Chairman's Corner

Shirley Brandt Chairman

THE HOUSTON SECTION OF AIAA is categorized by National Headquarters as a large section. This category includes sections which have between 400 and 900 members. Our section is on the high side of this category. However, only about 15% of the membership is active in the local activities. The local section can use the help of all members in whatever amount of time and energy each person is able to devote. Getting involved can be gratifying.

When I was a kid...

movies only cost a dime, but not anymore. Now days you have to take every break you can get...That's why AIAA gives you the opportunity to easily earn coupons worth five dollars off:



Take Five

dues ♦ meeting registration ♦ personal line items ♦ books ♦ TID Services ♦ continuing education

Just sponsor a new member by putting your name in the sponsor block of any AIAA membership application. Then give the application to the person you feel would benefit from membership. For every person you sponsor that becomes a member of AIAA, you receive a \$5 coupon. The more people you sponsor, the more coupons you receive. Maybe you can't go to the movies on them, but you could accumulate enough coupons to get a free membership renewal.

For more information call 202/646-7430.



American Institute of Aeronautics and Astronautics

Although the 1993-1994 AIAA year has only 25% of the year remaining, there is still plenty of time to get involved. Besides the monthly dinner meetings and Lunch & Learn meetings, another Employment Workshop is being organized. In addition, arrangements are in progress for the Annual Technical Symposium to be held in May. All of these programs could use your help. There are many more activities that we could offer with more participation from our membership.

Consider becoming an Active Member of AIAA, and share your ideas and effort for the benefit of the entire membership. As you gain momentum from involvement in the last quarter of the year, maintain this momentum, and stay active during the next administrative year.

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Horizons is the monthly newsletter of the Houston Section of the American Institute of Aeronautics and Astronautics. It is created by members of the Houston Section and reproduced at the Houston offices of Lockheed Engineering and Sciences Company. Please address all correspondence to the Vice-Chairman of Operations, Tek Shrini, U08C, or to the Editor, Lou Livingston, 1911 Pepper Hill, Houston, TX 77058.

Section Elections

Dr. George Nield Chairman-Elect

In accordance with Section Bylaws, a nominating committee has been formed to come up with nominees for next year's officers and council members. Nominating committee members include George Nield, committee chairman, Steve Hawley, André Sylvester, Suzan Voss and Paul Judas. If you would like to nominate someone or be considered for one of the positions yourself, please contact one of the committee members prior to March 15. For the Section to be successful next year, we will need to have good people serving in the leadership positions. To help in understanding the responsibilities associated with each position, excerpts from the Bylaws are reprinted below:

Chairman: The Chairman shall be the Chief Executive Officer of the Section. He shall be a member of the Council and of all committees except the Nominating Committee. The Chairman shall preside at all meetings and functions of the Council and of the Section and represent the Section in dealing with outside agencies, making all appointments except the Nominating Committee and transacting all business of the Section as directed by it or by its Council, and in accordance with these Bylaws.

Chairman-Elect: The Chairman-Elect shall assist the Chairman in performing his duties as requested by the Chairman. He shall attend Executive Council committee meetings to monitor and become familiar with the functions of the Section officers and the Section committees. He shall coordinate with all officers, councillors, and committee chairmen to prepare plans for the orderly transition for his term of office during the following year.

Vice Chairman: The Vice Chairman-Operations and the Vice Chairman-Technical shall be members of the Council and responsible for conducting the detailed planning in their respective areas. [The VC-

Ops oversees the activities of a number of committees, including Programs, Membership, and Publicity. The VC-Technical oversees the technical activities of the Section, including especially the planning for the annual Technical Symposium.]

Secretary: The Secretary shall be a member of the Council and shall maintain minutes of all meetings of the Section and shall be custodian of all its records not specially assigned to others. The Secretary shall conduct the correspondence of the Section and the Council, send out all meetings notices and shall maintain an accurate membership list, with addresses.

Treasurer: The Treasurer shall be a member of the Council, and shall have charge of the funds of the Section, shall make all required financial reports and and such expenditures as may be authorized by the Section or by the Council or by the Bylaws of the Institute.

Council Member: The Council shall consist of not less than four elected Members [we currently have 11, with five positions coming open this year], and the Chairman, Chairman-Elect, Vice Chairman-Operations, Vice Chairman-Technical, Secretary, Treasurer, and the Chairman of the previous year. The Council shall have general supervision of the work of the Section. The elected Council Members shall take office at the beginning of the administrative year [June 1] for terms of two years and shall continue in office until their successors qualify and take office. Council Members shall be limited to two consecutive two-year terms. One council position in alternate years shall be set aside for a member who is under the age of thirty-one at the time of election.

ABSTRACTS FOR PAPERS to be presented at the Houston Section's 19th Annual Technical Symposium are due March 25, 1994. See flyer in this issue for details. Submit abstracts or direct inquiries to Dudley Nelson, LESC/B25, 333-7054.

Committee News

Fluid Dynamics TC

Rakesh Bhargava Chairman, Fluid Dynamics TC

THE FLUID DYNAMICS TC HAS SCHEDULED two interesting seminars for March and April:

- March: "Parallel Processing in Computational Mechanics," by Dr. Rajesh Aggarwal, ATERC, Inc.
- April: "Survey of General Purpose Commercial CFD Programs" by Dr. Christopher J. Matice, Stress Engineering Services, Inc.

