on 1 January 2051. An abort is triggered when linearly propagated 3σ uncertainty in NEO position/velocity equates to an encounter epoch uncertainty exceeding ± 10 days. Consequently, a "Yes" in this column indicates reported encounters may be inaccurate (particularly in later years), and other encounters leading to possible mission opportunities from 2020 through 2050 may be missing altogether. A "No" indicates higher confidence in finding and reporting all Earth encounters pertaining to a specific NEO from 2020 through 2050. Even if encounter date uncertainty is less than ± 10 days, position uncertainty may extend over millions of kilometers.

Table 3: Earth encounters with accessible NEO destinations

Encounter #	Designation	Approx. Diameter (m)	Cov. Abort Before 2051	Encounter Date	r_{MIN} (AU)	v_{MIN} (km/s)
1	1996 XB ₂₇	150	No	2027 Jul 29	0.156919	1.696
2	1996 XB ₂₇	150	No	2049 May 19	0.115122	0.852
3	1998 HG ₄₉	143	No	2031 Jul 27	0.163567	1.055
4	2001 BB ₁₆	104	No	2020 Mar 08	0.091314	6.489
5	2001 BB ₁₆	104	No	2035 Jan 06	0.037748	4.860
6	2001 BB ₁₆	104	No	2039 Mar 07	0.041600	4.698
7	2003 SM ₈₄	99	No	2040 Jul 26	0.063785	2.589
8	2003 SM ₈₄	99	No	2046 Jul 20	0.051413	1.503
9	2000 AE ₂₀₅	90	No	2048 Nov 28	0.068063	2.848
10	2001 QJ ₁₄₂	72	Yes	2024 May 09	0.059030	2.239
11	1999 AO ₁₀	57	No	2026 Feb 11	0.026794	2.679
12	1999 AO ₁₀	57	No	2045 Dec 26	0.076668	5.095
13	2008 BT ₂	47	Yes	2022 Mar 16	0.086192	1.547
14	2008 CX ₁₁₈	45	Yes	2024 Jul 18	0.090004	1.301
15	2001 FR ₈₅	43	No	2039 Mar 21	0.045029	3.162
16	2001 FR ₈₅	43	No	2039 Sep 28	0.030896	2.860
17	2001 FR ₈₅	43	No	2040 Mar 28	0.058253	3.179
18	2001 FR ₈₅	43	No	2040 Aug 14	0.096517	3.486
19	2000 SG ₃₄₄	38	Yes	2028 May 07	0.019622	2.034
20	2000 SG ₃₄₄	38	Yes	2029 Feb 16	0.052714	1.471
21	2000 SG ₃₄₄	38	Yes	2029 Jul 28	0.034215	1.189
22	2000 SG ₃₄₄	38	Yes	2029 Nov 21	0.045229	1.253
	2007 TF ₁₅	34	No			
23	1999 CG ₉	31	Yes	2034 Feb 6	0.045397	2.738

Encounter #	Designation	Approx. Diameter (m)	Cov. Abort Before 2051	Encounter Date	r_{MIN} (AU)	v_{MIN} (km/s)
	1993 HD	30	Yes			
24	2005 ER ₉₅	30	Yes	2028 Mar 23	0.033469	2.636
25	2006 BZ ₁₄₇	29	No	2035 Feb 25	0.019218	3.897
26	2006 BZ ₁₄₇	29	No	2036 May 09	0.094208	3.083
27	2006 BZ ₁₄₇	29	No	2037 Aug 06	0.052206	2.041
28	2006 BZ ₁₄₇	29	No	2038 Aug 26	0.098697	6.195
29	2006 QQ ₅₆	23	No	2050 Apr 22	0.047459	1.579
30	2006 QQ ₅₆	23	No	2050 Aug 07	0.033290	1.666
	2003 YN ₁₀₇	19	No			
31	2006 UB ₁₇	19	Yes	2034 Oct 03	0.077556	3.772
32	2007 VU ₆	17	Yes	2034 Oct 06	0.032501	2.324
33	1999 VX ₂₅	16	Yes	2028 Sep 15	0.048372	4.497
34	1999 VX ₂₅	16	Yes	2034 Sep 28	0.026033	2.938
35	2005 LC	15	Yes	2040 May 30	0.030686	2.740
36	2001 GP ₂	14	Yes	2020 Oct 03	0.008029	2.486
37	2001 GP ₂	14	Yes	2048 Apr 19	0.089772	5.176
38	2005 QP ₈₇	10	No	2031 Sep 18	0.032880	3.533
39	2008 EA ₉	10	Yes	2020 Apr 25	0.074595	1.321
40	2008 EA ₉	10	Yes	2033 Nov 15	0.078024	3.695
	2006 JY ₂₆	8	No			
41	2008 HU ₄	8	Yes	2047 Jan 22	0.090688	1.437
	2008 KT	8	No			
42	2009 BD	8	Yes	2034 Mar 27	0.092508	3.703
43	2009 BD	8	Yes	2034 Sep 01	0.093932	1.598
44	1991 VG	7	No	2038 Nov 07	0.073178	3.052
45	1991 VG	7	No	2039 May 29	0.060540	1.483
46	2007 UN ₁₂	6	Yes	2020 Jul 04	0.043224	2.897
47	2007 UN ₁₂	6	Yes	2021 Jan 08	0.095489	2.013
48	2007 UN ₁₂	6	Yes	2049 Apr 30	0.089922	1.770
49	2008 TS ₁₀	6	Yes	2032 Jul 31	0.092398	6.061
50	2000 LG ₆	5	No	2036 Jun 24	0.026258	2.429
51	2008 UA ₂₀₂	5	Yes	2028 May 18	0.088711	4.943
52	2008 UA ₂₀₂	5	Yes	2029 Oct 20	0.013617	2.807
53	2006 RH ₁₂₀	4	Yes	2028 Aug 08	0.028815	0.215
54	2006 RH ₁₂₀	4	Yes	2044 Jun 07	0.064970	1.180
55	2008 JL ₂₄	4	No	2026 Mar 05	0.060990	2.403
56	2008 JL ₂₄	4	No	2026 Jun 21	0.093079	1.991
57	2008 JL ₂₄	4	No	2043 Dec 09	0.018955	3.319
58	2008 JL ₂₄	4	No	2045 May 17	0.016299	3.269