Date and location for these seminars will be announced as soon as possible. For further information contact Dr. Rakesh Bhargava at 713/983-0057.

Spirit of Apollo Scholarship Program

Dr. George Nield Chairman-Elect

For several years now, the Houston Section of the AIAA has sponsored the Spirit of Apollo scholarship program that currently provides a \$1,000 scholarship each year. Applicants must have defined a scholastic plan that provides entry into some field of engineering or science pertinent to AIAA technical activities and must meet other specified eligibility requirements.

The scholarship was established in 1988 and is funded from interest on monies the Section maintains in a local savings account.

We initiate the process each year with a mail-out package to college and university financial offices in mid-February. Included in the package is a description of the application process, selection criteria, and application forms. This year's applications must be postmarked by May 2. A scholarship committee,

headed by the Chairman-Elect, is appointed to evaluate the applications and select the recipient for the following school year. Successful applicants are notified in mid-May. The first half of the scholarship amount is mailed to the school's financial office at the start of the fall term, with the second half provided at the start of the spring term.

A copy of this year's application package is included in this issue of Horizons. For more information on the scholarship program, please contact me at 483-1364.

Second Unemployment Workshop Planned

Dr. Zafar Taqvi Coordinator

TENTATIVE PLANS FOR THE SECOND AIAA Unemployment Workshop have been made. The following tentative dates have been reserved at the Gilruth Center:

 Counselor training 	TBD
Registration	March 28
· Session 1	April 4
· Session 2	April 6
 Session 3 	April 11
 Session 4 	April 18
Sessions will run from 5:30	to 8:30 PM.



Attendees at the January dinner meeting hear about the National Aerospace Plane.

Photo by Jim McLane

Been There, Done That ... 25 Years Ago

David S. F. Portree History/Heritage Committee

As spring arrived in Houston, Apollo 9 left Florida for the first orbital test of the Lunar Module (LM) with a Command/Service Module (CSM). The Space News Roundup reported events this way...

Successful Apollo IX Forges Missing Link in All-Up Stack

"Apollo IX was launched into a near circular 102.3 × 103.9 nm orbit following an on-time liftoff at 10 a.m. CST on March 3 from Kennedy Space Center Launch Complex 39A. At three hours after liftoff, Apollo IX crewmen James McDivitt, David Scott, and Russell Schweikart...did a turnaround and docked with the LM nested in its housing atop the S-IVB...The LM extraction went normally, and for the first time the entire Apollo spacecraft was flying in space.

"[On March 7] Spider (LM) spun an invisible web around Gumdrop (CSM)...As Spider closed on Gumdrop...Scott, flying solo in the Command Module, sang out as he spotted the LM emerge into daylight, 'You're the biggest, friendliest, funniest-looking spider I've ever seen!'" (Excerpted, Space News Roundup, March 21, 1969.)

Apollo X Launch Set for May 18

"The Apollo X mission remains...a descent to within 50,000 feet of the moon's surface...a final decision...will be made next week after a review of Apollo IX data." (Excerpted, *Space News Roundup*, March 21, 1969.)

Rock Picking Lunartics

"Practicing with tong and scoop...[Apollo XI Commander Neil Armstrong and LM Pilot Buzz Aldrin] trained last week on the gravel-covered west flank of the Quitman Mountains, Hudspeth Co., Texas.

Through practice, Armstrong found that he could steady himself by leaning on the lunar scoop, important because of the restriction placed on the ability to bend by the bulky suits to be worn during the EVA." (Excerpted, *Space News Roundup*, March 7, 1969.)

LM-2 Drops Simulate Landing Accelerations

"An Apollo lunar module today will make a landing—not on the moon but on a prepared surface in the MSC Vibration and Acoustic Test Facility. The landing is the first in a series of five drop tests from heights ranging from eight to 24 inches on manmade slopes and obstructions to simulate landings on rough moonscapes." (Excerpted, Space News Roundup, March 21, 1969.)

Events

AIAA/SOLE National Symposium

Steve Zobal

The ALAA Houston Section and the Society of LOGISTICS ENGINEERS (SOLE) will jointly sponsor the Sixth Space Logistics Symposium here at JSC, November 7-10, 1994. The Symposium, with the theme "Integrating Space Logistics in the Future-Working Smarter with Fewer Resources," provides an opportunity to focus upon and address relevant space logistics issues and solutions in today's socioeconomic environment. The Call for Papers appeared in the January 1994 issue of Aerospace America. You still have time to submit a paper; the abstract deadline has been moved back to April 15, 1994. And, if you don't want to submit a paper, we can use your support on one of the symposium committees. If you can help, contact Shirley Brandt at 929-7289 or Steve Zobal at 283-1023. #

Apollo Anniversary

Dr. George Nield Chairman-Elect

THE TWENTY-FIFTH ANNIVERSARY OF THE APOLLO XI moon landing is only a few months away. If you have any ideas for activities that you would like to see the AIAA sponsor to commemorate that event, either on our own or in conjunction with other organizations, please contact George Nield at 483-1364.

AIAA Calendar

THE AIAA CALENDAR is intended to encompass all Houston Section events and significant dates. This includes Executive Council meetings, which are open to interested members, and *Horizons* deadlines.

March

21-24 - Monday-Thursday

AlAA/NASA Conference on Intelligent Robots in Field, Factory, Service and Space (CIRFFSS). South Shore Harbour Resort and Conference Center.

Information: Mary Stewart, 483-1724 (fax 483-7580).

24 - Thursday

Monthly Executive Board meeting. 5:15-6:30 PM.

<u> 28 - Monday</u>

Horizons inputs for April due COB.

31 - Thursday

Monthly dinner meeting.

"Design Challenges of Several Unconventional Aircraft," John Roncz, AIAA Distinguished Speaker.

JSC Gilruth Center, 5:30/6:30/7:30.

April

<u> 21 - Thursday</u>

Monthly Executive Board meeting. 5:15-6:30 PM.

25 - Monday

Horizons inputs for May due COB.

28 - Thursday

Monthly dinner meeting.

"Information Superhighway: Southwestern Bell's Role," Wayne Alexander, Regional Vice-President, SW Bell Telephone. JSC Gilruth Center, 5:30/6:30/7:30.

May

19 - Thursday

19th Annual Technical Symposium: "Uniting the World Through Aerospace".
Bayou Bldg., UHCL

Monthly Executive Board meeting. 5:15-6:30 PM.

31 - Tuesday

Horizons inputs for June due COB.

June

23 - Thursday

Monthly Executive Board meeting. 5:15-6:30 PM.

30 - Thursday

Monthly dinner meeting.

Annual Honors & Awards Banquet.

JSC Gilruth Center, 5:30/6:30/7:30.

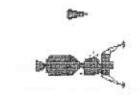
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OUTSTANDING SECTION AWARD



1975-1976 1976-1977 1979-1980 1980-1981 1981-1982 1983-1984 1986-1987







SECTION SPECIAL EVENT AWARD



1971-1972 1972-1973 1979-1980 1981-1982 1983-1984 1985-1986 1988-1989

AIAA Houston Section P.O.Box 57524 Webster, TX 77598



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American Institute of Aeronautics and Astronautics

HOUSTON SECTION P.O. BOX 57524 WEBSTER, TEXAS 77598

AIAA-HOUSTON SECTION

19th ANNUAL TECHNICAL SYMPOSIUM

CO-HOSTED BY

UNIV. OF HOUSTON-CLEAR LAKE, PROFESSIONAL & CONTINUING EDUCATION

THEME: UNITING THE WORLD THROUGH AEROSPACE

MAY19,1994

AT THE

UNIVERSITY OF HOUSTON - CLEAR LAKE

CALL FOR ABSTRACTS

Due: March 25, 1994

GUIDELINES FOR ABSTRACTS AND PRESENTATIONS

- Subject of your choice on aerospace activities. Suggested topics include: Communications Systems, Computer and Software Systems, Energy Systems, Simulation, Materials, Structures, Dynamics, Space Systems, Guidance, Navigation and Control, Life Sciences, Management, International Space Activities, Flight Mechanics, Space History, Human Support, Fluid Dynamics, Earth Observation, On-Orbit Operations, and Thermal Physics
- 2. The abstract should be 250 words or less. (Abstracts must be typed double spaced. Floppy discs are strongly encouraged; see attached example for format.)
- 3. Presentations should be 10 to 15 minutes. VU-graphs or 35 mm slides are preferred.
- 4. Formal publication is not required. However, please have handouts available at your presentation.
- 5. Include with your abstract:
 - Completed NASA Form FF427 or appropriate document availability authorization
 - All information on attached example
- 6. Submit abstracts or inquiries to:

Dudley Nelson, AIAA Vice-Chairman, Technical Lockheed Engineering and Sciences Co. / B25 2400 NASA Rd. 1, Houston, TX 77058 (713) 333 - 7054

EXAMPLE

ARC-JET TESTING TO EVALUATE THE EFFECTS OF CONTINGENCY TRAJECTORIES ON THE ORBITER THERMAL PROTECTION SYSTEM

T. G. Pendergast
I. Norman
D. C. Chao
J. D. Milhoan*
D. M. Curry*

Rockwell International *NASA/Johnson Space Center

A study to extend the orbiter contingency transoceanic abort landing (TAL) ranging capability to avoid a ditch/bailout is in progress. Some contingency entry trajectories that require lower angles of attack will cause high aeroheating rates on the shuttle thermal protection system (TPS).

This presentation will describe the low angle of attack entry trajectories being considered and the major problems incurred on the orbiter TPS. The surface entry environment that results from these trajectories may cause some mass loss of the carbon heat shield. A technical literature survey indicates the mass loss rate and surface recession depend on the surface temperature, pressure, enthalpy, chemical reactivity of the gaseous boundary layer, the flow geometry and the chemical reactivity of the carbon heat shield.

A program at the JSC Arc-Jet facility has been planned to investigate, by testing, carbon mass loss and performance of reinforced carbon-carbon (RCC) using RCC coated (TEOS/TYPE A) and uncoated test specimens. This presentation will discuss the status of testing and test philosophy.