IV. Stage 3: Destination Near-Earth Object Human Mission Trajectory Design

In the context of human NEO exploration, viability of a Table 3 encounter must ultimately be assessed with a trajectory design in the corresponding time frame. Such a design consists of an outbound leg departing Earth and arriving at the NEO destination 10 days or more before the return leg departs the NEO bound for Earth. Heliocentric conic arcs approximate both trajectory legs to sufficient accuracy. Therefore, Earth and NEO heliocentric positions at the termini of each trajectory leg are among the Lambert boundary conditions (LBCs) leading to trajectory solutions supporting mission viability assessment. Heliocentric NEO positions associated with these Lambert solutions are imported from JPL's HORIZONS ephemeris system, while those for

Earth are computed via general perturbations theory [7] as a convenience, minimizing data import labor. Heliocentric Earth position deviations between [3,7] ephemerides are less than 300 km and are of negligible consequence in this context because associated Lambert solutions completely ignore Earth gravity. To ensure reasonably brief transit times for each mission leg compatible with human endurance, LBCs are constrained such that only short way (type I) trajectory solutions spanning less than a 180° heliocentric transfer angle are produced.

Pork-chop charts (PCCs) are the primary aid in selecting optimal departure and arrival dates for outbound and return trajectory legs. A PCC is an array of values, with each element corresponding to a unique Lambert heliocentric trajectory solution. Each column in a PCC array is dedicated to a departure date, and each row is dedicated to an arrival date. On the outbound trajectory leg, PCC arrays composed of v_{HE} , δ_D , or Δv_A values may be relevant. For the return trajectory leg, PCC arrays composed of Δv_D , v_{EI} , or δ_R values may be relevant. Values appearing in a PCC are color-coded to visually aid optimization. When populated by speed values, PCC elements greater than 5 km/s are colored **red**, and those less than 2.5 km/s are colored **green**. When populated by declination values, PCC elements whose magnitudes exceed 57° are colored **red**, and those whose magnitudes are less than 28.5° are colored **green**. Intermediate PCC values are **pink** in color. Optimization criteria are as follows in order of decreasing priority.

Priority 1: minimize Δv_A and Δv_D at the expense of v_{HE} as necessary. Following launch into an EPO of unknown geocentric radius r_{EPO} , three propulsive impulses are assumed for the mission. The TNI impulse Δv_{TNI} occurs in the EPO using relatively efficient cryogenic propellant. If r_{EPO} is known, Δv_{TNI} can be computed from a PCC's v_{HE} value as follows.

$$\Delta v_{TNI} = \sqrt{v_{HE}^2 + \frac{2\mu_E}{r_{EPO}}} - \sqrt{\frac{\mu_E}{r_{EPO}}}$$

The final two impulses occur at NEO arrival and departure (Earth return braking is assumed to be through atmospheric friction) using relatively inefficient but storable hypergolic propellant. Because of this inefficiency, Δv_A and Δv_D pose a greater obstacle to NEO accessibility than does v_{HE} . Effectively zero priority is given to minimizing v_{EI} because it has no propulsive cost. Heat shield thermal loads are relatable to v_{EI} , but Earth atmospheric-entry shielding limits of future spacecraft are currently uncertain. Note the fastest v_{EI} experienced by humans was logged during Apollo 10 at 11.069 km/s ([8], p. 581).