Presenter: T. G. Pendergast Phone Number: 483-XXXX

Mail Code

EXAMPLE



SHIRLEY BRANDT CHAIRMAN 1993-94

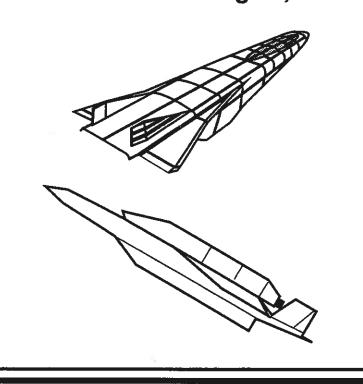
American Institute of Aeronautics and Astronautics

HOUSTON SECTION P.O. BOX 57524 WEBSTER, TEXAS 77598

Thursday, March 31, 1994

DESIGN CHALLENGES OF SEVERAL UNCONVENTIONAL AIRCRAFT

Dr. JOHN RONCZ AIAA Distinguished Speaker CEO/President Gemini Technologies, Inc.



ROBERT R. GILRUTH RECREATION CENTER
JOHNSON SPACE CENTER

PRESENTER / PROGRAM

John Roncz was born and raised in South Bend, Ind. He graduated from the University of Notre Dame in 1971 with an A.B. degree in Arts & Letters. John has always been intrigued by computers and learned to do aerodynamic work through his interest in computers. He began his aeronautical career in association with Burt Rutan by analyzing and designing airfoils for Rutan's Solitaire sailplane. In 1976, John founded Gemini Technologies, Inc. At the present time, Mr. Roncz has designed airfoils for 25 aircraft which have already been flight tested. The first to fly was a canard airfoil for the Long-EZ homebuilt. The latest to fly is Quiver, a very high altitude remotely piloted vehicle with several applications. John has received numerous awards, including the Stanley Dzik memorial trophy for outstanding design contributions from the Experimental Aircraft Association (EAA) and the Professor August Raspet award in 1990 by the EAA. which is its highest honor. His talk will look at some of the designs he has worked on over the years. He will explain the design goals of each plane, why his shapes were better than conventional shapes, and what problems needed to be solved to make it work properly.

EXECUTIVE HOST

Mike Hernandez CEO / President Hernandez Engineering, Inc.

DINNER MEETING

SOCIAL: 5:30 DINNER: 6:30 PROGRAM: 7:30

MENU: SPAGHETTI with MEAT SAUCE

MEMBERS & SPOUSES \$ 7.50
NONMEMBERS \$ 8.00
STUDENTS/YOUNG MEMBERS \$ 5.00
UNEMPLOYED MEMBERS \$ 5.00

FRANKIE HAP 333-6064 LOCKHEED ARDELL BROUSSARD 283-1040 McDONNELL DOUGLAS MARY ANN BIVONA 483-1350 RSOC SARAH LEGGIO 282-3160 ALLIEDSIGNAL

CALL ONE OF THE ABOVE FOR RESERVATIONS.

NOTE: RESERVATION DEADLINE IS MONDAY, MARCH 28, AT 12:00 NOON.

ANY CANCELLATIONS ARE REQUIRED PRIOR TO DEADLINE. NO-SHOWS WILL BE BILLED.

ALL ARE WELCOME

DINNER RESERVATIONS ARE NOT REQUIRED FOR ATTENDING THE PROGRAM ONLY.

CIRFFSS '94

AIAA/NASA Conference on Intelligent Robots In Field, Factory, Service, and Space

MARCH 21-24, 1994

South Shore Harbour Resort and Conference Center League City, Texas

Sponsored by:

The American Institute of Aeronautics & Astronautics & the National Aeronautics and Space Administration, Johnson Space Center, Houston, Texas

In cooperation with the American Association for Artificial Intelligence, IEEE Robotics and Automation Society, National Service Robot Association, Robotic Industries Association, Society of Photo-Optical Instrumentation Engineers, AIAA Space Automation and Robotics Technical Committee, Clear Lake Council of Technical Societies, AIAA Houston Section, ISA Clear Lake Section, and IEEE Galveston Bay Section

MONDAY

MARCH 21, 1994

REGISTRATION WELCOME 7:30 AM

8:30 AM

FIRST PLENARY SESSION

9:00 AM

Sharing Technology in the National Interest Paul J. Weltz, Associate Director, NASA Johnson Space Center

Intelligent Robotics Can Boost America's Economic Growth Jon Erickson, Chief Scientist, Automation and Robotics Division, NASA Johnson Space Center

OPENING KEYNOTE ADDRESS: Technology for America's Economic Growth Includes Intelligent Robotics Hon. Lionel Johns, Associate Director for Technology and Space, Office of Science and Technology Policy, Executive Office of the President of the United States

Intelligent Robotics: The Technical Program Lawrence Seldman, Department Head, MITRE Corporation, Houston

VIDEO TOUR

10:15 AM

NASA Johnson Space Center, Automation & Robotics Program

CONFERENCE LUNCH 12:00 Noon

PARALLEL APPLICATION SESSIONS (4)

1:30 PM

Field Track: Nuclear Industry
Robots Are Coming (Have Come) to

Robots Are Coming (Have Come) to a Nuclear Plant Near You

Teleoperated Systems for Nuclear Reactors Inspection and Maintenance

ARK: Autonomous Mobile Robot in an Industrial Environment

Biologically-Inspired Hexapod Robot

A Vendor's Perspective on the Manufacture, Sale, and Use of Robotics at Nuclear Power Facilities

Odysseus Autonomous Walking Robot: The Leg/Arm Design Factory Track: Agile Manufacturing

A Vision Advisor System for Flexible Manufacturing Application of the Modular Automated Reconfigurable Assembly System Concept to Adaptable Vision Gauging and Parts Feeding

Multiple Disk Load/Unload Sputter System

Agile Manufacturing and the Factory of the Future

Confessions of a Robot Lobotomist

Integration of Vision and Robotic Workcell

Service Track: Security/Building Monitoring

Meeting the Challenges of Installing a Mobile Robotic System Design of an Autonomous Exterior Security Robot Task Automation in a Successful Industrial Telerobot

Controlling Multiple Security Robots in a Warehouse Environment

Space Track: On-Orbit Applications I

Technology Transfer and Evaluation for Space Station Telerobotics

Space Flight Manipulator Technologies and Requirements as Developed for the NASA Flight Telerobotic Servicer

A Space Station Robot Welker and its Shared Control

A Space Station Robot Walker and its Shared Control Software

Technology Devel. for Robotic Surface Inspection in Space A Highly Redundant Robot System for Inspection Free-Floating Dual-Arm Robots for Space Assembly

Space Applications for Advanced Intelligent Telerobots

EMERGING TECHNOLOGIES

5:00 PM

Reception, cheese and wine

TUESDAY

MARCH 22, 1994

PARALLEL TECHNOLOGY SESSIONS (3) 8:00 AM Robotic Sensing, Vision, and Perception Track: Vision & Sensing Technologies for Autonomous Robots

Design and Control of Active Vision Based Mechanisms for Intelligent Robotsn

Vision Based Object Pose Estimation for Mobile Robots

Simulation of an Application of an Old Method Mobile Robot Self Location to a New Sensor Model

Unsupervised Texture Image Segmentation by Improved Neural Network ART2

Microwave Vision for Robots

An Electromagnetic Noncontacting Sensor for Thickness Measurement in a Dispersive Media

Perception System and Functions for Autonomous Navigation in a Natural Environment

Planning, Reasoning, and Control Track: Situated Control and Low-Level Control

Fuzzy Logic Based Robot Controller

Vehicle Following Controller Design for Autonomous Intelligent Vehicles

The Real-World Navigator

A Streamlined Software Environment for Situated Skills

Situational Reaction and Planning

Autonomous Mobile Robot Teams

Systems Technology and Architectures Track: Robotic Systems Architectures

Building Brains for Bodies

Object-Based Task-Level Control: A Hierarchical Control Architecture for Remote Operation of Space Robots

Task-Level Control for Autonomous Robots

A Survey of NASA and Military Standards on Fault Tolerance and Reliability Applied to Robotics

A Performance Analysis Method for Distributed Real-Time Robotic Systems: A Case Study of Remote Teleoperation Predictive Sufficiency and the Use of Stored Internal State Using Generic Tool Kits to Build Intelligent Systems

PARALLEL APPLICATION SESSIONS (4)

1:30 PM

Field Track: Environmental Restoration, Waste Management, and Hazardous Operation

The U.S. DoE Robotics Technology Development Program Chemobyl Sarcophagus Today — A Robotics View from Inside

The New Sarcophagus for Chernobyl
A Reactive System for Off-Road Navigation

The Road Plan Model — Information Model for Planning Road Building Activities

Design Reuse Experience of Space and Hazardous Operations Robots

A Multi-Mode Manipulator Display System for Controlling Remote Robotics Systems

Factory Track: Robotlo Remanufacturing

Programmable Automated Welding System

Robotic NDE Inspection of Advanced Solid Rocket Motor Casings

Automation for Nondestructive Inspection of Aircraft

Graphical Simulation for Aerospace Manufacturing

The Automated Aircraft Rework System (AARS) — A System Integration Approach

Automated Inspection of Turbine Blades

Service Track: Healthcare

TRC Research Products: Components for Service Robots
An Update on 'Lab Rover': A Hospital Material Transporter

A Robot Wheelchair

Dexterity Enhancement in Microsurgery Using Telemicro-Robotics

The Role of Robotics in the ARPA Biomedical Technology Program

An Intelligent Robotic Aid System for Human Services

Space Track: On-Orbit Applications II

An Intelligent Robot for Helping Astronauts

Terrestrial Applications of NASA Space Telerbotics Technologies

On-Orbit Spacecraft Servicing — An Element in the Evolution of Space Robotics Applications

A Modular Artificial Intelligence Inference Engine System (MAIS) for Support of On-Orbit Experiments

Panel Discussion: Future of Robotics in Manned Space

Reception and Banquet with Keynote Address 6:30 PM

"Application Driven Robot Technology" Joseph Engelberger, Transitions Research Corporation, Danbury CT

WEDNESDAY

MARCH 23, 1994

PARALLEL TECHNOLOGY SESSIONS (3)

8:00 AM

Robotic Sensing, Vision, and Perception Track: vision Systems integration and Architecture

Real-Time Correlation-Based Stereo: Algorithm, Implementations and Applications

Research on an Autonomous Vision-Guided Helicopter Real-Time Tracking of Objects for Space Applications Using A Laser Range Scanner