Priority 2: minimize any $|\delta_D| > 28.5^\circ$ to the extent permitted by v_{HE} , Δv_A , and Δv_D . As observed in Section II's SBDB filter Disclaimer 2, a geocentric Earth departure trajectory's asymptotic declination magnitude $|\delta_D|$ sets a lower limit on EPO equatorial inclination. Assuming a Florida launch into a posigrade EPO, $|\delta_D| > 28.5^\circ$ will impose a performance loss in achieving EPO. At $|\delta_D| > 57^\circ$, additional launch performance losses are likely to be imposed by range safety constraints. Any of these losses will reduce the EDS propellant available to perform TNI for a given spacecraft payload mass at a given r_{EPO} . Effectively zero priority is given to minimizing $|\delta_R|$ because it imposes no propulsive cost.

Priority 3: maintain round-trip mission duration ΔT at less than a year. This constraint addresses crew microgravity and radiation exposure concerns, but it may require considerable modification as the means to mitigate these concerns are developed. Although a low priority constraint in this list, sufficiently short ΔT is actually enforced by Stage 1's SBDB filter and by previously noted LBCs confining trajectory solutions to less than a 180° heliocentric transfer

angle. Thus, missions with small v_{HE} , Δv_A , and Δv_D values naturally tend to possess sufficiently short ΔT values.

As an illustration of optimized NEO human mission trajectory designs using data from Section III, consider Table 3's Earth encounter number 11 with 1999 AO₁₀. Figures 2–5 are PCCs presenting v_{HE} , δ_D , Δv_A , and Δv_D values key to trajectory design in the encounter number 11 time frame. Data circumscribed by boxes in these PCCs correspond to optimal departure and arrival dates.

In arriving at optimal dates from the ensuing PCC data, two conflicting trends must be resolved. The primary conflict arises between Δv_A and Δv_D values in Figures 4 and 5, where minimal Δv_D in Figure 5 is obtained for 1999 AO₁₀ departure dates well before Figure 4's minimum Δv_A for 1999 AO₁₀ arrival dates. Fortunately, a reasonable compromise between Δv_A and Δv_D trends can be achieved by selecting 1999 AO₁₀ arrival on 7 January 2026, with departure 10 days later. At the expense of greater mission duration ΔT , further Δv_A reduction could be achieved by selecting an earlier Earth departure date. Unfortunately, launch dates much earlier than 19 September 2025 lead to a second conflicting trend in Figure 3. Shifting the Earth departure date earlier, while maintaining the 1999 AO₁₀ arrival on 7 January 2026 in Figure 3 rapidly increases δ_D , incurring significant launch performance losses and likely range safety constraint violations by late August 2025. Choice of outbound leg departure and arrival dates is fortunately supported by a reasonably small v_{HE} value in Figure 2.

1999 AO10	A	B	C	D	E	F	G	H	I	J	K	L
Arrive Date	7/31/25	8/10/25	8/20/25	8/30/25	9/9/25	9/19/25	9/29/25	10/9/25	10/19/25	10/29/25	11/8/25	
9/19/25	10.868	12.973	16.807	24.824	49.488							
9/29/25	7.620	8.639	10.389	13.511	20.101	40.337						
10/9/25	5.374	5.863	6.710	8.107	10.664	16.076	32.438					
10/19/25	3.789	4.007	4.427	5.097	6.264	8.425	12.840	26.154				
10/29/25	2.690	2.767	2.978	3.320	3.921	4.984	6.814	10.563	21.658			
11/8/25	1.984	1.987	2.097	2.288	2.646	3.263	4.223	5.896	9.189	18.799		
11/18/25	1.613	1.575	1.631	1.751	1.998	2.406	2.995	3.939	5.477	8.450	17.220	
11/28/25	1.496	1.424	1.443	1.520	1.703	1.990	2.384	2.988	3.863	5.275	8.069	
12/8/25	1.522	1.408	1.389	1.430	1.565	1.766	2.038	2.448	2.992	3.788	5.119	
12/18/25	1.606	1.429	1.368	1.373	1.466	1.603	1.788	2.072	2.421	2.902	3.643	
12/28/25	1.713	1.434	1.324	1.295	1.352	1.440	1.561	1.757	1.979	2.275	2.714	
1/7/26	1.863	1.398	1.232	1.173	1.204	1.254	1.328	1.461	1.596	1.773	2.037	
1/17/26	2.260	1.290	1.066	0.994	1.013	1.040	1.081	1.170	1.244	1.343	1.497	
1/27/26	57.640	0.988	0.791	0.757	0.788	0.806	0.826	0.885	0.916	0.962	1.047	
2/6/26	58.843	46.301	0.854	0.651	0.632	0.619	0.611	0.639	0.636	0.644	0.684	
2/16/26	58.696	58.870	26.659	1.851	1.020	0.752	0.622	0.567	0.516	0.490	0.493	
2/26/26	58.433	58.720	58.892	23.470	2.832	1.516	1.058	0.838	0.710	0.643	0.612	
3/8/26	58.052	58.444	58.769	58.845	22.678	3.705	2.025	1.432	1.151	1.008	0.932	
3/18/26	57.550	58.044	58.482	58.781	58.754	22.910	4.483	2.514	1.825	1.510	1.345	
3/28/26	56.921	57.517	58.062	58.488	58.772	58.689	23.986	5.195	2.982	2.215	1.859	
4/7/26	56.162	56.858	57.508	58.048	58.471	58.792	58.616	26.192	5.878	3.416	2.569	

Figure 2: PCC tabulating v_{HE} in km/s (outbound leg, Earth to 1999 AO₁₀)

1999 AO10	A	B	C	D	E	F	G	H	I	J	K	L
Arrive Date	7/31/25	8/10/25	8/20/25	8/30/25	9/9/25	9/19/25	9/29/25	10/9/25	10/19/25	10/29/25	11/8/25	
9/19/25	-12.431	-12.203	-11.817	-11.391	-11.041							
9/29/25	-11.075	-10.952	-10.649	-10.237	-9.800	-9.547						
10/9/25	-7.895	-7.861	-7.672	-7.334	-6.914	-6.690	-6.574					
10/19/25	-2.210	-2.253	-2.229	-2.030	-1.750	-1.787	-1.875	-2.033				
10/29/25	7.019	6.895	6.609	6.514	6.402	5.687	5.005	4.263	3.613			
11/8/25	20.762	20.539	19.592	18.804	17.722	15.613	13.780	11.928	10.298	9.345		
11/18/25	38.095	37.665	35.439	33.255	30.324	26.154	22.777	19.508	16.702	14.875	13.676	
11/28/25	54.706	53.635	49.493	45.379	40.251	34.246	29.619	25.212	21.495	18.973	17.035	
12/8/25	66.503	64.042	57.794	51.992	45.346	38.461	33.284	28.327	24.161	21.272	18.848	
12/18/25	73.094	68.756	60.829	53.999	46.675	39.605	34.361	29.272	24.984	21.989	19.304	
12/28/25	76.358	70.255	61.030	53.509	45.867	38.827	33.700	28.663	24.405	21.461	18.666	
1/7/26	78.154	70.607	59.776	51.452	43.520	36.529	31.603	26.722	22.577	19.803	17.013	
1/17/26	78.148	70.277	56.384	46.895	38.778	31.997	27.489	22.983	19.084	16.658	14.024	
1/27/26	-2.880	64.335	43.388	34.004	27.549	22.165	18.950	15.573	12.295	10.614	8.474	
2/6/26	-15.383	-52.871	-27.744	-11.113	-3.617	-2.256	-1.209	-1.012	-2.714	-2.706	-3.407	
2/16/26	-16.466	-19.489	-75.385	-57.699	-47.673	-42.234	-37.595	-33.047	-33.077	-30.383	-28.074	
2/26/26	-17.314	-19.827	-23.252	-80.766	-65.619	-62.523	-59.512	-56.077	-54.865	-49.481	-44.826	
3/8/26	-18.084	-20.336	-22.704	-26.509	-85.203	-69.399	-65.601	-61.513	-57.536	-50.529	-44.591	
3/18/26	-18.807	-20.864	-22.822	-24.961	-29.031	-89.412	-69.672	-63.942	-58.121	-50.326	-43.532	
3/28/26	-19.491	-21.377	-23.069	-24.649	-26.540	-30.578	-85.401	-68.197	-60.574	-51.959	-44.221	
4/7/26	-20.137	-21.862	-23.338	-24.584	-25.694	-27.056	-30.920	-80.194	-65.833	-55.827	-46.831	

Figure 3: PCC tabulating δ_D in deg (outbound leg, Earth to 1999 AO₁₀)

	A	B	C	D	E	F	G	H	I	J	K	L
1	1999 AO10	Earth Depart Date										
2	Arrive Date	7/31/25	8/10/25	8/20/25	8/30/25	9/9/25	9/19/25	9/29/25	10/9/25	10/19/25	10/29/25	11/8/25
3		20.273	22.827	26.927	35.043	59.549						
4		16.192	17.633	19.662	22.941	29.476	49.390					
5		13.042	13.894	14.988	16.546	19.092	24.258	40.191				
6		10.529	11.038	11.649	12.446	13.600	15.544	19.589	32.310			
7		8.496	8.791	9.129	9.545	10.100	10.946	12.436	15.653	26.076		
8		6.841	6.999	7.176	7.386	7.654	8.044	8.684	9.886	12.614	21.617	
9		5.494	5.564	5.644	5.741	5.866	6.051	6.355	6.902	7.997	10.520	18.826
10		4.401	4.416	4.442	4.481	4.538	4.633	4.800	5.099	5.664	6.779	9.282
11		3.523	3.507	3.509	3.526	3.561	3.626	3.743	3.947	4.308	4.944	6.126
12		2.832	2.804	2.806	2.828	2.868	2.935	3.044	3.217	3.490	3.920	4.615
13		2.317	2.288	2.312	2.357	2.419	2.504	2.620	2.781	3.008	3.325	3.785
14		1.983	1.951	2.017	2.097	2.184	2.285	2.406	2.554	2.743	2.984	3.302
15		1.922	1.794	1.919	2.029	2.130	2.233	2.344	2.470	2.620	2.796	3.014
16		56.161	1.852	2.042	2.145	2.228	2.308	2.392	2.484	2.588	2.706	2.844
17		57.459	45.980	2.685	2.507	2.481	2.495	2.525	2.567	2.620	2.680	2.749
18		57.315	57.468	27.159	3.650	2.998	2.814	2.739	2.707	2.696	2.694	2.699
19		57.206	57.481	57.616	24.097	4.510	3.430	3.084	2.916	2.815	2.740	2.678
20		57.117	57.513	57.798	57.882	23.369	5.233	3.777	3.277	3.015	2.838	2.698
21		57.037	57.556	57.969	58.259	58.265	23.643	5.830	4.037	3.387	3.028	2.778
22		56.956	57.598	58.137	58.566	58.860	58.778	24.790	6.334	4.209	3.411	2.959
23		56.860	57.626	58.293	58.853	59.298	59.598	59.448	27.130	6.779	4.298	3.354