Integration for Navigaton on the UMass Mobile Perception Lab The 4-D Approach to Visual Control of Autonomous Systems Fusion of Sonar and Image Sensory Data for 3-D Modeling of the Free Navigation Space

Planning, Reasoning, and Control Track: Selective Perception and Human Robot interaction

Tele-Assistance for Semi-Autonomous Robots

Mobile Robot Exploration and Navigation of Indoor Spaces Using Sonar and Vision

Mobile Robot Navigation Using Neural Networks and Nonmetrical Environmental Models

The Ground Vehicle Manager's Associate

Deictic Primitives for General Purpose Navigation

A Methodology for the Generation of the 2-D Map from Unknown Navigation Environment by Traveling a Short Distance

Systems Technology and Architectures Track: Robotic Systems Technologies

Simplifying Applications Software for Vision Guided Robot Implementation

An Open Architecture Motion Controller

Telerobotics for Depot Modernization

A Smart Telerobotic System Driven by Monocular Vision GA-Optimization for Rapid Prototype System Demonstration

A Robot Control Formalism Based on an Information Quality Concept

CONFERENCE LUNCH 12:00 Noon

PARALLEL APPLICATION SESSIONS (4) 1:30 PM

Field Track: Military and Other Field Applications

The Network Data Delivery Service: A Real-Time Data Connectivity System

Robotics in a Controlled Environment Agriculture

Robotic Hauling Truck for Surface Mining

A Nonlinear Strategy for Sensor-Based Vehicle Path Control

The Problem With Multiple Robots

Survey Status of Militarty Ground Robotics

Factory Track: Dual-Use Precommercial Robotic Technology

A Generic Telerobotics Architecture for C-5 Industrial Processes

A Practical Method of Reverse Engineering and Automatic Path Programming for Robotic Surface Finishing

Virtual Environments for Telerobotic Shared Control

New Design Ideas for Modular Robots

An Octahedral Hexapod as a New Machine Tool Solution

Designing the Next Generation of Robotics Controllers

Service Track: Building Operations

An End User's Wishlist

The First Commercial Floor Care Company that Ventured into the Production of Robotics

Mobile Robots in the Workplace

Space Track: Planetary Exploration Applications

Non-Geometric Hazard Detection for a Mars Rover CMU Rover

Low Computation Vision-Based Navigation for a Martian Rover

The 'Mity' Micro-Rover: Sensing, Control, and Operation Supervised Space Robots Are Needed in Space Exploration Multitasking Behavioral Control for the Robot All Terrain Lunar Exploration Rover (RATLER)

OPTIONAL SPECIAL EVENTS

TOUR SPACE CENTER HOUSTON RECEPTION/DINNER 4:00 PM 7:00 PM

See next page for details

THURSDAY

MARCH 24, 1994

PARALLEL TECHNOLOGY SESSIONS (3) 8:00 AM Robotic Sensing, Vision, and Perception Track: Vision Systems Integrations and Architecture II

SAVA III: A Testbed for Integration and Control of Visual Processes

An Architecture for Real-Time Vision Processing Motion Estimation of Objects in KC-135 Microgravity Real-Time Tracking of Objects in a KC-135 Microgravity Experiment

Grasping Objects Autonomously in Simulated KC-135 Zero-G

Object Tracking with Stereo Vision

Planning, Reasoning, and Control Track: Planning

A Software Architecture for Hard Real-Time Execution of Automatically Synthesized Plans or Control Laws

Finding All Feasible Plans Using Temporal Reasoning Integrating Deliberative Planning in a Robot Architecture

Real-Time Robot Deliberation by Compilation and Monitoring of Anytime Algorithms

Passive Mapping and Intermittent Exploration for Mobile Robots

Systems Technology and Architectures Track: New Directions in Robotic Systems

Extensibility in Local Sensor-Based Planning for Hyper-Redundant Manipulators (Robot Snakes)

Fault-Tolerant Kinematic Control of Hyper-Redundant Manipulators

Failure Tolerant Operation of Kinematically Redundant Manipulators

UM-PRS: An Implementation of the Procedural Reasoning System for Multirobot Applications Control of Parallel Manipulators Using Force Feedback Robust Inverse Kinematics Using Damped Least Squares with Dynamic Weighting

ControlShell: A Real-Time Software Framework

SECOND PLENARY SESSION

12:30 PM

Commercialization

chaired by Gene Kozmetsky, President of IC2 , University of Texas at Austin, Texas

Lyndon B. Johnson Space Center (JSC) Proposed Dual-Use Technology Investment Program in Intelligent Robotics

Case Study: Concurrent Research and Commercialization of Modular Robots

Part 1 - Research Regulrements

Part 2 — Correlating Modular Designs with Requirements

Part 3 - A Feasible Business Plan

Examples of Robotic Technology Commercialization

Examples of Virtual Reality and Robotics

Panel Discussion and Q&A: How to Use NASA Technology

OPTIONAL SPECIAL EVENTS

SPACE CENTER HOUSTON is the new visitors center at the NASA Johnson Space Center. Designed by Disney Imagineering, this center has an IMAX Theater and hands-on interactive exhibits and displays. It will be the eite of a tour as well as the reception/dinner on Wednesday, March 23. The tour, lasting from 4:00-6:00 PM, will include the Johnson Space Center via tram; the cost is \$10.00. The tour and dinner, lasting from 4:00-8:00 PM, will include a private showing of an IMAX film; the cost is \$25.00. For those who wish to attend only the dinner and IMAX film, the cost is \$15.00.