Figure 4: PCC tabulating Δv_A in km/s (outbound leg, Earth to 1999 AO₁₀)

	A	B	C	D	E	F	G	H	I	J	K	L
1	Earth Return Date	1999 AO10 Depart Date										
2		11/28/25	12/8/25	12/18/25	12/28/25	1/7/26	1/17/26	1/27/26	2/6/26	2/16/26	2/26/26	3/8/26
3		31.575										
4		9.908	29.526									
5		5.500	9.016	26.785								
6		3.533	4.808	7.849	23.295							
7		2.366	2.920	3.957	6.458	19.189						
8		1.559	1.805	2.223	3.023	4.962	14.811					
9		0.972	1.077	1.256	1.573	2.185	3.653	11.015				
10		0.592	0.647	0.750	0.928	1.229	1.781	3.051	9.281			
11		0.555	0.615	0.718	0.875	1.109	1.475	2.117	3.577	10.768		
12		0.808	0.865	0.962	1.105	1.308	1.602	2.061	2.872	4.746	14.147	
13		1.142	1.178	1.257	1.377	1.548	1.788	2.139	2.691	3.680	6.018	17.875
14		1.497	1.496	1.543	1.633	1.767	1.956	2.225	2.621	3.249	4.409	7.194
15		1.870	1.810	1.813	1.862	1.954	2.093	2.291	2.575	2.998	3.696	5.016
16		2.285	2.131	2.072	2.073	2.118	2.205	2.340	2.537	2.826	3.279	4.056
17		2.788	2.479	2.332	2.271	2.263	2.298	2.375	2.501	2.692	2.997	3.506
18		3.500	2.894	2.609	2.464	2.394	2.374	2.396	2.462	2.579	2.785	3.143
19		4.798	3.471	2.936	2.670	2.523	2.443	2.411	2.423	2.482	2.620	2.889
20		8.636	4.500	3.388	2.911	2.657	2.508	2.421	2.383	2.395	2.485	2.701
21		48.638	7.391	4.185	3.243	2.815	2.574	2.426	2.341	2.314	2.371	2.558
22		61.227	39.182	6.378	3.832	3.036	2.654	2.432	2.299	2.239	2.274	2.448
23		61.186	60.270	31.151	5.460	3.434	2.770	2.442	2.255	2.165	2.187	2.360

Figure 5: PCC tabulating Δv_D in km/s (return leg, 1999 AO₁₀ to Earth)

To summarize, PCC data in Figures 2–5 facilitate an optimized human-mission trajectory design, with major events listed in Table 4.

Table 4: Major events in an optimized human mission to NEO 1999 AO₁₀

Date	Event
2025 Sep 19	Depart Earth: $v_{HE} = 1.254$ km/s, $\delta_D = +36.529^\circ$
2026 Jan 7	Arrive 1999 AO ₁₀ : $\Delta v_A = 2.285$ km/s
2026 Jan 17	Depart 1999 AO ₁₀ : $\Delta v_D = 1.475$ km/s
2026 Feb 21	Arrive Earth: $v_{EI} = 11.332$ km/s, $\delta_R = -9.570^\circ$, $\Delta T = 155$ days

Outbound and return legs of the optimized 1999 AO₁₀ trajectory are plotted heliocentrically in Figure 6 and geocentrically in Figure 7.

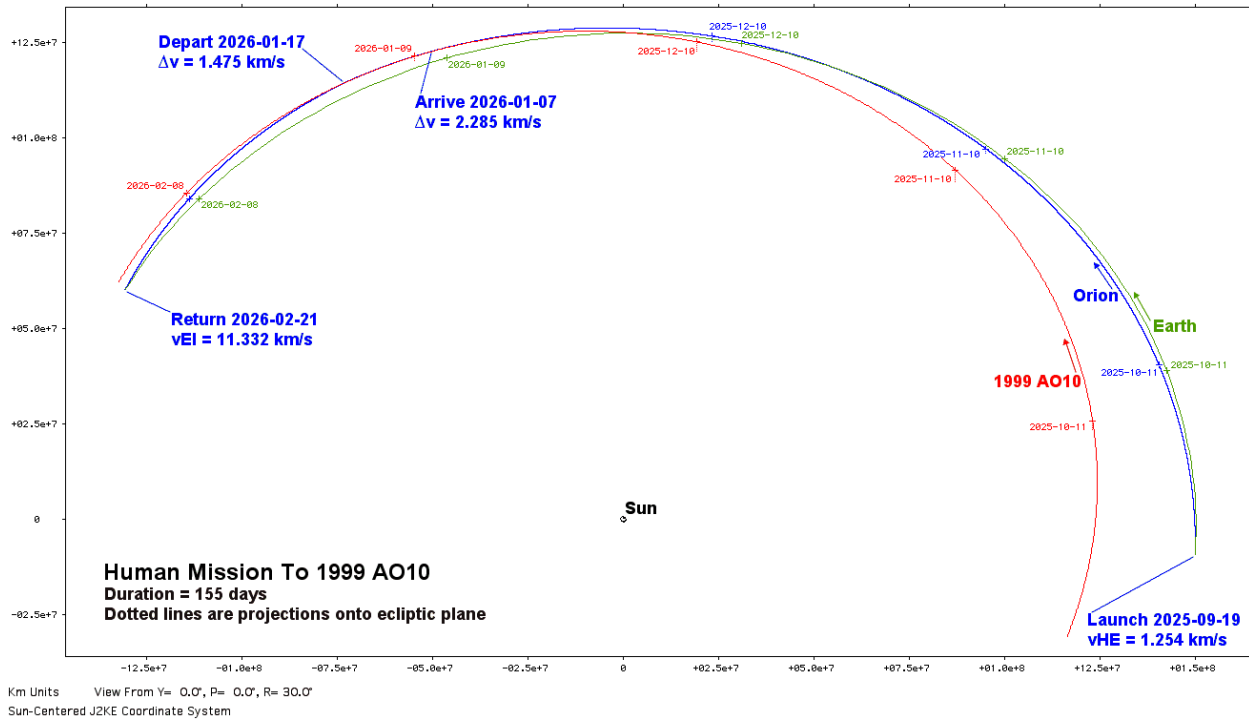


Figure 6: Heliocentric 1999 AO₁₀ Human Mission Trajectory

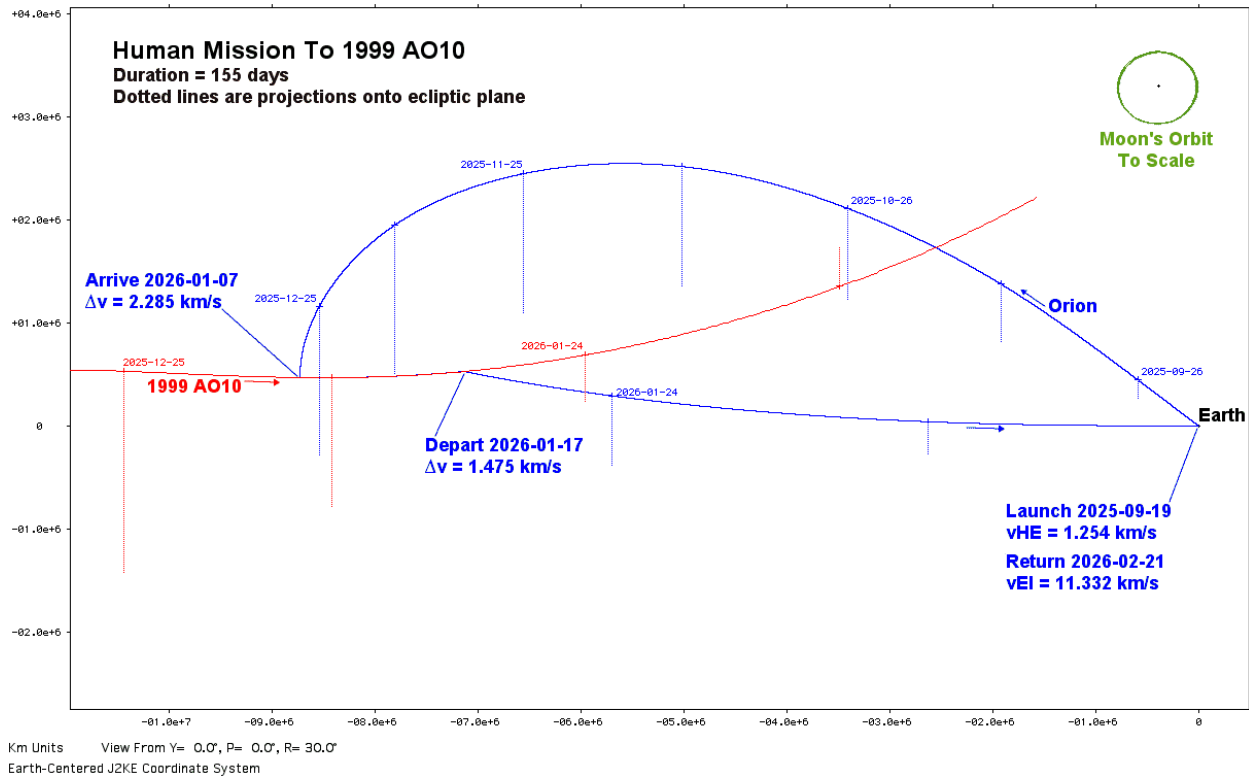


Figure 7: Geocentric 1999 AO₁₀ Human Mission Trajectory

Stage 3 mission assessments akin to the foregoing 1999 AO₁₀ example have been performed for some additional Table 3 Earth encounters with accessible NEO destinations. Results from these trajectory designs are summarized in Table 5.