SPOUSE PROGRAM

A SHOPPING SPREE on Monday, March 21, will depart from the South Shore Harbour Resort and Conference Center at 10:30 AM and will return at 4:00 PM. The cost is \$25.00 per person. The litherary will include the Lone Star Factory Outlet Stores, which include 40 of America's best known manufacturers with Texas-sized savings. In the afternoon, you will travel to Old Seabrook, rich in history from the early 1800s, now a local arts and antiques colony.

VISIT THE MOODY GARDENS Rain Forest in Galveston on Wednesday, March 23. The bus departs at 10:00 AM and returns at 3:00 PM. Cost is \$35,00 per person which includes a gourmet meal and acres of gardens and traits to explore. You will visit the ten-story Rain Forest Pyramid with over 2,000 species of exotic plants, animals, and butterfiles from Asia, Africa, and the Americas.

CONFERENCE LOCATION/TRANSPORTATION

THE SOUTH SHORE HARBOUR Resort and Conference Center is located in the Clear Laked eague City area of Houston. The hotel is 25 minutes southeest of Hobby Airport, 15 minutes from Ellington Field, and an hour from Intercontinental Airport. Call 713/334-1000 for reservations. AIAA conference room rates are \$100 regular (a/d), or \$90 government per diem rate (a/d; ID required). South Shore Hairbour also provides complimentary pick-up and delivery to Hobby Airport and Ellington Field for registered hotel guests. If you require this service, you will need to make reservations at least 48 hours in advance. Call 713/334-1000, ext. 2054, and ask for the bell stand.

800 Elkridge Landing Road Linthicum Heights, Maryland 21090 (301) 621-0390

THE THEME OF CIRFFSS '94 is "Sharing Technology in the National Interest." This responds to President Climons initiatives to take a new direction in building economic strength for America by using closer relationships between government and private industry through partnerships consortia, and collaborations. These relationships will enable us to capitalize on government research and development in commercial enterprises and to create and present jobs. The NASA Johnson Space Center is cosponed to present by forming multiple new relationships. We hope you will come to CIRFFSS '94 to encourage the sharing of the seleption of the precommercial, dual use stage of development by forming multiple new relationships. We hope you will come to CIRFFSS '94 with the idea of forming new partnerships between or among buyers users manufacturers integrations, and technology developers of molitigent robotics. The NASA Johnson Space Center is eager to work with others, patificularly those in industry wenting to use intelligent robotics technology developed for space in commercial applications on seath. REGISTRATION FOR CIRFFSS '94

All participants are urged to use the advance registration from bund in the December 1993 AIAA Bulletin, or the abbreviated form on the reverse of this page. Registrating in advance saves conference attendess \$50. Early Bird registration forms, accompanied by check, money order, or credit card information, must be received by February 21, 1894. Preregistration desk, Late registration will be available at the cusite registration desk. For additional information, please call 202646-7463. Acting Director, NASA Johnson Space Center

Nonmember participants who qualify for AIAA membership and pay the full nonmember fee will receive a one-year membership and Aerospace America each month by completing a membership application form, available from American institute of Aeronautics and Astronautics Department No. 0018

Washington, DC 20073-0018

This offer is valid within six months of conference start date.

BOUND VOLUMES of the CIRFFSS 94 proceedings are complimentary to conference attendees and will be distributed at the conference. Additional copies may be CONFERENCE PROCEEDINGS

ordered by contacting: NASA Center for Aerospace Information

REGISTRATION FEE OPTIONS ARE AS FOLLOWS:

	By 2/21/94	After 2/21/94
Option 1: Full Conference*	-,	CHIEF CE HOA
Member	\$300	\$350
Nonmember	\$420	\$470
Option 2: Full-Time Student*		
Member	\$0	\$0
Nonmenber	\$25	\$25
Option 3: Full-Time Retired**		****
Member	\$0	\$0
Nonmember	\$25	\$25
Option 4: Block***	\$185	N/A
Option 5: Spouse		Laboration of the state of the
Monday Shopping \$25	Wednesda	y Rain Forest \$35
Option 6: Special Event		
Space Center Houston	Tour only	\$10 each
Tour, dinner, and IMAX	film	\$25 each
Dinner and IMAX film or	ıly	\$15 each
Extra Lunch Tickets: \$15 each	ch, Banquet Ti	ckets: \$35 each
 Includes session participation 	lunch on Mond	ay and Wednesday,

Monday evening reception, Tuesday banquet, and one copy of the conference proceedings.
Includes session participation only.
Advance only. 10 or more from the same organization. Includes session participation only.