Table 5: Summary of optimized mission designs associated with some Table 3 encounters

Enc. #	Designation	~Diam. (m)	Launch Date	v_{HE} (km/s)	Δv_A (km/s)	Δv_D (km/s)	v_{EI} (km/s)	ΔT (days)
1	1996 XB ₂₇	150	2027 Jan 31	4.327	3.937	3.514	11.230	260
2	1996 XB ₂₇	150	2049 Jan 01	2.586	3.693	3.331	11.431	290
3	1998 HG ₄₉	143	2031 Apr 21	2.504	3.712	3.200	11.847	240
5	2001 BB ₁₆	104	2034 Nov 30	2.425	1.964	2.871	11.227	240
7	2003 SM ₈₄	99	2040 Feb 20	1.383	2.780	1.051	11.236	210
8	2003 SM ₈₄	99	2046 Mar 22	1.467	2.054	1.378	11.177	180
9	2000 AE ₂₀₅	90	2048 Jun 11	2.868	2.796	2.750	11.262	220
10	2001 QJ ₁₄₂	72	2024 Apr 10	2.115	1.102	2.386	11.352	200
11	1999 AO ₁₀	57	2025 Sep 19	1.254	2.285	1.475	11.332	155
13	2008 BT ₂	47	2021 Dec 12	1.569	2.921	3.104	11.425	270
14	2008 CX ₁₁₈	45	2024 Jan 11	2.164	2.551	2.273	11.162	350
16	2001 FR ₈₅	43	2039 Aug 30	1.642	2.094	0.847	11.513	210
19	2000 SG ₃₄₄	38	2028 Feb 09	0.298	0.754	1.754	11.124	310
23	1999 CG ₉	31	2033 Dec 30	1.867	2.290	2.296	11.355	220
24	2005 ER ₉₅	30	2027 Dec 11	0.749	3.459	2.666	11.107	260
25	2006 BZ ₁₄₇	29	2035 Jan 29	2.553	0.919	1.060	11.572	360
36	2001 GP ₂	14	2019 Dec 09	1.522	2.073	0.170	11.339	304
39	2008 EA ₉	10	2019 Nov 30	2.186	0.979	1.762	11.214	155
47	2007 UN ₁₂	6	2020 Jul 18	2.679	1.109	1.707	11.346	190
53	2006 RH ₁₂₀	4	2028 Mar 31	0.901	2.042	1.606	11.224	130

The sum $\Delta v_A + \Delta v_D$ for each of the 20 Table 5 missions is plotted in Figure 8 against the associated NEO/Earth encounter's r_{MIN} from Table 3. A correlation between these two variables is evident, such that all Figure 8 points fall above the dotted line $\Delta v_A + \Delta v_D \text{ km/s} = 25 r_{MIN} \text{ AU}$. The 25 km/s/AU slope in this relationship is reasonably in accord with constant speed transits covering r_{MIN} in six months. For example, consider $r_{MIN} = 0.04 \text{ AU} = 5,983,915 \text{ km}$. Covering this distance in six months (182 days or 15,724,800 s) requires a constant speed of 0.381 km/s, approximating Δv_A or Δv_D in this simplified model. When doubled to approximate $\Delta v_A + \Delta v_D$ in Figure 8, constant transit speed change at the NEO is 0.762 km/s. Constant transit speed equivalent slope from this example is then $0.762/0.04 = 19.0 \text{ km/s/AU}$. The dotted line passing through Figure 8's origin with 25 km/s/AU slope should therefore pass below all real-world mission design points, excepting those with ΔT near 1 year for which the NEO destinations have nearly zero geocentric relative motion at spacecraft arrival and departure.