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City:				
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OPTION:	AMOUNT:	OPTION:	NO.	AMOUNT
Q 1: FULL CONFERENCE	<u> </u>	G 6: SPECIAL EVENT	f <u></u>	
Q 2: FULL-TIME STUDEN	т	TOUR ONLY		
O 3: FULL-TIME RETIRED		TOUR, DINNER,	IMAX	
CI 4: BLOCK (ADVANCE O	ONLY)	DINNER, IMAX O	NLY	
CI 5: SPOUSE SHOPPING		EXT.LUNCH O MON	O WED	
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American Institute of Aeronautics and Astronautic

HOUSTON SECTION P.O. BOX 57524 WEBSTER, TEXAS 77598

Spirit of Apollo Scholarship

AIAA Houston Section Scholarship Program, 1994-95

The Houston Section of the AIAA is pleased to announce the Spirit of Apollo Scholarship for the 1994-95 school year in the amount of \$1000. The first half (\$500) will be available for the Fall Semester. The second half (\$500) will be available for the Spring Semester. Eligibility requirements must be met for both the Fall and Spring semesters.

OBJECTIVE

The objective of the American Institute of Aeronautics and Astronautics (AIAA) is to advance the arts, sciences, and technology of aeronautics and astronautics.

The AIAA encourages original research, furthers dissemination of new knowledge, fosters the professional development of those engaged in scientific and engineering activities, improves public understanding of the profession and its contributions, fosters education in engineering and science, promotes communication among engineers and scientists and with other professional groups, and stimulates outstanding professional accomplishments.

ELIGIBILITY

The following eligibility requirements shall be met by the applicants for the AIAA/Houston Section Scholarship award:

- 1. Applicant must have completed at least one academic year of full-time college work at the time of receiving the scholarship.
- 2. Applicant must have a college grade point average of not less than 3.0 on a 4.0 scale.
- 3. Applicant shall be enrolled in an accredited college or school.
- 4. Applicant's scholastic plan shall be such as to provide entry into some field of engineering or science (i.e., physical science, mathematics, or computer science) which is pertinent to the technical activities of the AIAA.
- 5. Applicant shall not have, or subsequently receive, any other scholarship award which, combined with the AIAA award, would provide a stipend greater than the tuition plus direct educational expenses (such as books, lab fees, etc.) estimated by the educational institution he or she plans to attend.
- 6. Students who receive an award are eligible to reapply in succeeding years. It should be stressed that regardless of GPA, renewal is not automatic. To apply for renewal, and individual must follow the application procedure indicated below.
- 7. Applicants must be either U.S. citizens or permanent residents of the U.S.

SELECTION CRITERIA

The recipients of the scholarship awards will be selected using the following criteria, which are listed in order of importance:

1. Scholarship

This criterion will be evaluated on the basis of the applicant's grade point average or equivalent. A grade point average of not less than 3.0 (B) will be required.

2. Personal Assessment of Career Goals

This criterion will be evaluated through a 500-1000 word typewritten essay. The essay should specify the career objectives of the applicant and should outline the academic program required to achieve those career objectives.

3. Recommendations

Each applicant will be judged on personal and academic merit, based on letters of recommendation.

4. Extra-curricular Activities

Each applicant's high school, college, and community activities, offices, awards, and work experience will receive due consideration.

APPLICATION PROCESS

Each applicant will provide the following information:

- 1. A completed application form.
- 2. A current college transcript.
- 3. Each new applicant must include no more and no less than three typewritten letters of recommendation. Individuals seeking renewal shall supply two and only two letters. Recommendations from relatives will not be accepted. The letters of recommendation may be attached to the application or sent under separate cover at the address indicated below. Recommendations must be post-marked no later than the due date of the application.
- 4. A 500-1000 word typewritten essay as described in selection criteria.

The Applications (including transcripts, essays, etc.) for the next academic year must be post-marked no later than 2 May of the current academic year.

Applications and related materials should be addressed to:

Chairman, Scholarship Program
AIAA-Houston Section
American Institute of Aeronautics and Astronautics
P.O. Box 57524
Webster, TX 77598

ADMINISTRATION OF THE SCHOLARSHIP PROGRAM

The AIAA-Houston section's scholarship committee will be responsible for selecting the recipients of the awards.

SELECTION OF THE SCHOLARSHIP RECIPIENTS

The decisions of the AIAA Scholarship committee are considered to be final and the winner for the next academic year will be advised of the outcome by 13 May of the current academic year.

DISBURSEMENT OF THE SCHOLARSHIP FUNDS

Disbursement of the scholarship awards shall be made in the form of a check in the name of the recipient and sent to the educational institution of the selected candidate. Educational institutions attended by the recipients will be notified of the scholarship awards, so that the institutions can coordinate the financial resources of the recipients.

American Institute of Aeronautics and Astronautics - Houston Section Application for Scholarship 1994-95

[Please print or type. If additional space is necessary, continue on a separate sheet
Personal Information
Name: Soc. Sec. number:
Local Address:no. & street
Telephone: ()
city state zip
Date of Birth: School Telephone: ()
Citizenship: [] U.S. Citizen [] Permanent Resident of the U.S.
Current Class Rank: out of
List your educational experience to date:
Name of High School or College Dates Attended Graduation Date Degree GPA
out of
out of
out of
Indicate the school year for which the scholarship is requested: [] Sophomore [] Junior [] Senior [] Graduate
Degree sought (major):
Activity and Employment Information
List High School, College, and Community activities, including offices held and/or awards:
Organization Offices/Awards Dates of Involvement
List work experience during the last four years:
Type of work Employer/Company Dates of employment
Signature of applicant Date