With the Stage 1 filter's Assumption B equating to $\Delta v_A + \Delta v_D < 3 \text{ km/s}$, Figure 8's correlation would impose a Stage 2 encounter search constraint of $r_{MIN} < 3/25 = 0.12 \text{ AU}$. This criterion is in close agreement with the encounter search strategy documented in Section III. At a more optimistic capability equivalent to $\Delta v_A + \Delta v_D < 5 \text{ km/s}$, Stage 2 searches constrained to $r_{MIN} < 5/25 = 0.2 \text{ AU}$ would be appropriate. Because Stage 2 encounter searches with $r_{MIN} > 0.1 \text{ AU}$ were only performed for 1996 XB₂₇ and 1998 HG₄₉, the two largest accessible NEOs, other Figure 8 points for missions to smaller destinations undoubtedly exist for $r_{MIN} > 0.1 \text{ AU}$. It remains to be verified where these points fall with respect to the $\Delta v_A + \Delta v_D \text{ km/s} = 25 r_{MIN} \text{ AU}$ line. Finally, note how the lone mission opportunity to marginally inaccessible 1998 HG₄₉ becomes an outlying point in Figure 8. Although this mission's $\Delta v_A + \Delta v_D$ is competitive with those pertaining to the two 1996 XB₂₇ missions, its v_{EI} is more than 0.4 km/s greater than that of either 1996 XB₂₇ mission and is the largest such value in Table 5.

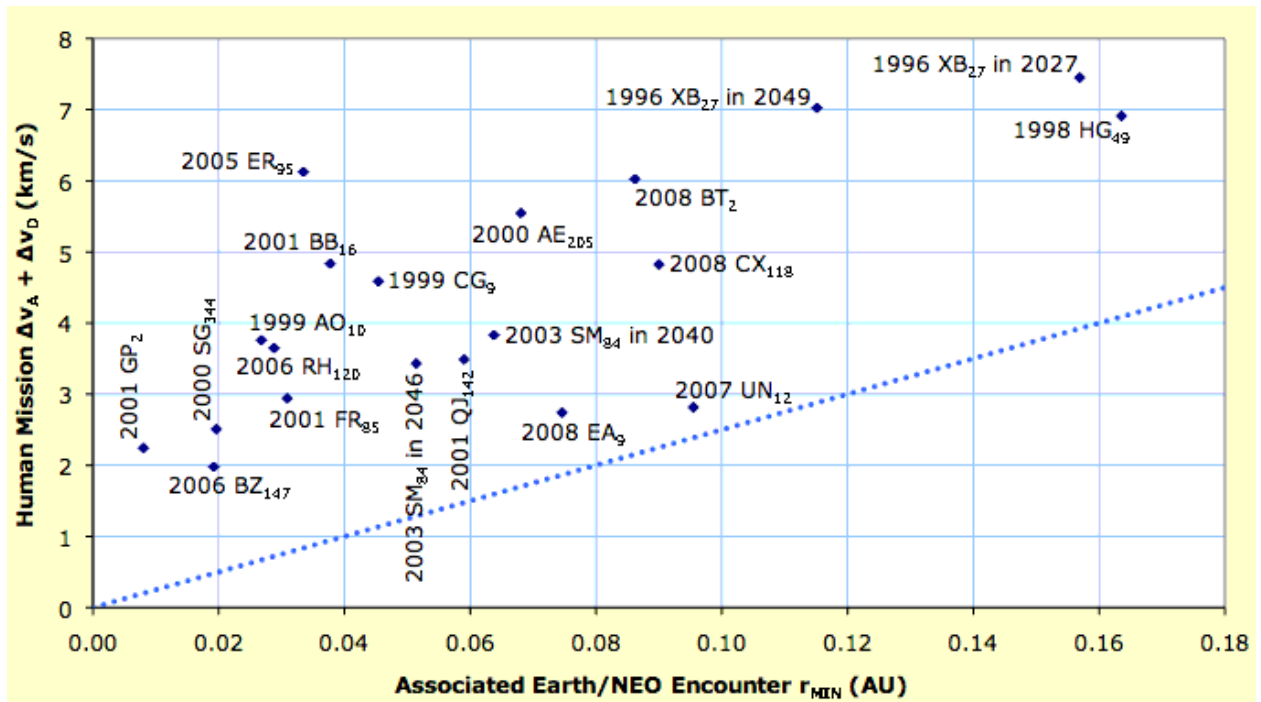


Figure 8: Correlation between $\Delta v_A + \Delta v_D$ and r_{MIN} in Table 5 missions

V. Conclusions

A three-stage survey process to identify and assess human NEO mission prospects has been documented and applied to JPL's current SBDB in the context of anticipated human exploration capabilities beyond LEO. No less than 36 potentially accessible human mission destinations were culled from the SBDB in June 2009. Over the interval from 2020 to 2050, these destinations give rise to at least 58 potential mission opportunities coinciding with NEO encounters closer than 0.1 AU from Earth. Of these opportunities, half a dozen require storable propulsive capability at the NEO destination less than the 3 km/s change-in-velocity assumed as an initial accessibility criterion. If this capability is augmented, viable mission opportunities proliferate dramatically. As the SBDB is populated with an order of magnitude more NEOs in the coming decades, opportunities using any exploration capability appreciably beyond that achieved during the Apollo Program will increase by at least a factor of 10.

To illustrate this population explosion, Stage 1's filter again polled the SBDB in November 2009. From discoveries catalogued in the five months since June 2009, 2009 OS₅ and 2009 RT₁ have joined the 36 initially identified accessible NEOs as potential human exploration destinations.

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